



PART B — (5 × 16 = 80 marks)

11. (a) (i) What are the typical challenges of programming for embedded systems? (8)
- (ii) What is timing diagram? Give the timing diagram for NOR gate and explain. (8)

Or

- (b) (i) Discuss about the shared data problems and the mechanism to solve the problems in detail. (10)
- (ii) What is an interrupt controller? Design an interrupt controller to connect 16 devices to a microprocessor with 4 interrupt pins. (6)
12. (a) (i) Describe input port expansion using serial peripheral interface with neat diagram. (8)
- (ii) Explain the applications of pulse width modulation outputs in detail. (8)

Or

- (b) (i) Explain output port expansion using serial peripheral interface with schematic diagram. (10)
- (ii) Describe the special features of PIC in detail. (6)
13. (a) (i) An 8-bit microprocessor has a 16-bit address bus. The first 15 lines of the address are used to select a bank of 32 K bytes of memory. The high-order bit of the address is used to select a register which receives the contents of the data bus. Explain how this configuration can be used to extend the memory capacity of the system to 8 banks of 32 K bytes each, for a total of 256 K bytes of memory. (10)
- (ii) With suitable diagram explain the functions of a typical parallel I/O interface. (6)

Or

- (b) (i) Describe the quantitative parameters used to evaluate the performance of an I/O interface. Also explain any two approaches to high speed interfaces. (8)
- (ii) What does meant by addressing mode? Describe the addressing modes of MC 68 H 11. (8)

14. (a) (i) Briefly explain various debugging strategies used in an embedded systems. (8)
- (ii) Describe the scheduling architecture and the algorithms used in embedded software development. (8)

Or

- (b) (i) What is recursion? What is its relevance in embedded systems? (6)
- (ii) Describe the essential features of an IDE for the development of software for embedded systems. (10)
15. (a) (i) What is a task and how is it started, scheduled and deleted? (8)
- (ii) Describe various intertask communication mechanism in real time systems. (8)

Or

- (b) (i) Why it is necessary to return the execution control after executing an ISR to the task that was executed when the ISR was raised? (8)
- (ii) Describe the design issues of an RTOS in detail. (8)