



**M.E DEGREE EXAMINATIONS: JUNE 2015**

Regulation 2014

Second Semester

**CAD/CAM**

P14CCT201: Mechanical Vibrations

**Time: Three Hours**

**Maximum Marks: 100**

**Answer all the Questions:-**

**PART A (10 x 1 = 10 Marks)**

1. The torsional stiffness of a circular shaft is [K<sub>1</sub>]
  - a) Directly proportional to its length
  - b) Inversely proportional to its length
  - c) Independent of its length
  - d) Sequence of its length
2. In single degree low damped forced vibration the force vector polygon approximates a rectangle under vibration. [K<sub>2</sub>]
  - a) Below resonance conditions
  - b) At resonant conditions
  - c) Above resonance condition
  - d) At zero frequency
3. The spring for vibration isolation in forced system for low damping should be made of [K<sub>1</sub>]
  - a) metal
  - b) Rubber pads
  - c) Air spring
  - d) Neoprene pads
4. Match the following list [K<sub>2</sub>]

List I	List II
P. Continuous relative rotation	1. D' Alembert's principle
Q. Velocity and acceleration	2. Grubler's criterion
R. Dynamic-static analysis	3. Grashoff's law
S. Continuous relative rotation	4. Kennedy's theorem

- a) P-1,Q-2,R-3,S-4
  - b) P-3,Q-4,R-2,S-1
  - c) P-2,Q-3,R-4,S-1
  - d) P-4,Q-2,R-1,S-3
5. Centrifugal pendulum absorber is used to reduce the [K<sub>2</sub>]
    - a) Centrifugal forces in the rotating system
    - b) Torsional vibration of rotating system



18. What do you mean by coordinate coupling? [K<sub>2</sub>]
19. Define Stodola's method. [K<sub>2</sub>]
20. State that Dunkerley's Equation for Shafts [K<sub>2</sub>]

**PART C (6 x 5 = 30 Marks)**

21. Derive the step by step function of Laplace transform [K<sub>2</sub>]
22. Derive the equations of motion of a system using Lagrange's Equation [K<sub>2</sub>]
23. Explain the concept of vibration absorber with neat sketch. Also state the demerit of dynamic Vibration absorber. [K<sub>2</sub>]
24. Illustrate the Dunkerley's equation for natural frequency of a shaft carrying several loads [K<sub>2</sub>]
25. Describe the procedure for Stodola method [K<sub>3</sub>]
26. Derive the frequency equation of longitudinal vibration for free-free beam with zero initial displacement. [K<sub>2</sub>]

**PART D (4 x 10 = 40 Marks)**

27. An electric motor is supported on a spring and a dashpot. The spring has the stiffness 6400N/m and the dashpot offers resistance of 500 N at 4m/sec. The unbalanced mass 0.5 kg rotates at 5 cm radius and total mass of vibratory system is 20kg. The motor runs at 400 rpm. Determine (a) damping factor (b) Amplitude of vibration and phase angle (c) resonance speed and resonance amplitude (d) force exerted by the spring and dashpot on the motor. [K<sub>4</sub>]
28. Determine natural frequency of multi degree of freedom (3 DOF) system using Matrix iteration Method [K<sub>3</sub>]
29. Determine natural frequency of three degree of freedom system using Holzer method. [K<sub>4</sub>]  
(Assume  $m_1=m_2=m_3=1$ ;  $k_1=k_2=k_3=1$ ;) )
30. A shock absorber is to be designed so that its overshoot is 10% of the initial [K<sub>4</sub>]

displacement when released. Determine damping factor. If the damping factor is reduced to one half this value, what will be the overshoot?

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