

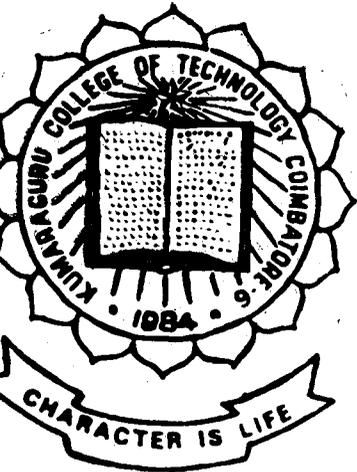
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# MICROCONTROLLER BASED PROGRAMMABLE TIMER

PROJECT WORK

SUBMITTED BY

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UNDER THE GUIDANCE OF  
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IN PARTIAL FULFILMENT OF THE  
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Department of Electrical & Electronics Engineering  
**KUMARAGURU COLLEGE OF TECHNOLOGY**

P207

DEPARTMENT OF ELECTRICAL AND ELECTRONICS ENGINEERING

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## CERTIFICATE

This is to certify that the Project Report entitled

### **MICRO CONTROLLER BASED PROGRAMMABLE TIMER**

has been submitted by

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### **Bachelor of Engineering in Electrical and Electronics Engineering**

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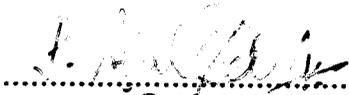
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## SYNOPSIS

A microcontroller based system has many advantages like high speed, reliability, userfriendly, versatility and accuracy. In this system the microcontroller operations are co-ordinated using Realtime clock and external memory. The realtime clock chip provides precise clock pulse which enhances the accuracy.

In this project, an innovative attempt is made to incorporate multiple facilities using microcontroller devices to design a programmable timer. To carry out different operations in the programmable timer, different mode are set in micro controller through software and proper accessing of these modes and other operations are carried over by 4 different keys that are provided externally.

The designed hardware circuit is fabricated and a software in assembler language is developed. In view of the extended facilities provided by the software, the timer is suitable for application in industries where time controlled operations are involved.

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## CHAPTER-I

### INTRODUCTION

Timers are generally of the type (a) Electromechanical (b) Analog (c) Digital in nature. The programmable timer developed by us is digital in nature and is controlled by dedicated micro controller which is having a very high level of reliability and accuracy.

The following facilities are provided through software namely.

1. Time setting mode : This mode is used for setting the real time clock to current time , date, day etc.

2. Alarm setting mode : The alarm setting mode is used for setting the time and duration for which bell has to ring multiple inputs can be given.

3. Alarm deleting mode : This mode is used for deleting the unnecessary alarm setting.

4. Holiday setting mode : This mode is used for turning the alarm off on holidays.

5. Holiday Deleting mode : This mode is used for deleting the unnecessary holiday inputs.

6. Day setting mode : This allows the user to turn the alarm setting on or off for that particular day.

7. Reset mode: This mode is used for resetting the timer to initial position.

8. Display mode : This mode is used for switching from time option to calendar option & vice versa. The external key control is through a set of four (4) keys namely.

1. submenu key : This key is used for setting year, month, hours, say e.t.c to a particular value after a particular mode is selected.



2. increment key : This key is used for incrementing the year, month e.t.c to the required value.

3. Toggle / Accept key : This key used for toggling between time display & calendar display modes. In all other modes it is used as accept key. Thus this key prevents accidental changing of the time.

4. mode changing key : This key is used for changing from one mode to another mode.

## CHAPTER II

### MICRO-CONTROLLER

#### INTRODUCTION :

The 8051 family of products is based on the industry standard for 8-bit high performance micro-controller. The architecture for the family has been optimized for sequential real time control applications. The 8051 family of products are used in a wide range of applications from those that are relatively simple to applications in medical instrumentation and automobile control systems. All of the devices included in the family are available in versions that have either internal ROM, EPROM, or CPU only.

In this project 8031 micro-controller which does not have any internal program memory is used for controlling the programmable timer Fig. 2.1 gives the block diagram of 8031.

## 2.2 HARDWARE DESCRIPTION :

The hardwares used in a micro-controller are

1. 8-bit CPU optimized for control applications.
2. Extensive Boolean processing (Single bit logic) capabilities
3. 32bit-bi-directional and individual addressable i/o lines.
4. 128 bytes of on chip data RAM
5. Two 16 bit Timer / Counters.
6. Full Duplex UART.
7. Source Interrupt structure with two priority levels.
8. On chip clock oscillator.
9. 64 KB programmable memory address space.
10. 64 KB data memory address space
11. 40 pin DIP

The port drives and how they function both as ports as ports and for port 0 and port 2 in bus operation, the timers/counters, the serial interface, the interrupt system and reset are described below.



<u>SYMBOL</u>	<u>POSITION</u>	<u>NAME AND SIGNIFICANCE</u>
CY	PSW.7	Carry flag
AC	PSW.6	auxilliary carry flag (for BCD operations)
FO	PSW.5	flag 0
RS1	PSW.4	register bank select control bits 0 set
RS0	PSW.3	cleared by software to determine working register bank.
OV	PSW.2	overflow flag.
-	PSW.1	user definable flag.
P	PSW.0	parity flag.

#### 2.3.4. STACK POINTER :

The stack pointer register is 8 bits wide. PUSH and CALL (POP) executions can be done.

#### 2.3.5. DATA POINTER :

DPTR consists of a high byte (DPH) and a low byte (DPL). Its intended function is to hold a 16 bit address.

#### 2.3.6. PORTS 0-3 :

PO,P1,P2 and p3 are the SFR latches of port 0,1,2 and 3 respectively.

#### 2.4 PORT STRUCTURES AND OPERATIONS :

All ports in 8051 are bi-directional. Each consists of a latch as an output driver and an input buffer.

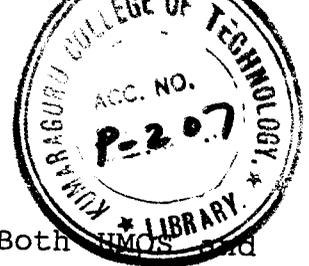
The output drivers of ports 0 and 2 and the input buffer of port 0 are used to access the external memory. In this application port 0 output, the low byte of external memory address, time multiplexed with the byte of external memory address, time multiplexed with the byte being written or read.

All the port 3 pins are multi-functional. They are port pins, but also serve the functions of varied features as listed below.

<u>PORT PIN</u>	<u>ALTERNATE FUNCTION</u>
P3.0	RXD (serial input)
P3.1	TXD (serial output port)
P3.2	INT0 (external interrupt)
P3.3	INT1 (external interrupt)
P3.4	TO (Timer/Counter 0)
P3.5	T1 (Timer/Counter 2)
P3.6	WR (external data memory write strobe)
P3.7	RD (external data memory read strobe)

## 2.5 PORT LOADING AND INTERFACING :

The output buffers of port 1,2 and 3 can each drive 4 LS TTL inputs. These ports on HMOS versions can be driven in



a normal manner by any TTL or NMOS circuit. Both NMOS and CHMOS pins can be driven by open collector and open drain outputs, but 0 to 1 transition will not be fast.

2.6 TIMER/COUNTER :

In the timer functions, the register is incremented in every machine cycle. Thus one can think of it as counting machine cycles. Since a machine cycle consists of 12 oscillator periods, the count rate is 1/12 of the oscillator frequency.

In the counter function a register is incremented in response to a 1 or 0 transition at the corresponding external input pin t0 or t1. The timer 0 and 1 have four operating modes to select.

MSB							LSB
GATE	C/T	M1	MO	GATE	C/T	M1	MO
			TIMER 1				TIMER 0

GATE - Gating control when set. Timer/counter 'x' is enabled only while TNTX pin is high and 'IRX' control pin is set. When cleared Timer is enable whenever 'TRX' control bit is set.

C/T - Timer/Counter selector Clear for timer operation (input from internal system clock). Set for counter operation.

<u>M1</u>	<u>M0</u>	<u>OPERATION MODE</u>
0	0	8048 Timer TLX serves as 5 bit pre-scaler.
0	1	16 - bit timer/Counter. THX and TLX are cascaded. There is no pre-scaler.
1	0	8 bit auto - reload timer/Counter THX holds a value which is to be reloaded into TLX each time it overflows.
1	1	(Timer 0 ) TLO is an 8 bit controlled by standard timer 0 control bits. THO is an 8 bit timer only, controlled by timer 1 control bits.
1	1	(Timer 1) Timer/Counter 1 stopped.

### 2.7.1 MODE 0 :

Putting either timer into mode 0 makes it look like a timer, which is an 8 bit counter with a divide by 32 pre-scaler.

In this mode the timer register is configured as a 32 bit register. As the counter rolls over, from all 1s to all 0s it sets the timer interrupt flag TFI. The counter input is enabled to the timer TR1 = 1 and either GATE = 0 or INT1 = 1. Setting GATE = 1 allows the lower to be controlled by external input INT1 to facilitate pulse width measurements. TRI is a control bit in the special function register TCON GATE in TMOD.

The 13 bit register consists of all 8 bits of TH1 as the lower 5 bits of TL1. The upper 3 bits of TL1 are indeterminate and should be ignored. Setting the run flag TR1 does not clear the register.

Mode 0 operation is the same for timer 0 and timer 1. Substitute TRO, TFO and INTO for the corresponding timer 1 signals in figure. There are two different gate bits, one for timer 1 (TMOD.7) and the other for timer 0 (TMOD.3).

#### 2.7.2. MODE 1 :

Mode 1 is the same as mode 0 except that the timer register is being run with all 16 bits.

#### 2.7.3 MODE 2:

The mode 2 configuration , the timer register is an 8 bit (TL1) with automatic reload.

#### 2.7.4 MODE 3.

Timer 1 in mode 1 simply holds its count. The effect is the same as setting TR1 = 0.

2.8 STANDARD SERIAL INTERFACE :

MSB LSB  
 TF1 TR1 TFO TRO IE1 I11 IE0 IT0

<u>SYMBOL</u>	<u>POSITION</u>	<u>NAME AND SIGNIFICANCE</u>
TF1	TCON.7	Timer 1 overflow flag.
TR1	TCON.6	Timer 1 run control bit set/cleared by software to turn Timer/Counter ON/OFF.
TFO	TCON.5	Timer 0 overflow flag set by hardware on timer/counter overflow.
TRO	TCON.4	Timer 0 run control bit.
IE1	TCON.3	Interrupt 1 edge flag set by hardware when external interrupt edge detected. Cleared when interrupt processed.

<u>SYMBOL</u>	<u>POSITION</u>	<u>NAME AND SIGNIFICANCE</u>
IT1	TCON.2	Interrupt 1 type control bit/cleared by software to specify falling edge/low level triggered external interrupts.
IE0	TCON.1	Interrupt 0 edge flag set by hardware when external interrupt edge detected. Cleared when interrupt Processed.
IT0	TCON.0	Interrupt 0 type control bit set/cleared by software to specify falling edge/low level triggered external interrupts.

## 2.9 SERIAL PORT CONTROL (SCON) REGISTER :

### 2.9.1 INTERRUPTS :

The 8031 provides 5 interrupt sources. The external interrupts INTO and INT1 can each be either level activated or transition activated depending on bits IT0 and IT1 in register TCON. The flags that actually generate these interrupt bits are bit IE0 and IE1 in TCON. When the external interrupt is generated the flag that is generated is cleared by the hardware. The service routine is vectored to only if the interrupt is transition activated.

### 2.9.2 PRIORITY OF INTERRUPT :

<u>SOURCE</u>	<u>PRIORITY LEVEL</u>	<u>VECTOR ADDRESS</u>
IE0	highest	0003H
TE0		000BH
IE1		0013H
TF1		001BH
R1+T1	lowest	0023H

### 2.9.3. RESET

The reset input is the RST pin, which is the input to a Schmitt trigger. A reset is accomplished by holding the RST pin high for at least two machine cycles, while the oscillator is running. The CPU responds by generating an external reset.



## CHAPTER III

### SYSTEM DESCRIPTION

#### DIRECT BUS CONNECTED CMOS REAL TIME CLOCK / CALENDAR

##### 3.1.1. GENERAL DESCRIPTION

The MSM6242B is a silicon gate CMOS Real time clock / Calendar for use in direct bus connection Microprocessor/Microcomputer applications. An on-chip 32.768 KHZ crystal oscillator time base is divided to provide addressable 4-bit I/O data for SECONDS, MINUTES, HOURS, DAY OF WEEK, DATE MONTH, and YEAR. Data access is controlled by 4-bit address, chip selects (CS0, CSI) WRITE, READ, and ALE control registers D, E, and F provided for 30 SECOND error adjustment, INTERRUPT REQUEST (IRQ FLAG) and Busy status bits, clock STOP, HOLD, and RESET FLAG bits, 4 selectable INTERRUPTS rates are available at the STD. P (STANDARD PULSE) output utilizing control Register inputs T0, T1 and the ITRPT/STND (INTERRUPT/STANDARD). Masking of the interrupt output (STD.P) can be accomplished via the MASK bit. The MSM6242 B can operate in a 12/24 hour format and leap year timing is automatic.

