



M.TECH. DEGREE EXAMINATIONS: JAN 2015

(Regulation 2014)

First Semester

APPAREL TECHNOLOGY

P14FTT101: Automation in Apparel Manufacture

Time: Three Hours

Maximum Marks: 100

Answer all the Questions:-

PART A (10 x 1 = 10 Marks)

1. Important components of pneumatic system are [K₁]
 1. Compressor
 2. Air tank
 3. Prime mover
 4. Fluid conditioner

a) 1 and 2	b) 2, 3, 4
c) 1, 2, 3	d) 1, 2, 3, 4
2. The part of SNLS machine which produces loop from the top thread is [K₂]
 - a) Bobbin Hook
 - b) Needle
 - c) Bobbin
 - d) Looper
3. Match the following [K₂]

(a) Laser cutting	-	(i) ionized gas
(b) Water jet cutting	-	(ii) wear and tear of tool
(c) Plasma cutting	-	(iii) produces sound in cutting
(d) Knife cutting	-	(iv) CO ₂

a) (a)- (i), (b)- (ii), (c)-(iii), (d)-(iv)	b) (a)- (ii), (b)- (i), (c)-(iii), (d)-(iv)
c) (a)- (iv), (b)- (iii), (c)-(i), (d)-(ii)	d) (a)- (iii), (b)- (ii), (c)-(i), (d)-(iv)
4. The edge neatening is done in over lock machine [K₂]

- (a) before stitching
- (b) After stitching
- (c) At the time of stitching
- (d) In the middle of stitching

- a) (a) is correct
- b) (b) is correct
- c) (c) is correct
- d) (d) is correct

5. Match the following [K₂]

- 1. Reinforcement stitch - (a) bar tacking
- 2. Over lock machine - (b) 500 class stitches
- 3. Button holing machine - (c) cradle feed system
- 4. Spreading - (d) 4200 stitches/min

- a) 1-b, 2- d, 3- c, 4-b
- b) 1-a, 2-b, 3- d, 4- c
- c) 1-d, 2- b, 3- a, 4-c
- d) 1-c, 2- a, 3- b, 4-b

6. The number stitches in bar tacking varies between [K₁]

- a) 14-28 stitches
- b) 28-32 stitches
- c) 100-200 stitches
- d) 32-42 stitches

7. The following one is correct flow process route in fusing [K₂]

- 1. loading area → fusing → cooling area → take-off area
- 2. loading area → cooling area → fusing area → take-off area
- 3. loading area → fusing → take off area → cooling area
- 4. cooling area → fusing → loading area → take-off area

- a) 2 is correct
- b) 3 is correct
- c) 1 is correct
- d) 4 is correct

8. An overhead transport system that moves individual units from work station to work station for assembly is known as [K₂]

- a) CTS
- b) UPS
- c) WTS
- d) ORD

9. The part which is used to grasp and hold an object and place it at a desired location in a robot is [K₂]

- a) Gripper
- b) Wrist
- c) Sensor
- d) End effector

10. Robots in apparel industry are used in _____ [K₃]
- a) Marker planning
 - b) Pattern making
 - c) Material handling
 - d) Costing

PART B (10 x 2 = 20 Marks)

- 11. Define servo valves [K₁]
- 12. Demonstrate the advantages of Pneumatic system [K₂]
- 13. Identify the different feed mechanisms in sewing machines [K₁]
- 14. Describe the special features of pocket making machine [K₂]
- 15. Demonstrate the importance of carousel opener in apparel industry [K₃]
- 16. Illustrate the advantages of vacuum ironing table [K₃]
- 17. Name few types of conveyor systems [K₁]
- 18. Illustrate machine vision system [K₃]
- 19. Give examples of role of robots in tufting [K₂]
- 20. Recognize return on investment in automation [K₁]

PART C (6 x 5 = 30 Marks)

- 21. In electrical drives, define group drive, individual drive and multitude drive, list their advantages and disadvantages [K₁]
- 22. Construct two main types of fluid power systems [K₄]
- 23. Appraise on automation and special features of bar tack machine [K₅]
- 24. Analyze the working principle and specifications of laser cutting machine [K₄]
- 25. Demonstrate electronic steam ironing and jacket finisher [K₃]

26. Appraise on automated storage and retrieval systems [K₅]

PART D (4 x 10 = 40 Marks)

27. Compose and explain with necessary sketches the stitch cycle of overlock machine [K₆]

28. Appraise on features and functions of Unit Production System [K₅]

29. Construct in detail the application of robotics in spreading, cutting and sewing [K₆]

30. Asses on robotics for material handling [K₅]
