

12. What is locality of reference? Classify the types of locality of references. [K₂]
13. What are the assumptions made for a perfect processor in the hardware speculation? [K₂]
14. What are the advantages of dynamic scheduling? [K₁]
15. Tell the limitations of multiple issue processors? [K₂]
16. What do you mean by multithreading? [K₁]
17. Tell why multiprocessors are often called as message passing multiprocessors? [K₂]
18. When do you say that a program is synchronized? [K₁]
19. Differentiate cache memory from virtual memory [K₂]
20. Define: dirty bit and miss penalty [K₁]

PART C (6 x 5 = 30 Marks)

21. How do you measure the performance of a computer? Discuss about the levels of programs used to evaluate the performance. [K₂]
22. Define Amdahl's law with a formula to calculate the overall speedup. Also mention the factors to measure speedup using Amdahl's law. [K₅]
23. Define pipelining? Create a simple implementation of pipeline processor and explain how it allows every instruction to be executed in 4 clock cycles. [K₆]
24. Define instruction level parallelism. Discuss about the limitations of ILP for related processors? [K₂]
25. What are the ways of measuring the performance of symmetric shared-memory multiprocessor? Explain. [K₂]
26. Explain about Reliability measures and Benchmarks [K₂]

PART D (4 x 10 = 40 Marks)

27. Describe how you overcome data hazards with Dynamic scheduling approach. [K₂]
28. What is multithreading? Discuss about how it uses ILP support to exploit thread level parallelism. [K₆]

29. Demonstrate the working of Directory based cache coherence protocol in detail. [K₃]

30. How do you optimize the performance of Cache memory? Explain. [K₂]