The MSM 6242B normally operates from a 5v + or - 10% supply at - 30 to 85'c Battery backup operation down to 2.0v allows continuation of time keeping when main power is off. The MSM 6242B is offered in a 18-pin plastic DIP a 24 pin FLAT package, and a 18-pin PLCC package.

### 3.1.2. FEATURES

#### DIRECT MICROPROCESSOR / MICROCONTROLLER BUS CONNECTION

The main features can be listed below as

- \* 4 bit data bus
- \* 4 bit address bus
- \* READ, WRITE, ALE and CHIP SELECT INPUTS
- \* Status registers - IRQ and BUSY
- \* Selectable interrupt outputs - 1/64 second, 1 second  
1 minute, 1 hour
- \* Interrupt masking
- \* 32.768 KHZ crystal controlled operation
- \* 12/24 hour format
- \* Auto leap year
- \* + or - 30 second error correction

- \* Single 5 v supply
- \* Battery backup down to  $V_{DD} = 2.0$  v
- \* Low power dissipation :
  - 20 microwatt max at  $V_{DD} = 2V$
  - 150 microwatt max at  $V_{DD} = 5$
- \* 18 pin plastic DIP, 24-pin FLAT and 18-pin PLCC package.

### 3.1.3 PIN DESCRIPTION

#### DATA BUS ( $D_0 - D_3$ )

Data input / output pins to be directly connected to a microcontroller bus for reading and writing of the clock/calendar's registers.  $D_0$ =LSB and  $D_3$  = MSB.

### ADDRESS BUS (A<sub>0</sub> - A<sub>3</sub>)

Address input pin for use by a microcomputer to select internal clock/calendar's registers and control registers for read/write operations. Address input pin A<sub>0</sub> -A<sub>3</sub> are used in combination with ALE for addressing registers.

### ALE (ADDRESS LATCH ENABLE)

This pin enables writing of address data when ALE = 1 and CS<sub>0</sub> = 0 ; address data is latched when ALE = 0 Microcontroller / Microprocessors having an ALE output should connect to this pin ; other it should be connected at V<sub>DD</sub>.

### $\overline{\text{WR}}$ (WRITE)

Writing of data is performed by this pin.

When CS<sub>1</sub> =1 and CS<sub>0</sub> = 0 D<sub>0</sub> D<sub>3</sub>  
data is written into the register at the lowering edge of WR.

## $\overline{\text{RD}}$ (READ)

Reading of register data is accomplished using this pin. When  $\text{CS}_1=1$ ,  $\text{CS}_0=0$  and  $\text{RD}=0$ , the data of the register is output to  $\text{D}_0$   $\text{D}_3$ . If both  $\text{RD}$  and  $\text{WR}$  are set at 0 simultaneously,  $\text{RD}$  is to be inhibited.

## CHIP SELECT ( $\text{CS}_0$ , $\text{CS}_1$ )

These pins enable/disable ALE,  $\text{RD}$ , and  $\text{WR}$  operation.  $\text{CS}_0$  and ALE work in combination with one another, while  $\text{CS}_1$  work independent of ALE.  $\text{CS}_1$  must be connected to power failure detection.

## STD.P

Output pin of N - CH OPEN DRAIN type. The output data is controlled by the  $\text{D}_1$  data content of E register. This pin has a priority to  $\text{CS}_0$  and  $\text{CS}_1$ .

### XT, $\overline{XT}$

32.768 KHZ crystal is to be connected to these pins. When an external clock of 32.768 KHZ is to be used for MSM 6242's oscillation source, either CMOS output or pull-up TTL output is to be input from XT, while ST should be left open.

### POWER SUPPLY ( $V_{DD}$ )

+2 to +6v power is to be applied to this pin.

### GROUND (GND)

This is used for grounding the ckt

## 3.2 MEMORY

### 3.2.1 EPROM 27256

This is an erasable programmable read only memory, which can be only read but not written into. It is of nonvolatile type.

This EPROM is used to store valuable data and monitor programs which should not be lost during power failures and ON/OFF of the system.

### 3.2.2 RAM 6264

6264 is a static random access memory with a standard 28 pin package configuration . It has 12 address lines, 8 input/output lines. 2 chip select lines of which CS1 is active low while CS2 is active high. No clock or timing strobe is required with the access time equal to the cycle time. The pin requires a single +5v supply and is directly TTL compatible.

### 3.3 74LS145

#### FEATURES

- \* 80 MA output drive capability
- \* 15V output breakdown voltage

## DESCRIPTION

The 145 is a 1-of-10 decoder with open collector outputs. This decoder accepts BCD inputs on the  $A_0$  to  $A_3$  address lines and generates 10 mutually exclusive active LOW outputs. When an input code greater than "9" is applied, all outputs are HIGH. This device can therefore be used as a 1-of-8 decoder with  $A_3$  used as an active low enable.

The 145 features an output breakdown voltage of 15v. This device is ideal as a lamp or solenoid driver. Refer Appendix for pin diagram.

### 3.4 74L245

#### FEATURES

- \* Octal bidirectional bus interface
- \* 3 - state buffer outputs
- \* PNP inputs for reduced loading
- \* Hysteresis on all data inputs.

## DESCRIPTION

The LS 245 is an octal transceiver featuring non-inverting 3-state bus compatible outputs in both send and receive directions. The outputs are all capable of sinking 24mA and sourcing up to 15mA, producing very good capacitive drive characteristics. The device features a chip enable (CE) input for easy cascading and a send/Receive (S/R) input for direction control. All data inputs have hysteresis built into minimize AC noise effects. Refer Appendix for pin diagram.

### 3.5 74LS138

#### FEATURES

- \* Demultiplexing capability
- \* Multiple input enable for easy expansion
- \* Ideal for memory chip select decoding
- \* Direct replacement for Intel 3205

## DESCRIPTION

The 138 decoder accepts three binary weighted inputs ( $A_0, A_1, A_2$ ) and when enabled, provides eight mutually exclusive, active LOW outputs (0 - 7). The device features three enable inputs ; two active LOW ( $EP_1, E_2$ ) and one active HIGH ( $E_3$ ). Every output will be HIGH unless  $E_1$  and  $E_2$  are LOW and  $E_3$  is HIGH. This multiple enable function allows easy parallel expansion of the device to a 1-of-32 (5 lines to 32 lines) decoder with just four 138S and one inverter.

The device can be used as an eight O/P demultiplexer by using one of the active LOW Enable inputs as the Data input and remaining Enable inputs as strobes. Enable inputs not used must be permanently tied to their appropriate active HIGH or active LOW state.

### 3.5 74LS373

#### FEATURES

- \* 8 bit transparent latch - 373
- \* 8 bit positive edge triggered register - 374
- \* 3 state output buffers
- \* common 3 state output Enable
- \* Independent register and 3 state buffer operation.

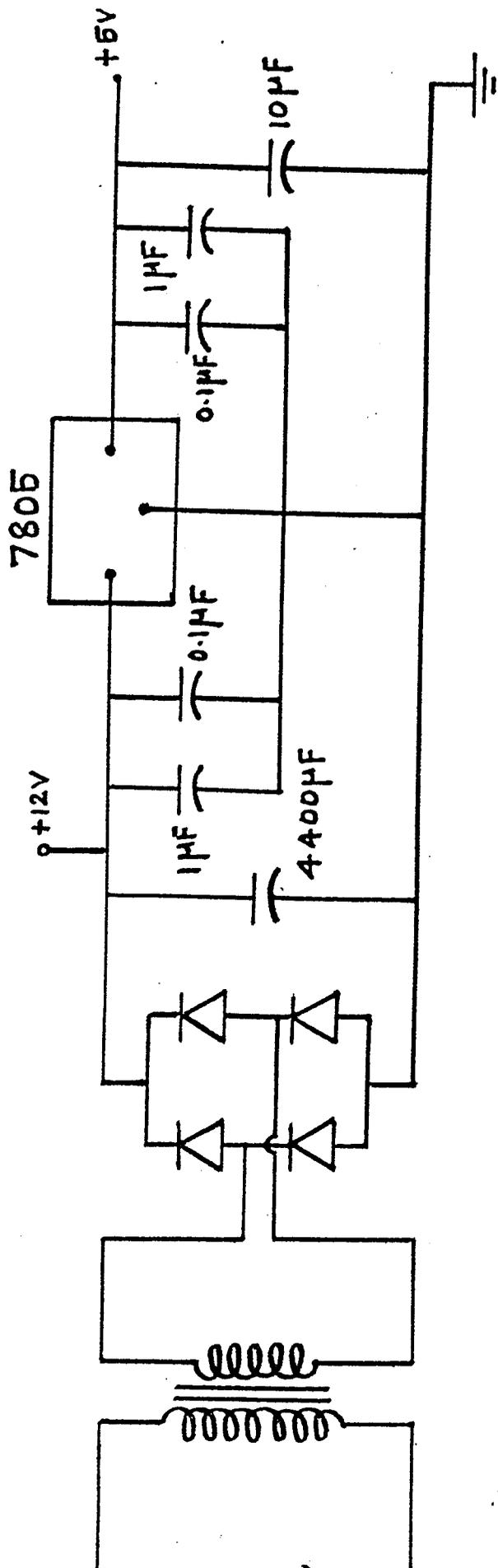
#### DESCRIPTION

The 373 is an octal transparent latch coupled to eight 3 state output buffers. The two sections of the device are controlled independently by Latch Enable (LE) and output Enable (OE) control gates.

### 3.7 Block Diagram of the Power Supply

The power supply to the microcontroller system for programmable timer is as shown in Fig 3.1. The AC current in the mains is 230v/5A. This is then converted to 12v using a

fullwave bridge rectifier. This is then passed through capacitors to cut down the ripples. The voltage with very less ripple factor is then passed through a voltage regulator IC7805 to reduce the O/P to regulated value of 5v which is given as Vcc to all the components.



3.7 BLOCK DIAGRAM OF THE POWER SUPPLY

## CHAPTER IV

### BLOCK DIAGRAM AND OPERATION OF THE PROGRAMMABLE TIMER

#### 4.1 Block Diagram

The block diagram of the timer is as shown in fig 4.1

The block diagram of the timer can be mainly divided into two section namely.

1. RAM, EPROM, RTC interconnected by address, data and control bus.

2. Display section consisting of decoder, keyboard and seven segment LED display unit.

#### 4.2 RTC & MEMORY UNIT

The RAM, EPROM, RTC are interconnected by address, data, control bus. The functions of these are as follows.

i. Address bus : it is a unidirectional bus consisting of sixteen lines namely  $A_0$  to  $A_{15}$ . The microcontroller uses the address bus to identify a peripheral or a memory location

ii. Data bus : it is a bidirectional bus. Microcontroller uses the data bus to transfer data.

iii. Control bus : The control bus is comprised of various single lines that carry synchronization signals. The microcontroller uses such lines to provide timing signals.

#### 4.3 KEYBOARD AND DISPLAY UNIT

From the port of 8031, 3 lines are connected to the 3 x 8 decoder the o/p of which is connected to the keyboard and display unit. A retrace line is taken from the keyboard and connected back to port of 8031 as input line.

The scan code generated by microcontroller keeps changing for every millisecond and if a particular key is pressed it is sensed through the retrace line and the particular scancode generated at the time is the valid one. Now display data is changed accordingly and this is displayed in the display unit for (eg) if increment key is pressed then the display value is incremented and this value is displayed on the display unit.

#### 4.4 Operation

The operation of the programmable timer is mainly controlled through four keys namely.

1. Sub menu key
2. increment key
3. Toggle/ Accept key
4. Mode changing key

The various modes provided through the software is as follows

1. Time setting mode
2. Alarm setting mode
3. Alarm deleting mode
4. Holiday setting mode
5. Holiday deleting mode
6. Reset mode
7. Day setting mode
8. Display mode

The functions of the keys are as follows.

#### 4.5 Submenu key :

This is used for setting particular year, month, date, hours, minutes, day, etc., to a particular value after a particular mode is selected.

#### 4.6 Increment key :

This key is used for incrementing the year, month, date, to the required value. For example if we want to set

the date to 15th, we must press the increment key 15 times so that it changes from 00 to 15 in steps of one. i.e increment key increments the value of contents in steps of one.

#### 4.7 Toggle / Accept key :

In the normal display mode, the calendar is displayed in the seven segment display. This key is used for toggling between the time & calendar display mode. Thus if the display is in calendar mode if we use press the toggle key the mode changed time display mode of vice versa. In all other modes it is used as accept key. The function of key is that, if we want to set the different values of alarm time, the micro controller will accept the data, only when the accept key is pressed. Otherwise the value is not accepted. Thus this prevents from accidental changing of the time.

#### 4.8 Mode changing key :

This key is used for changing the mode from one to another. The function of different modes being as follows.

#### 4.8.1 Time Setting Mode :

In this mode the display of the seven 7-segment LED's is as shown in fig 4.2 A.

In this mode, first in the display 'year' appears in the 3 seven segment LED and 'TS' in the next 7 segment LED's. We have to set the year to say '95' by incrementing the increment key '95' from 00 to 95.

After the submenu key pressed to next value. i.e month i.e./ it display 'mon' in the first 3 seven segment LED display then it is set to the desired value using increment and finally the accept key is pressed to accept the full cycle is obtained the data as shown in Fig 4.2 B when we press the submenu key. Thus these values are set using the increment & accept key.

#### 4.8.2 Alarm setting mode :

The alarm setting mode is used to set the time and duration for which the bell has to ring. In this mode the display of the seven - seven segment LED's is as shown in Fig 4.3 A first the hour is displayed. The no of setting is indicated as '00' at starting . Since we haven't input any time & duration before. Initially the data is at 0'. Now we set the pressing the increment key.

Next Month & duration is set in the similar way. Thus following cycle is followed as shown in Fig.4.3 B Now the no. of setting indicate the value of '01'. Thus this procedure is followed for all the time input & the time setting values indicates the value of no. of inputs given. Thus in this mode, time at which the bell should ring & duration is belling is given.

#### 4.8.3 Alarm deleting mode :

This mode is used for deleting an alarm set value if we don't need that particular value. The display is as shown in Fig.4.4 In the first seven - segment (LED), the letter 'D' appears to indicate it as delete mode here each time & duration can be seen by the incrementing key the increment key & we can delete the unwanted value by pressing the delete key (accept key).

#### 4.8.4 Holiday Setting Mode :

This mode is used for turning the Alarm off on the holidays. Thus the holiday date & month is given i/p & the microcontroller turns off alarm for these days. The first three display the 'mon' for month & no of setting is zero & we have to indicate the month, say march by 03 in the data incrementing the increment. Then submenu key is pressed to follow the cycle as shown in Fig.4.5.

#### 4.8.5 Hoilday Deleting Mode

This mode is used for deleting the holiday i/p given. This mode is useful since the date on which holiday occurs changes for each year. The display will be as shown in Fig4.6.

#### 4.8.6 Reset Mode :

This mode is used for deleting all the setting given including time setting, alarm setting & holiday setting and bringing it to the original condition.

This display in this mode will be as shown in the Fig.4.7 A

In this mode , the word 'PASS' appears on the display to indicate that pass word is needed resetting the timer. If we press the accept key, when the data is '99' then the timer is reset. The Display will be now as shown in the Fig.4.7B

#### 4.8.7 DAY SETTING MODE

This mode allows the user have to turn the alarm setting ON or OFF for that particular day. For (eg) if we want to turn the alarm 'off' on the Sunday or leave days, this mode comes in handy. The display will be as shown in the Fig.4.8A

The first three seven segment LED's indicate the day. The last two seven segment LED's indicate whether the alarm setting is ON or OFF. The increment key is used for toggling between ON or OFF. The following cycle followed as shown in Fig4.8B is followed when we press the submenu key. Finally to accept the setting we press the accept key.

#### 4.8.8 DISPLAY MODE

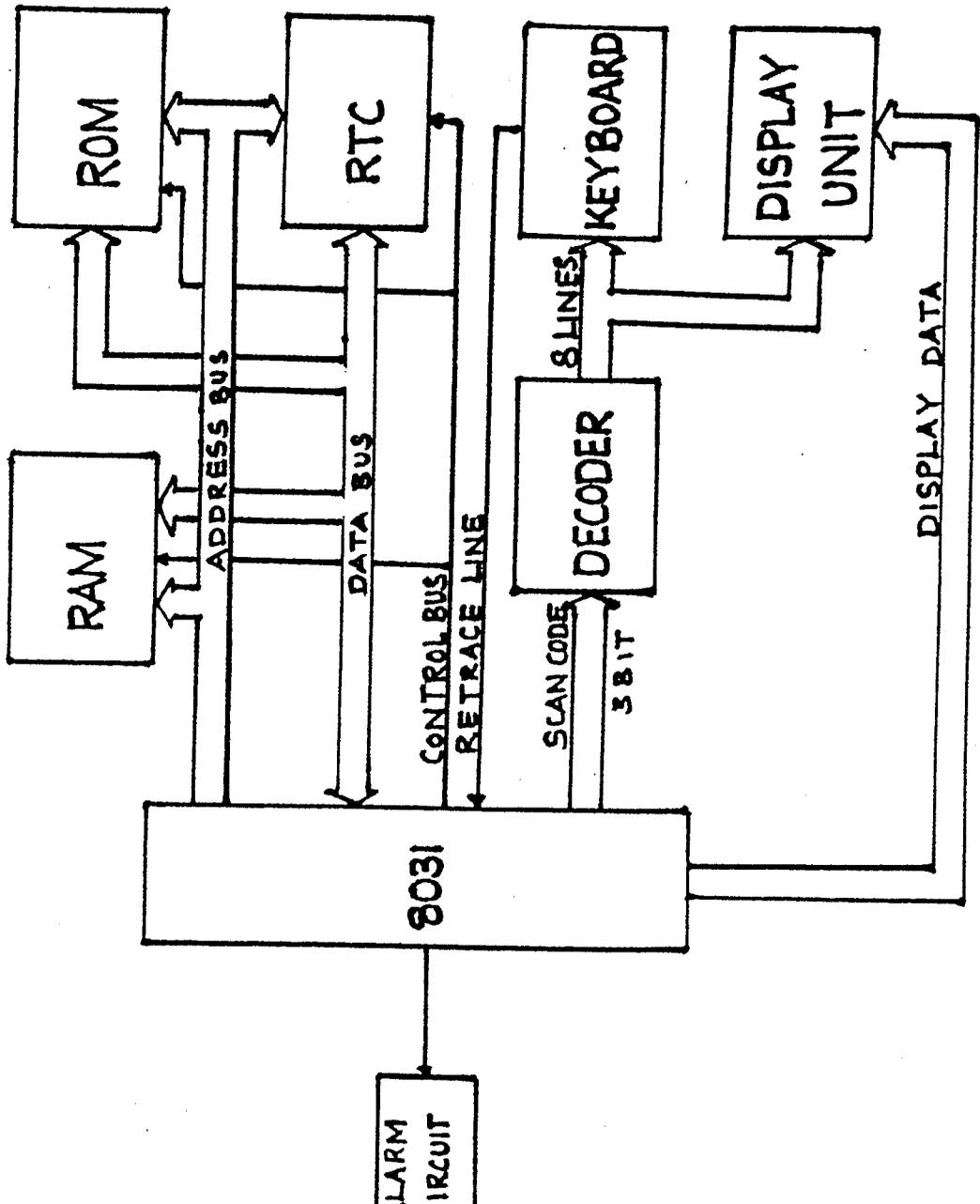
This mode essentially consists of two mode namely time display & calendar display mode

In time display mode ,the display of 7 - segment LED is as shown in Fig 4.9A. The first three segments display the day of week say sun (for Sunday) the next two indicate the hour & the next two seven seg. LED's the minutes. Thus this mode display the current time after the real time clock is synchronized using the time setting mode.

### Calendar Display Mode

The calendar display mode is used for displaying the current Date/mon/year. After the RTC is synchronized using the time setting mode. The toggle/accept key is used for changing the mode from calender to time display or vice versa

In this mode display will be shown in Fig4.9B here the &3 indicates the current date. The fourth & fifth the month and the last two the year.



4.1 BLOCK DIAGRAM OF THE PROGRAMMABLE TIMER

### TIME SETTING MODE :-

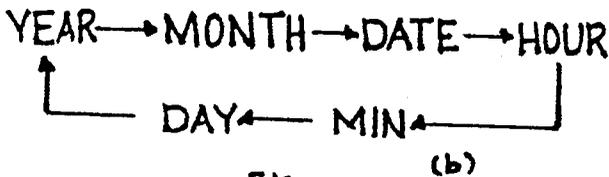
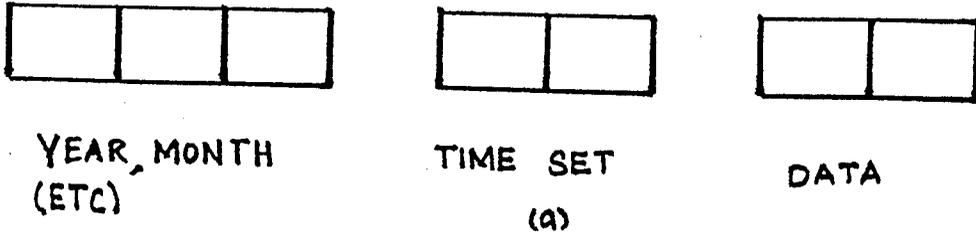


Fig 4.2

### ALARM SETTING MODE :-

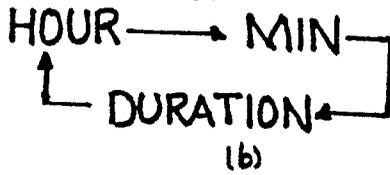
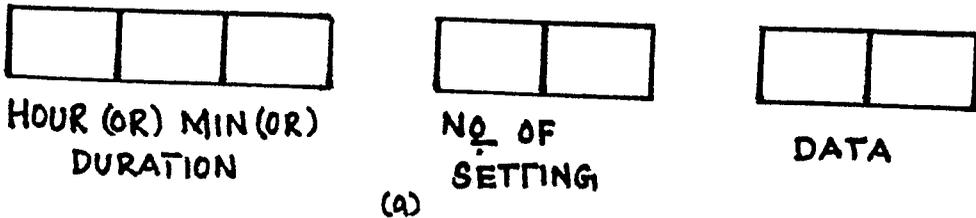


Fig 4.3

### ALARM DELETING MODE :-

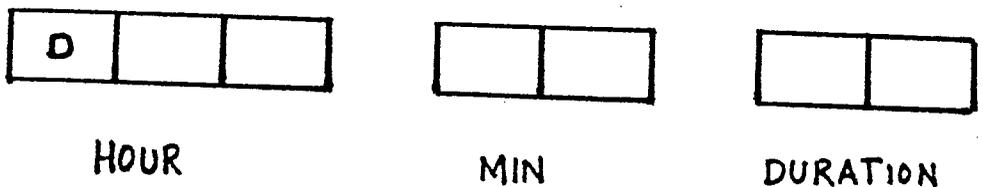


Fig. 4.4.

## HOLIDAY SETTING MODE:-

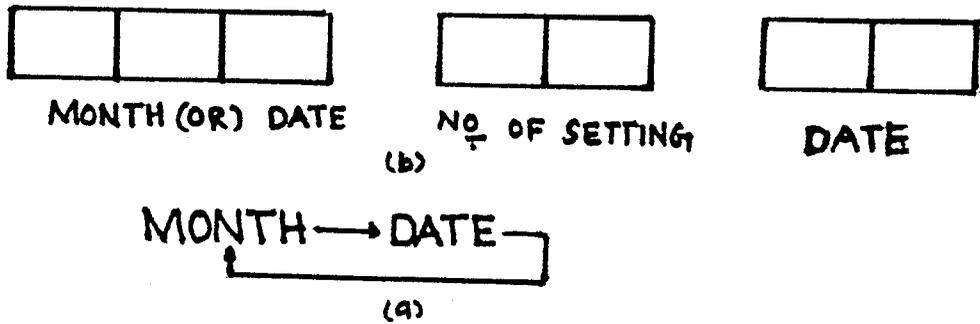


Fig. 4.5

## HOLIDAY DELETING MODE:-

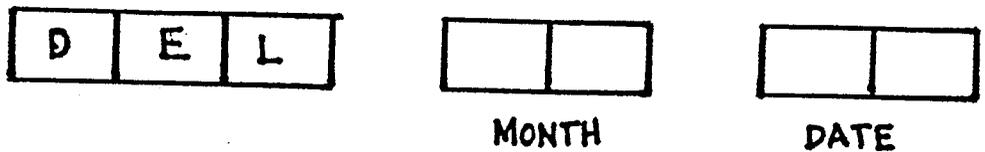


Fig 4.6

## RESET MODE:-

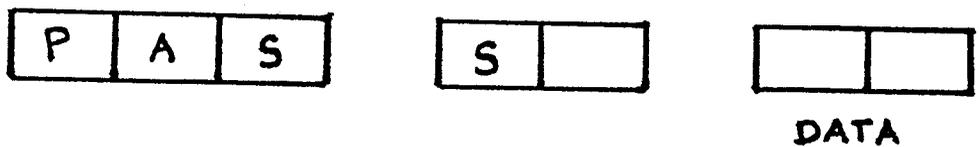


Fig 4.7

# DAY SETTING MODE:-

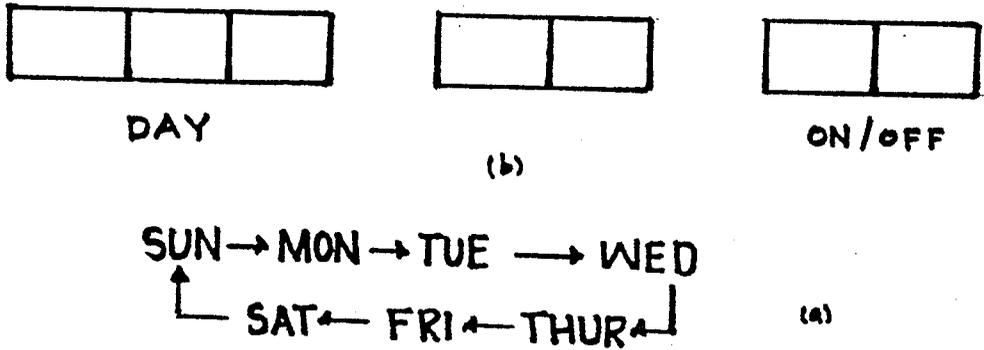


Fig. 4.8

# DISPLAY MODE:-

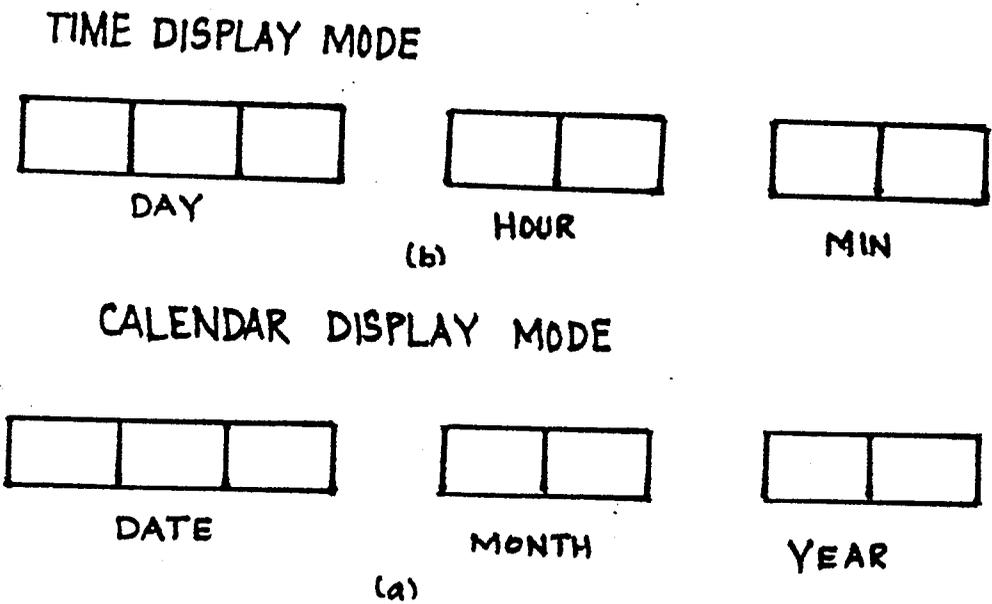


Fig 4.9

*Fabrication...*

## CHAPTER V

### FABRICATION

#### 5.1 INTERFACING MEMORY WITH 8031

The ports  $P_0$  and  $P_2$  gives the address of the memory. The port  $P_0$  constitutes address & data line. The address lines are latched with Arithmetic Latch enable signal (ALE). This signal is given to IC 74LS 373 as shown in Fig 5.1. The Data lines are pulled with the help of 10k resistance. The O/P of 74LS373 is connected with Data bus of 27256 and 6264 (RAM). The memory interfacing is done as shown in Fig 5.2. The address lines  $A_0 - A_{12}$  of 8031 is connected with RAM as such  $A_{13}$ ,  $A_{14}$  is left free &  $A_{15}$  is used for selecting the RAM .

## 5.2 INTERFACING 6242 REAL TIME CLOCK (RTC)

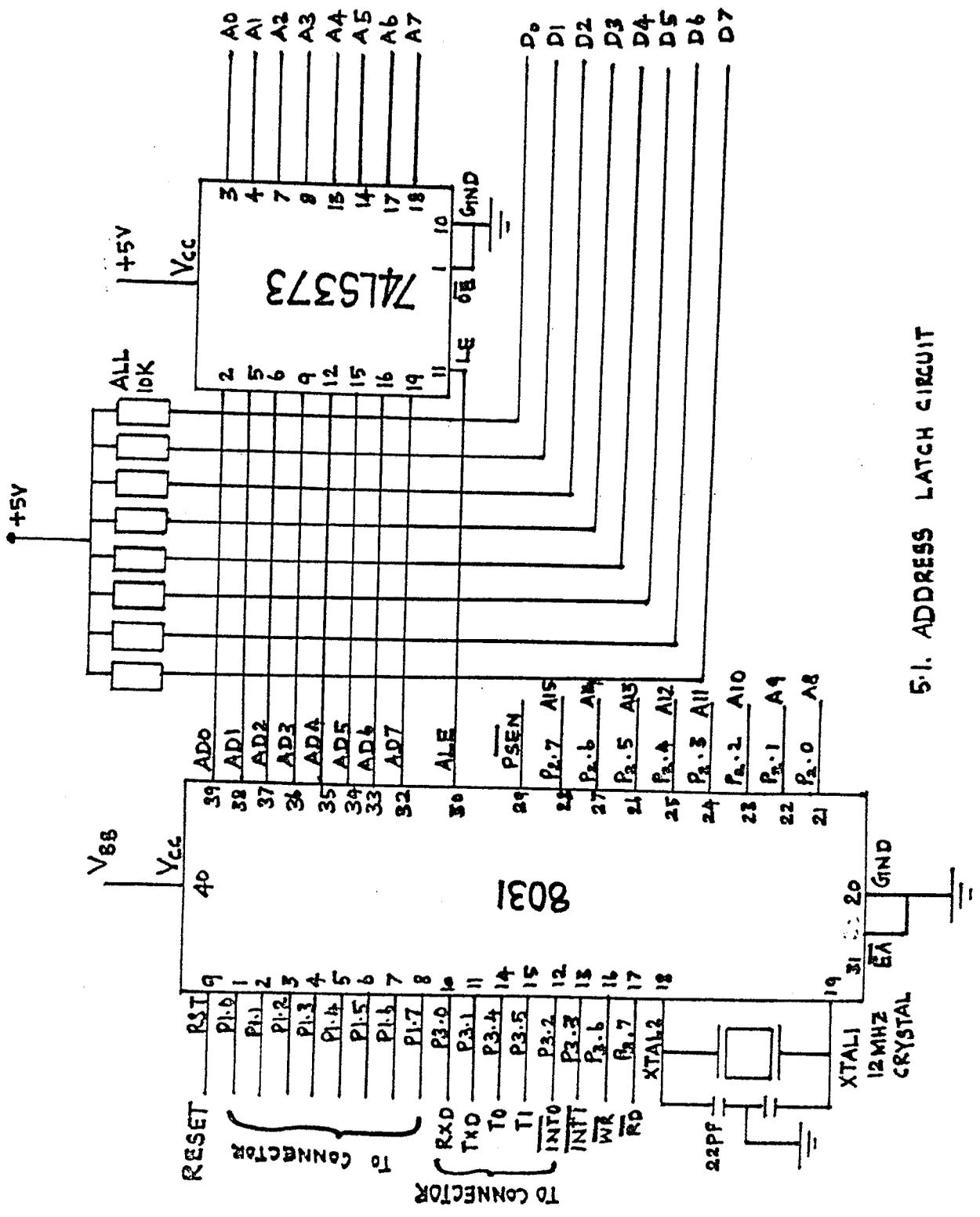
RTC has got 4 bit data bus and a four bit address bus.  $A_0 - A_3$  &  $D_0 - D_3$  of 8031 is connected with 6242 and ALE & RD is properly interfaced. The chip select signal is obtained from  $A_{14}$ .

## 5.3 INTERFACING DISPLAY WITH 8031

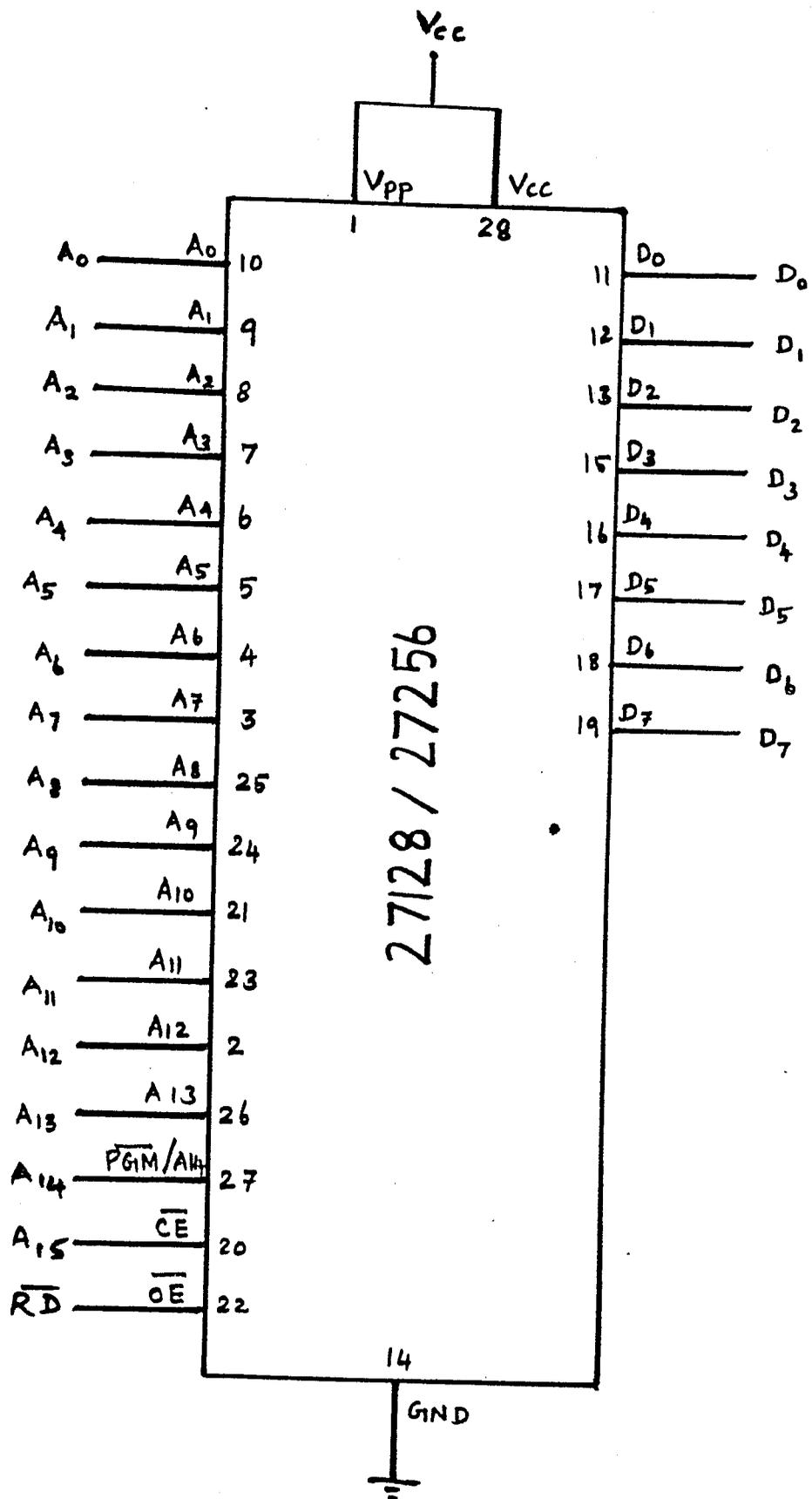
8 lines namely 1 to 8 of 8031 are taken and given as input to the octal transreceiver (i.e. 74LS245). From one output (here pin 18) of 74LS 245 is connected to the segment 'a' of all the seven segment LED DISPLAY . Similar procedure is followed for interfacing other segments with the O/P of the 74LS245. Pin 9,10,11 of 8031 is given as input to the 74LS145 so that any one of the seven segment LED's can be selected at any particular time

#### 5.4 INTERFACING KEYBOARD WITH 8031

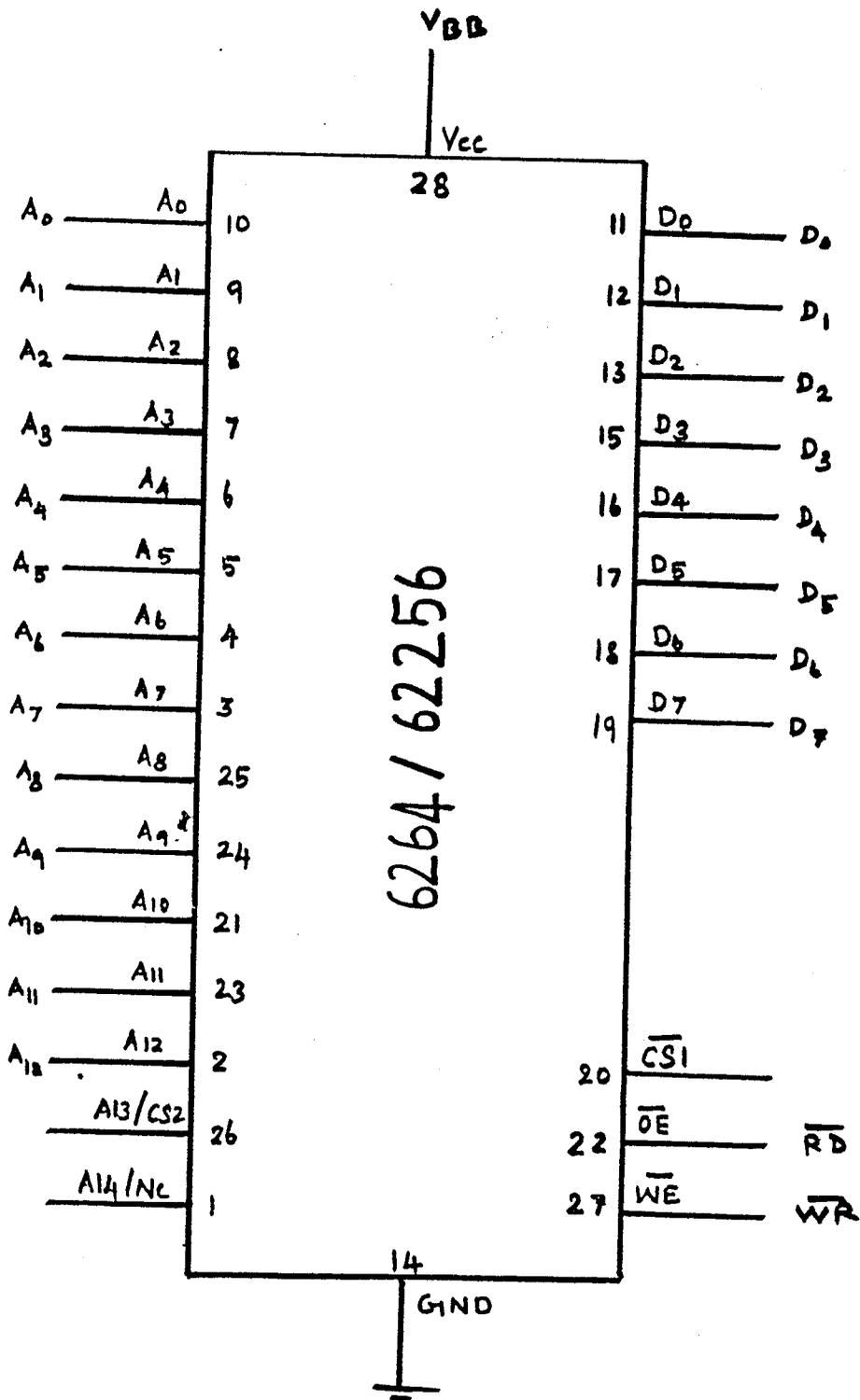
Lines 9,10,11 of 8031 are given as inputs to the decoder 74LS138 and the output of the decoder is directly connected with keyboard. From the keyboard a Retrace line is taken and given back as input to 8031.



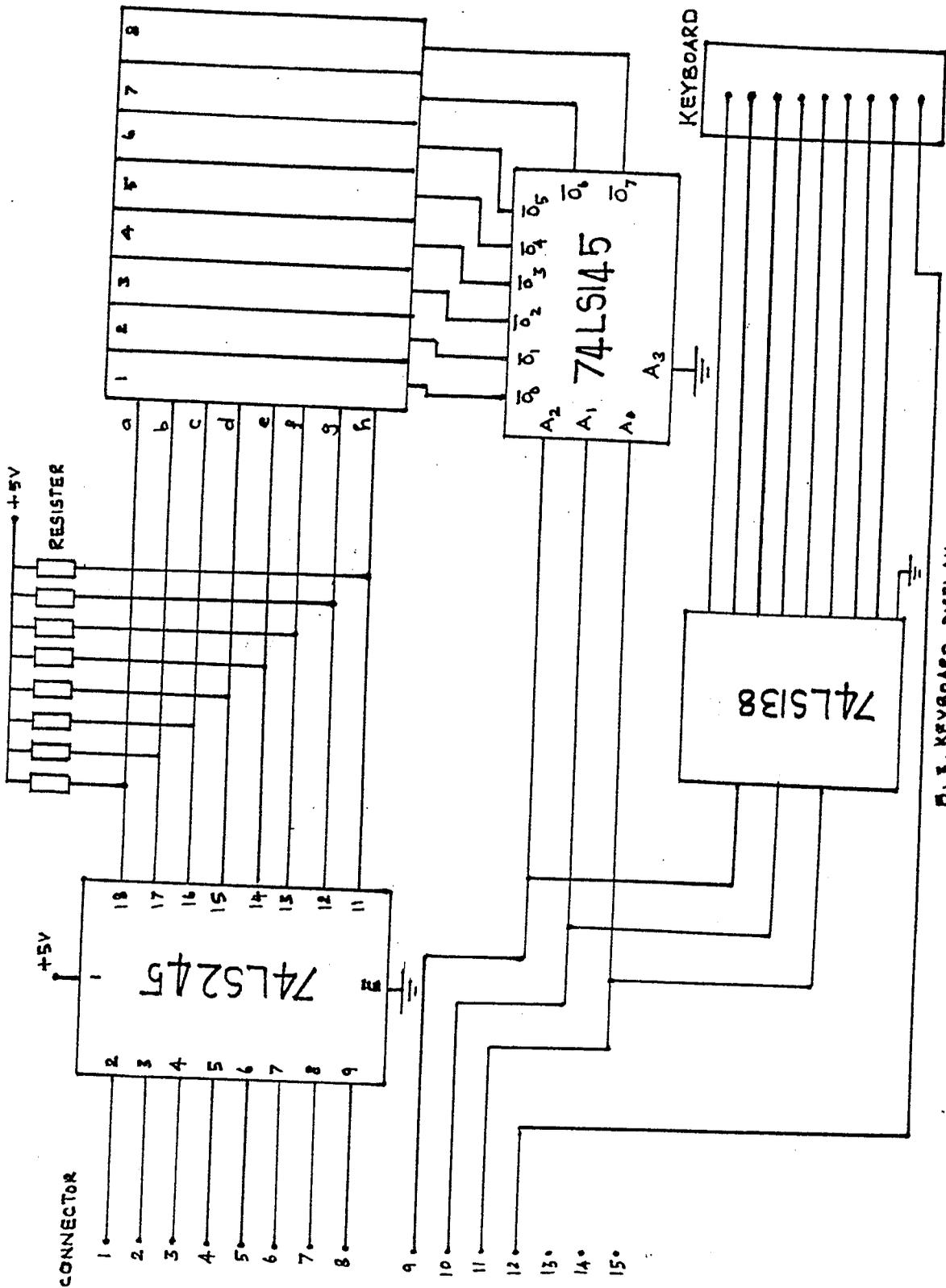
5-1. ADDRESS LATCH CIRCUIT



5.2. Memory Interfacing



### 5.2 MEMORY INTERFACING



D. 3. KEYBOARD DISPLAY INTERFACING CIRCUIT

2X artwork

31 Aug

94

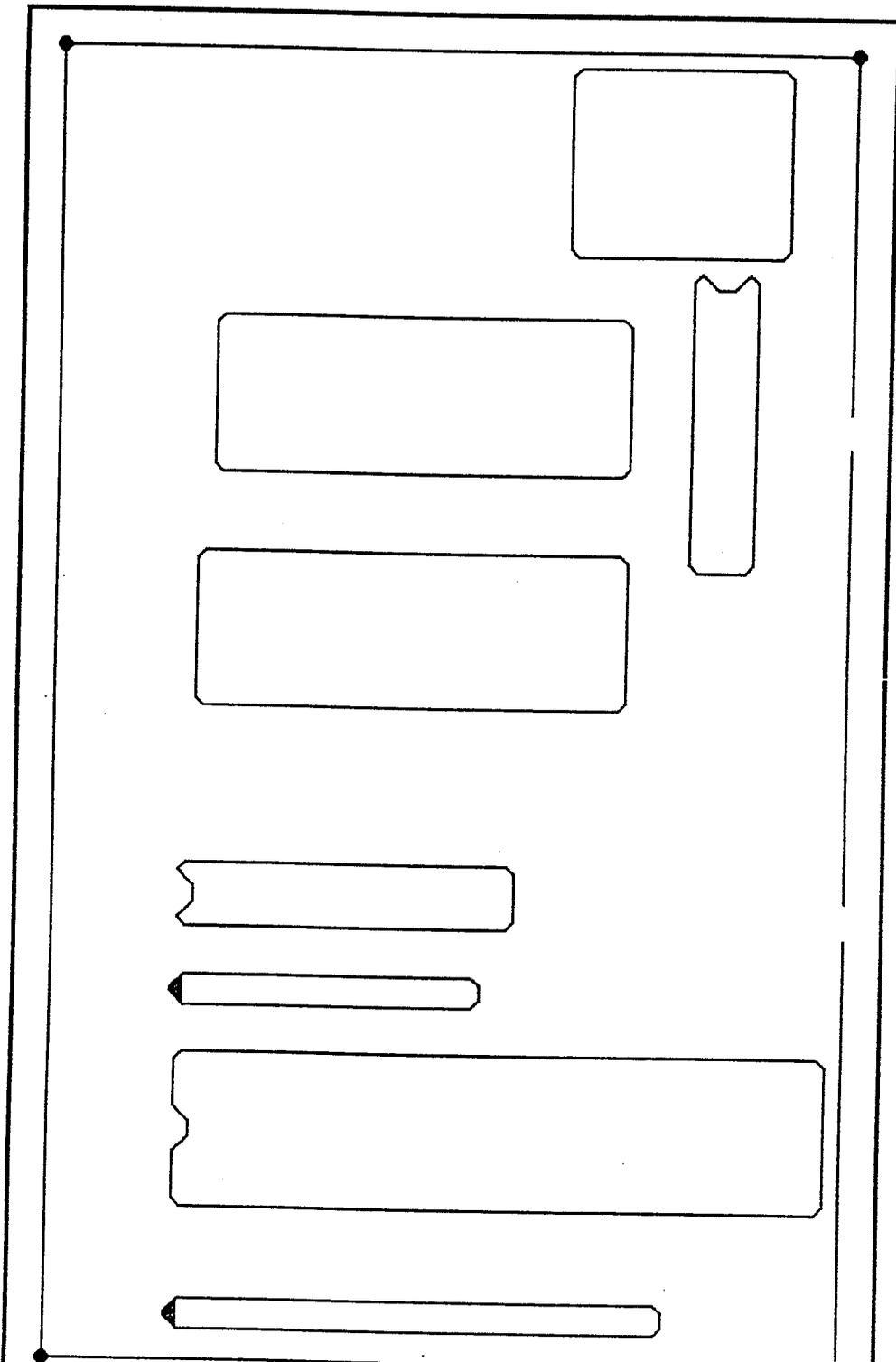
14:52:58

a:dee.pcb

v1.3 r4 holes: 279

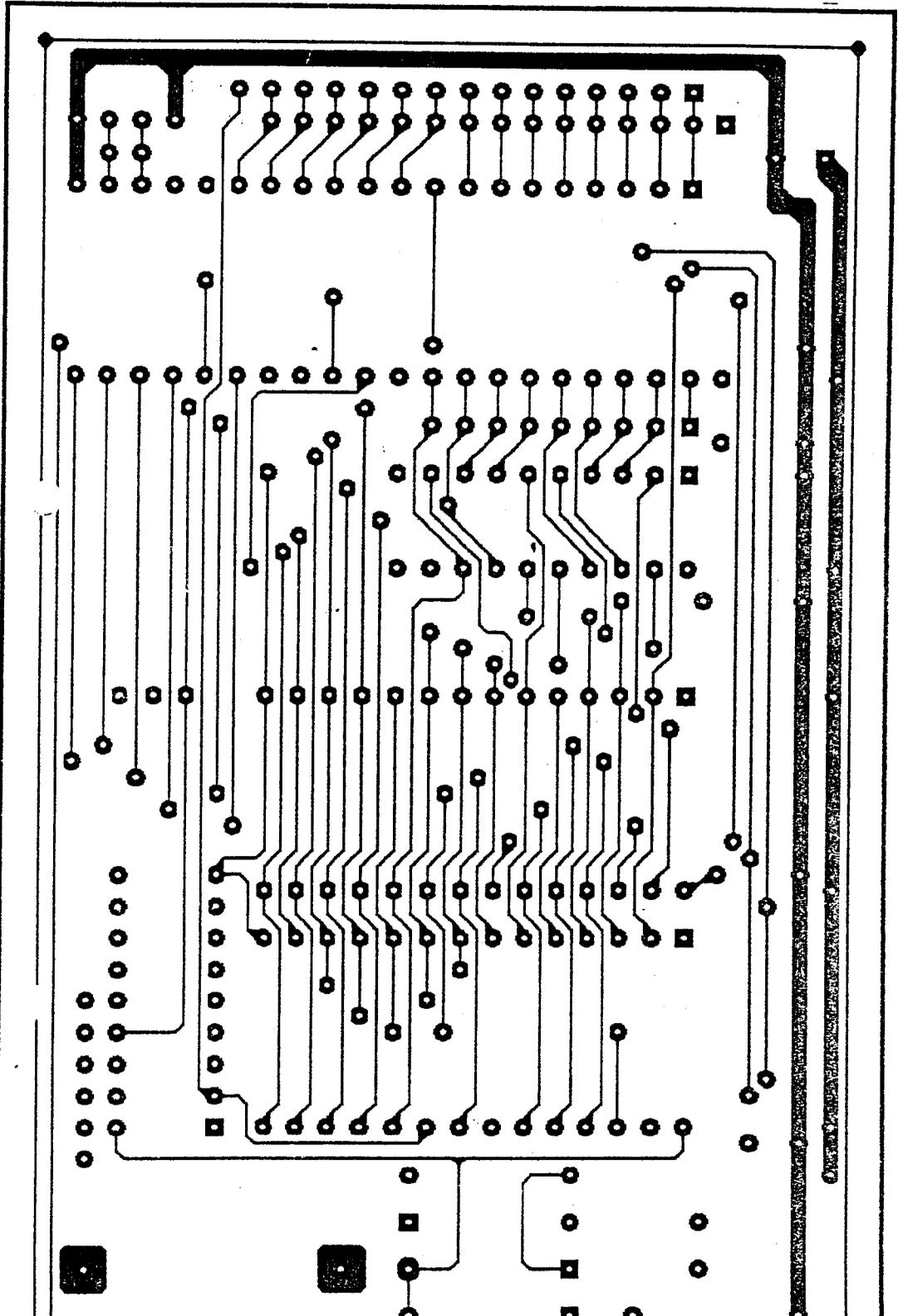
silkscreen

approximate size: 2.55 by 4.25 inches



COMPONENT SIDE

2.55 BY 4.25 INCHES



2X artwork

31 Aug 9

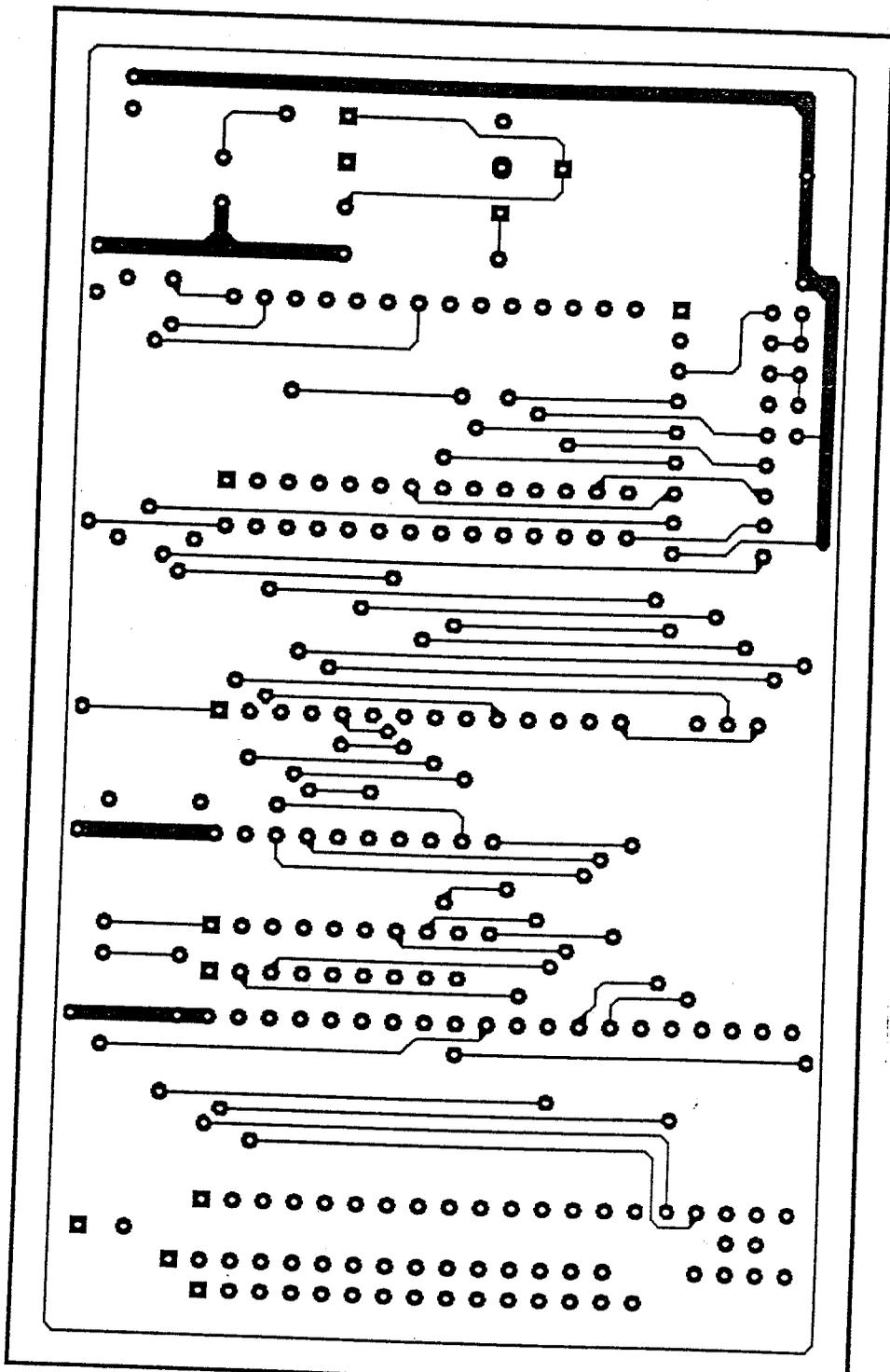
13:31:30

a:dee.pcb

v1.3 r4 holes: 279

approximate size: 2.55 by

solder side  
4.25 inches





2X artwork

21 Oct 92

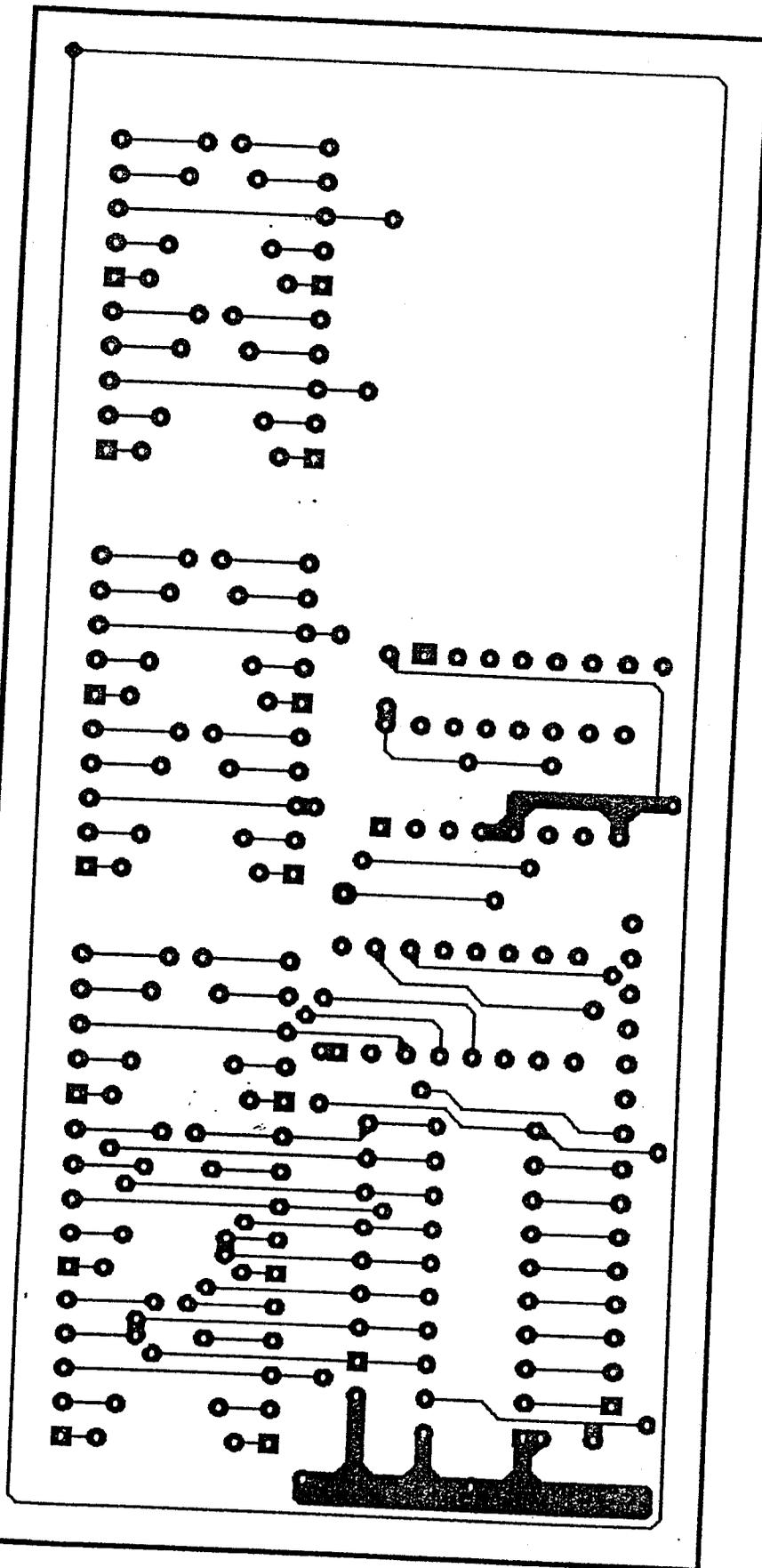
01:31:18

a:\Jag

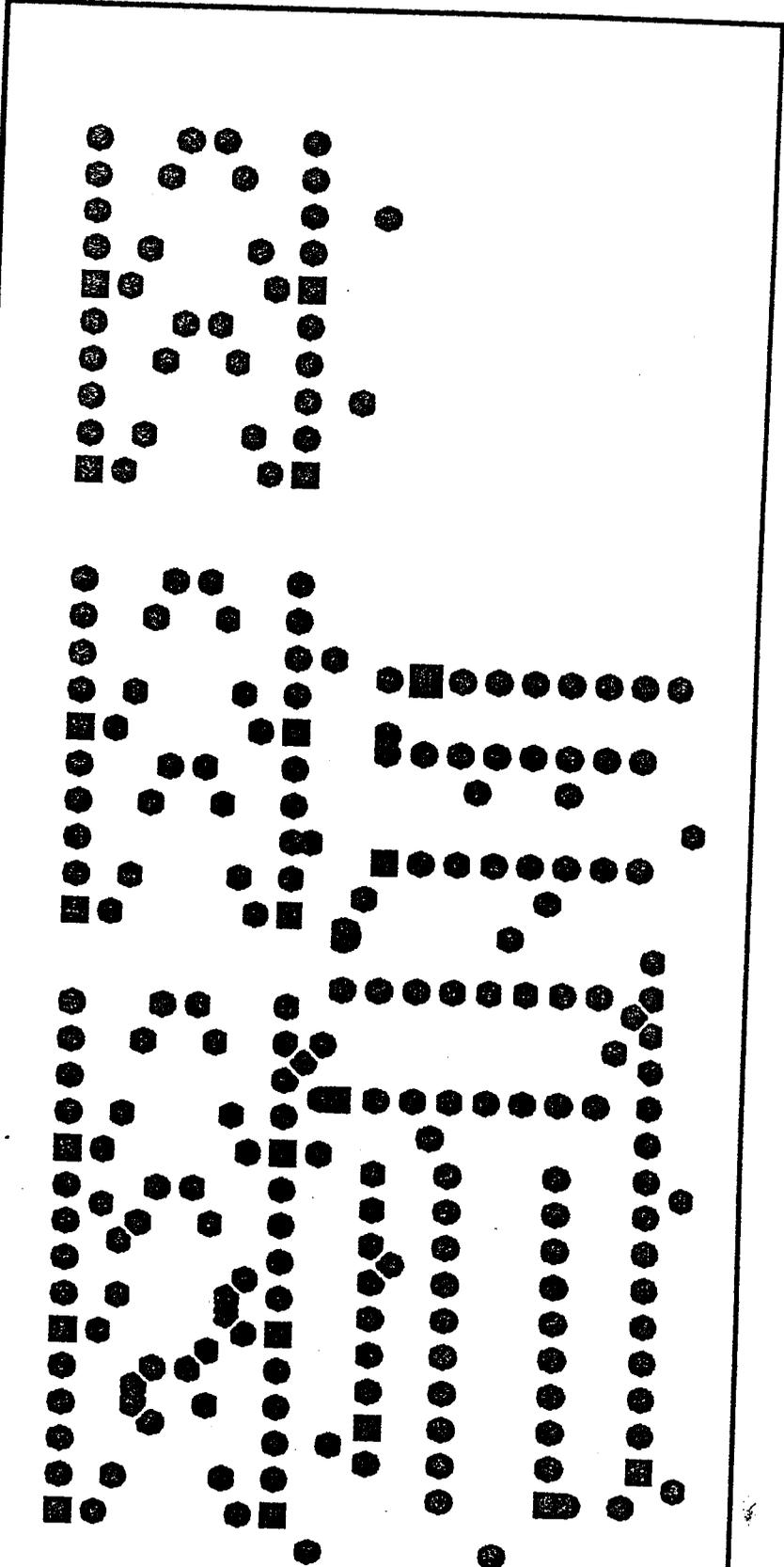
v1.3 r4 holes: 245

solder side

approximate size: 4.25 by 1.95 inches



artwork 21 Oct 92 01:54:46  
Jag  
3 r4 holes: 245 component side mask  
Approximate size: 4.25 by 1.95 inches



## CHAPTER VI

### SOFTWARE

#### 5.1 ALGORITHM

1. Set the time, thus synchronizing the RTC with current year, month, date, hour, minute, day.
2. get the multiple inputs for which the alarm is to  
ring
3. set the timer off on holidays by getting the date &  
month of the holiday.
4. set the timer ON or OFF for each particular day of  
the week.
5. delete the unnecessary alarm and holiday in puts.
6. make the timer to operate in the time display mode.
7. check whether today is a holiday, if so exit from  
the system else go to next step
8. check whether the particular day of the week is set  
if so go to step 9 else exit from the system.

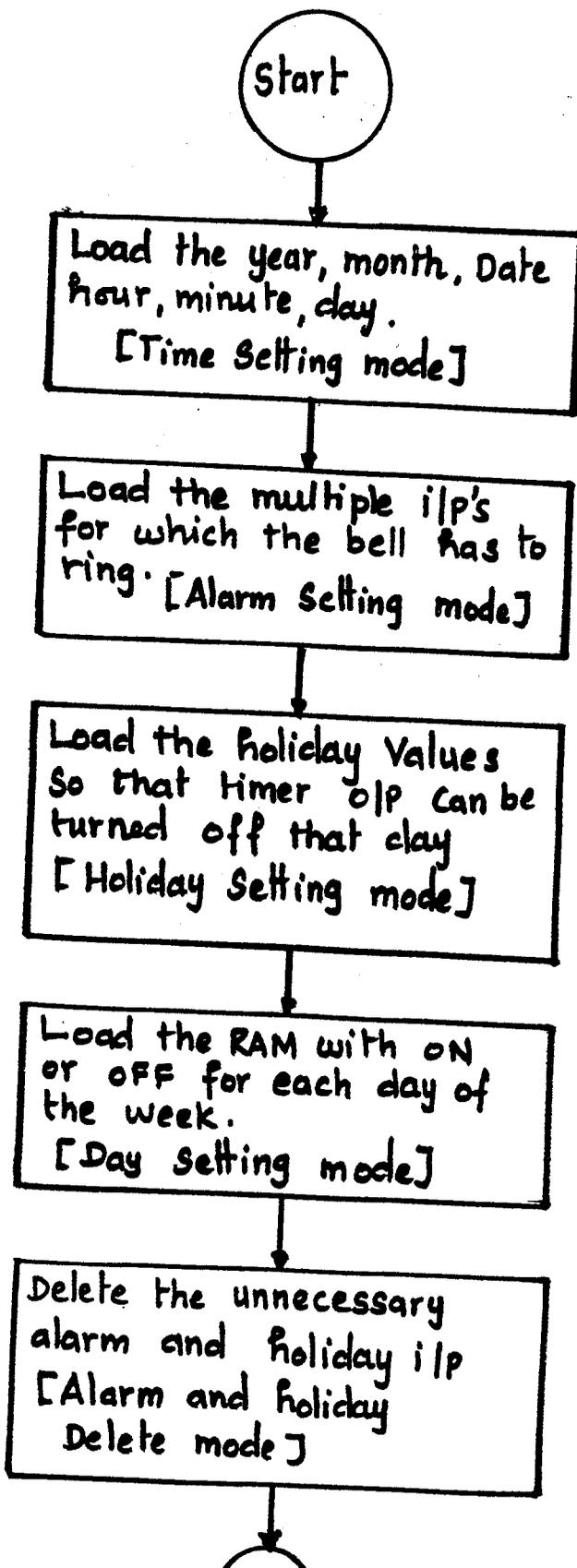
9. check whether if any of the alarm input is equal to the RTC value.

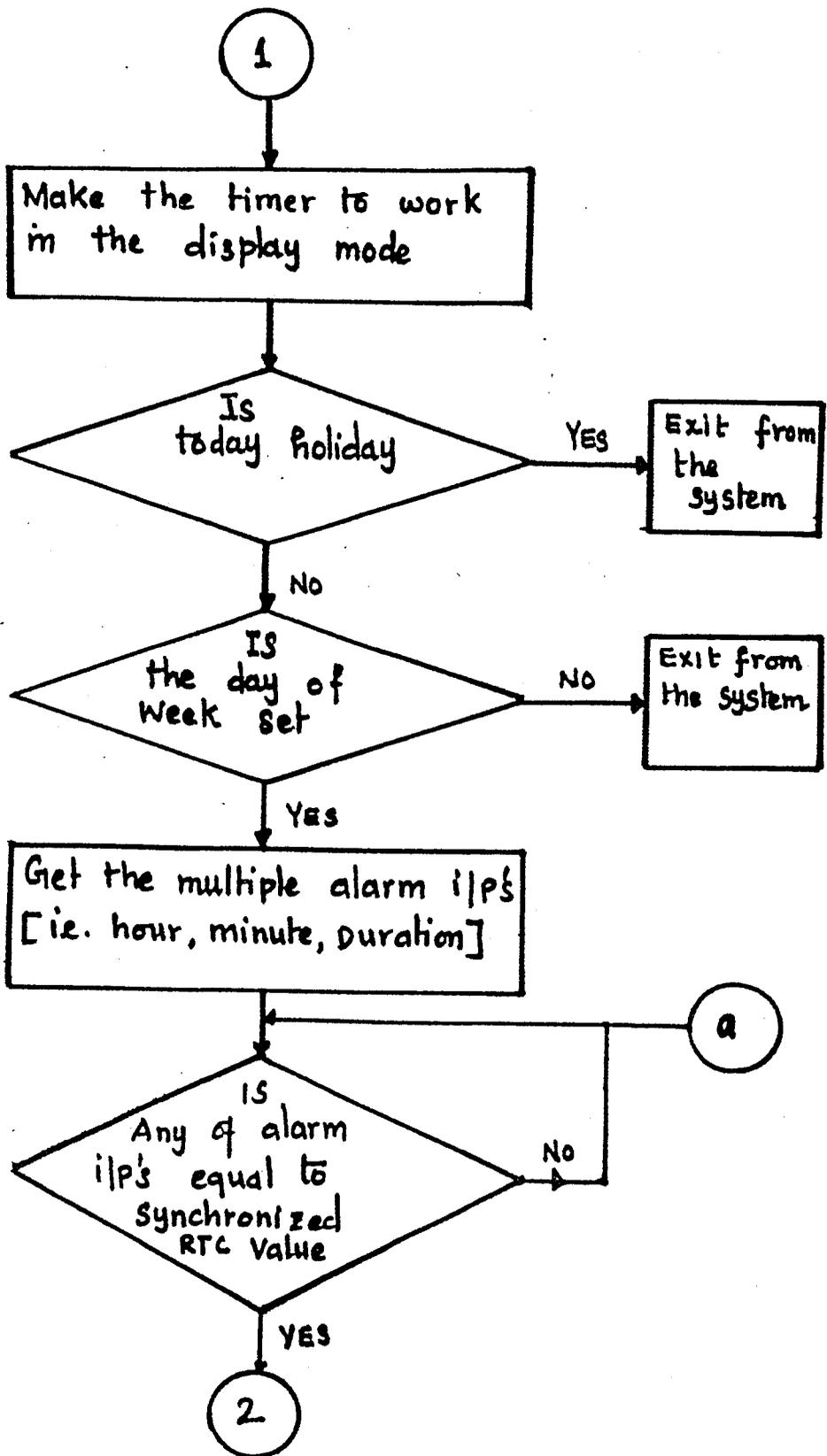
10. if it is not equal then to back to step 9

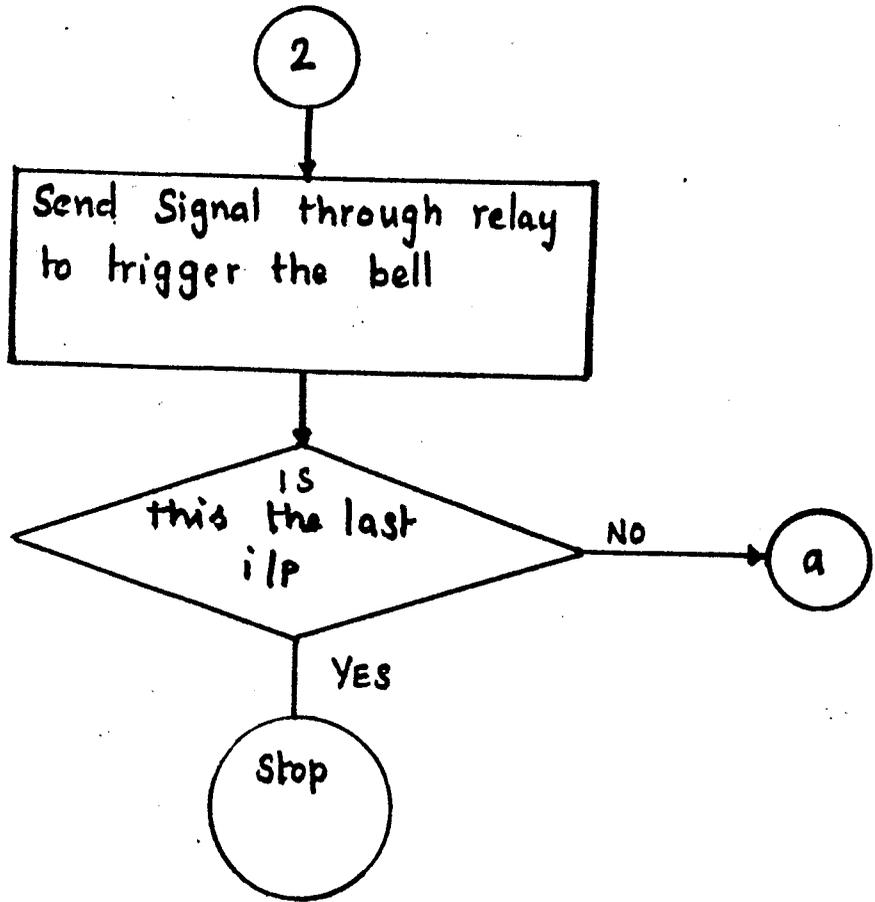
11. if it is equal then send signal through relay trigger the bell.

12. check whether if it is the last input, if so exit from the system else go to step 9.

# FLOWCHART







```
; ADDRESS
RTC EQU 8000H ; Address of Real Time Clock
```

```
; CONSTANTS
TMOD_VALUE EQU 00010101B ; TIMER 1 initialize code
TCNT_VALUE EQU 0FAFFH ; 1ms interrupt count value
```

```
R0$ EQU 00H
R1$ EQU 01H
R2$ EQU 02H
R3$ EQU 03H
R4$ EQU 04H
R5$ EQU 05H
R6$ EQU 06H
R7$ EQU 07H
```

```
FUN1 EQU 10H
FUN2 EQU FUN1+1
FUN3 EQU FUN2+1
FUN4 EQU FUN3+1
FUN5 EQU FUN4+1
FUN6 EQU FUN5+1
FUN7 EQU FUN6+1
```

```
HOU_BUFF EQU FUN7+1
MIN_BUFF EQU HOU_BUFF+1
DU_BUFF EQU MIN_BUFF+1
```

```
TEMP_HOU EQU DU_BUFF+1
TEMP_MIN EQU TEMP_HOU+1
TEMP_DUR EQU TEMP_MIN+1
```

```
HOU_BUFFER EQU TEMP_DUR+1
MIN_BUFFER EQU HOU_BUFFER+1
```

```
TEMP_HOUX EQU MIN_BUFFER+1
TEMP_MINX EQU TEMP_HOUX+1
```

```
FLK0 EQU 25H.0
FLK1 EQU FLK0+1
FLK2 EQU FLK1+1
FLK3 EQU FLK2+1
FLK4 EQU FLK3+1
FLK5 EQU FLK4+1
FLK6 EQU FLK5+1
```

```
FLTEST EQU FLK6+1
FLTEST1 EQU FLTEST+1
```

```
FLINC EQU FLTEST1+1
FLENT EQU FLINC+1
```

```
FLD0 EQU FLENT+1
FLLER EQU FLD0+1
```

```
FLK7 EQU FLLER+1
FLLERX EQU FLK7+1
```

```
FLDURLOADED EQU FLLERX+1
```



FLWDS	EQU	FLSEC+1
FLSET_WE_DAY	EQU	29H
DISP	EQU	30H
CHAR2	EQU	DISP+2
CHAR3	EQU	CHAR2+2
CHAR4	EQU	CHAR3+2
DISP_PTR	EQU	DISP+0AH
BUFFER	EQU	DISP_PTR+1
BUFFER_PTR	EQU	BUFFER+5
SECSRT	EQU	45H
MINRT	EQU	SECSRT+2
HRRT	EQU	MINRT+2
DATERT	EQU	HRRT+2
MONTRT	EQU	DATERT+2
YEARRT	EQU	MONTRT+2
WD	EQU	YEARRT+2
DURATION_BUFFER	EQU	55H
TEMPR	EQU	56H
KEY_DEL	EQU	57H
NUMB_KEYS	EQU	08H
MAX_TIME	EQU	44
MAX_MON	EQU	60
KEY_DEL_VALUE	EQU	50
MINS	EQU	4000H
HOURS	EQU	MINS+1
MONTH	EQU	HOURS+1
DAYX	EQU	MONTH+1
YEARX	EQU	DAYX+1
DURX	EQU	YEARX+1
BMINS	EQU	DURX+1
BHOURS	EQU	BMINS+1
BMONTH	EQU	BHOURS+1
BDAYX	EQU	BMONTH+1
BYEARX	EQU	BDAYX+1
BDURX	EQU	BYEARX+1
ST_TIME_BUFF	EQU	4050H
SORT_COUNT	EQU	4025H
SORT_COUNT1	EQU	SORT_COUNT+1
DEL_DATA	EQU	SORT_COUNT1+1
SORT_COUNTA	EQU	DEL_DATA+1
ST_TIME_BUFFX	EQU	4350H
SORT_COUNTX	EQU	4030H
SORT_COUNTX1	EQU	SORT_COUNTX+1
DEL_DATAX	EQU	SORT_COUNTX1+1

```

STORE_WEEK                EQU        DURATION_BUFFER1+1

        ORG        0000H

        JMP        START

;* External interrupt-0 *
        ORG        0003H
        RETI

;* Internal interrupt-0 *
        ORG        000BH
        RETI

        ORG        0013H
        RETI

        ORG        001BH
        JMP        TMR1_ISR        ; TIMER - 1 service routine

        ORG        0023H
        RETI        ; For later modification

TMR1_ISR:
        PUSH       DPL
        PUSH       DPH

        CLR        TR1            ; Reload the Timer1
        MOV        TL1,#LOW (TCNT_VALUE)
        MOV        TH1,#HIGH (TCNT_VALUE)
        SETB       TR1
        CALL       KDI
        POP        DPH
        POP        DPL
        SETB       EA
        RETI

START:
        MOV        SP,#65H
        CLR        EA
        SETB       EA
        MOV        IE,#10001000B
        MOV        TMOD,#TMOD_VALUE
        MOV        TL1,#LOW (TCNT_VALUE)
        MOV        TH1,#HIGH (TCNT_VALUE)
        SETB       EA
        CALL       CLFL            ; CLEARS ALL KEY FLAGS
        CALL       SEFL
        CALL       INT_FUC
        CALL       LOAD_SORT_COUNT1
        CALL       LOAD_SORT_COUNTX1
        CALL       DUR_WAIT
        CALL       L_SORT_C_A
        MOV        R2,#OFFH
        MOV        R1,#NUMB_KEYS
        MOV        R3,#08
        SETB       TR1

```

```

X:
    SJMP    XSTART

L_SORT_C_A:
    MOV     DPTR,#SORT_COUNT           ;LOAD SORT COUNT
    MOVX    A,@DPTR
    MOV     DPTR,#SORT_COUNTA
    MOVX    @DPTR,A
    RET

DUR_WAIT:
    MOV     DPTR,#DURATION_BUFFER1    ;DURATION WAIT 65 SECONDS
    MOV     A,#65
    MOVX    @DPTR,A
    RET

INT_FUC:
    ;NUMBER OF FUNCTIONS
    MOV     RO,#FUN1
    MOV     @RO,#06
    INC     RO
    MOV     @RO,#03
    INC     RO
    MOV     @RO,#00
    INC     RO
    MOV     @RO,#02
    INC     RO
    MOV     @RO,#00
    RET

SEFL:
    SETB    FLTEST1
    SETB    FLK0
    SETB    FLK1
    SETB    FLK2
    SETB    FLK3
    SETB    FLK4
    SETB    P3.3
    RET

PUTT:
    MOV     RO,#BUFFER
    MOV     DPTR,#BMINS
    MOVX    A,@DPTR
    MOV     @RO,A
    RET

PUTTH:
    MOV     RO,#BUFFER+1
    MOV     DPTR,#BMINS+1
    MOVX    A,@DPTR
    MOV     @RO,A
    RET

PUTTM:
    MOV     RO,#BUFFER+2
    MOV     DPTR,#BMINS+2
    MOVX    A,@DPTR

```

```

FUTTD:
    MOV     RO,#BUFFER+3
    MOV     DPTR,#BMINS+3
    MOVX    A,@DPTR
    MOV     @RO,A
    RET

KDI:
    CALL    DISP_BLK           ;KEYBOARD AND DISPLAY UPDATION
    DEC     R1

    CALL    KEY_SCAN

    CALL    SELECT_DIGIT

    CALL    DISP_DIGIT

    INC     R1
    DJNZ   R1,DISP11
    MOV     R1,#07

DISP11:
    MOV     DPTR,#RTC+15       ;DISPLAYS REAL TIME CLOCK
    MOV     A,#00000100B
    MOVX    @DPTR,A

SLAVE:
    CJNE   R3,#08,TIMEX1
    MOV     DPTR,#RTC+13
    MOV     A,#00000000B
    MOVX    @DPTR,A
    MOV     R7,#0DH
    MOV     DPTR,#RTC+13
    MOV     A,#00000001B
    MOVX    @DPTR,A
    MOV     DPTR,#RTC+13
    MOVX    A,@DPTR
    JB     ACC.1,SLAVE
    MOV     RO,#SECSRT
    MOV     DPTR,#RTC
RPT:
    MOVX    A,@DPTR
    ANL    A,#0FH
    MOV     @RO,A
    INC     RO
    INC     DPTR
    DJNZ   R7,RPT
    MOV     DPTR,#RTC+13
    MOV     A,#00000000B
    MOVX    @DPTR,A

    CALL    CHK_TIME_CODE
    JB     FLDURLOADED,DAYAX

JUG:
    CALL    TIMEX

```

```

;-----
;PROCEDURE TO FIND TIME MATCH AND ACTIVATE BELLING
;-----

```

DAYAX:

```

CALL    CHK_SEC
JNB     FLSEC,COW
JNB     FLK7,JUG
CLR     FLK7
JMP     DAYAX2

```

COW:

```

JB      FLK7,JUG
SETB   FLK7

```

DAYAX2:

```

MOV     DPTR,#DURATION_BUFFER1
MOVX   A,@DPTR
JZ      DAYAX1
DEC     A
MOVX   @DPTR,A
MOV     RO,#DURATION_BUFFER
MOV     A,@RO
JZ      JUG1
CLR     P3.3
DEC     A
MOV     @RO,A
JMP     JUG

```

JUG1:

```

SETB   P3.3
JMP     JUG

```

DAYAX1:

```

MOV     A,#65
MOVX   @DPTR,A
CLR     FLDURLOADED
JMP     JUG

```

CHK\_SEC:

```

MOV     RO,#SECSRT
MOV     A,@RO
JB      ACC.0,LRCC
SETB   FLSEC
RET

```

LRCC:

```

CLR     FLSEC
RET

```

SELECT\_DIGIT:

```

MOV     DPTR,#SEL_DIG
MOV     B,#03
MOV     A,R1
MUL    AB
JMP     @A+DPTR

```

;DIGIT TO BE ACTIVATED

SEL\_DIG:

```

LJMP   DISP6
LJMP   DISP5
LJMP   DISP4
LJMP   DISP3
LJMP   DISP2
LJMP   DISP1
LJMP   DISFO
LJMP   DISP7

```

```

DISP0:
    CLR    P3.0
    CLR    P3.1
    CLR    P3.2
    RET

DISP1:
    SETB   P3.0
    CLR    P3.1
    CLR    P3.2
    RET

DISP2:
    CLR    P3.0
    SETB   P3.1
    CLR    P3.2
    RET

DISP3:
    SETB   P3.0
    SETB   P3.1
    CLR    P3.2
    RET

DISP4:
    CLR    P3.0
    CLR    P3.1
    SETB   P3.2
    RET

DISP5:
    SETB   P3.0
    CLR    P3.1
    SETB   P3.2
    RET

DISP6:
    CLR    P3.0
    SETB   P3.1
    SETB   P3.2
    RET

DISP7:
    SETB   P3.0
    SETB   P3.1
    SETB   P3.2
    RET

DISP_DIGIT:
    MOV    A,R1
    MOV    RO,#DISP
    ADD    A,RO
    MOV    RO,A
    MOV    A,@RO
    MOV    P1,A
    RET

DISP_BLK:
    MOV    A,#BLANK_CODE
    MOV    P1,A
    RET

```

```

KEY_SCAN:                                ;KEY BOARD SENCING WITH DEBOUNCE
      JNB      FLTEST1,TEST3

      JNB      FLTEST,TEST
      MOV      A,R2
      CJNE    A,R1#,TEST4

TEST:
      JB       P3.4,TEST1
      JMP      LOCATE

TEST1:
      CLR      FLTEST
      JMP      TEST4

TEST3:
      MOV      R0,#KEY_DEL
      DEC      @R0
      CJNE    @R0,#00,TEST4
      MOV      @R0,#KEY_DEL_VALUE
      SETB    FLTEST1

TEST4:
      RET

LOCATE:
      CPL      FLTEST
      JNB      FLTEST,TEST2
      CLR      FLTEST1
      MOV      2,R1
      JMP      TEST4

TEST2:
      SETB    FLTEST1
      MOV      DPTR,#CONTROL
      MOV      B,#03H
      MOV      A,R1
      MUL     AB
      JMP     @A+DPTR

```

```

;-----
;PROCEDURE FOR FINDING CODE MATCH IN BUFFER & LOADS THE DURATION
;-----

```

```

CHK_TIME_CODE:
      PUSH    5
      PUSH    6
      JB      FLDURLOADED,RTYYY

      MOV     DPTR,#SORT_COUNTA
      MOVX   A,@DFTR
      JZ     CTC3
      MOV     R5,A

;CTC1:
      DEC     R5
      CALL   ADDR_CALC
      MOVX   A,@DFTR
      MOV     R6,A
      MOV     R0,#HRSRT
      MOV     A,@R0
      ANL    A,#0FH
      MOV     B,A

```

```

        INC     R0
        MOV     A,@R0
        ANL    A,#0FH
        SWAP   A
        ORL    A,B
        CJNE   A,R6#,CTC2
        INC    DPTR
        MOVX   A,@DPTR
        MOV    R6,A
        MOV    R0,#MINRT
        MOV    A,@R0
        ANL    A,#0FH
        MOV    B,A
        INC    R0
        MOV    A,@R0
        ANL    A,#0FH
        SWAP   A
        ORL    A,B
        CJNE   A,R6#,CTC2

        INC    DPTR
        MOVX   A,@DPTR
        MOV    R0,#DURATION_BUFFER
        MOV    @R0,A

;      JMP     CHK_DAY_DATE           ; CHECK

RTYYY:  SETB   FLDURLOADED

        POP    6
        POP    5

CTC2:   RET

        INC    R5
        DJNZ   R5,CTC3
        CALL   L_SORT_C_A
        POP    6
        POP    5
        RET

CTC3:   MOV    A,R5
        MOV    DPTR,#SORT_COUNTA
        MOVX   @DPTR,A
        POP    6
        POP    5

        RET

;-----
; COMPARES W AND C
;-----
CHK_DAY_DATE:

        MOV    DPTR,#STORE_WEEK     ; CHECK
        MOVX   A,@DPTR
        MOV    R6,A
        CALL   ABCD
        ANL    A,R6
        JZ     CHK_NEXT

```

```

        POP        6
        POP        5

        RET                                ; CHECK

ABCD:
        MOV        DPTR,#FIND_EQUAL
        MOV        RO,#WD
        MOV        A,@RO
        MOV        B,#03
        MUL        AB
        JMP        @A+DPTR

FIND_EQUAL:
        LJMP       S1
        LJMP       M1
        LJMP       AT1
        LJMP       W1
        LJMP       H1
        LJMP       F1
        LJMP       XA1
        LJMP       S33                                ; SAFE

S1:
        MOV        A,#00000001B
        RET

M1:
        MOV        A,#00000010B
        RET

AT1:
        MOV        A,#00000100B
        RET

W1:
        MOV        A,#00001000B
        RET

H1:
        MOV        A,#00010000B
        RET

F1:
        MOV        A,001000000B
        RET

XA1:
        MOV        A,01000000B
        RET

S33:
        RET

CHK_NEXT:
        MOV        DPTR,#SORT_COUNTX
        MOVX       A,@DPTR
        JZ         CN21
        MOV        R5,A

```

CN2:

```
DEC      R5
CALL     ADDR_CALCY
MOVX     A,@DPTR
MOV      R6,A
MOV      RO,#MONTRT           ;CHECK\
MOV      A,@RO
ANL      A,#OFH
MOV      B,A
INC      RO
MOV      A,@RO
ANL      A,#OFH
SWAP     A
ORL      A,B
CJNE     A,R6$,CN1
INC      DPTR
MOVX     A,@DPTR
MOV      R6,A
MOV      RO,#DATERT           ;CHECK\
MOV      A,@RO
ANL      A,#OFH
MOV      B,A
INC      RO
MOV      A,@RO
ANL      A,#OFH
SWAP     A
ORL      A,B
CJNE     A,R6$,CN1

POP      6
POP      5

RET
```

CN1:

```
INC      R5
DJNZ     R5,CN2
```

CN21:

```
JMP      RTYYY
```

```
-----
; LOAD DISPLAY FROM RTC DEPENDING UPON THE FLAG INPUT
;-----
```

TIMEX:

```
RTT1:    JNB      FLK6,RTT0
          CALL     LOAD_RSEC
          CALL     LOAD_RMIN
          CALL     LOAD_RHOU
          CALL     LOAD_RWEEK
          RET

RTT0:    CALL     LOAD_RYEAR
          CALL     LOAD_RMON
          CALL     LOAD_RDATE
          RET
```

```

;-----
; VARIOUS FUNCTIONS TO DISPLAY CALENDER
;-----

```

```

LOAD_RSEC:

```

```

    MOV     RO,#SECSRT
    MOV     A,@RO
    MOV     RO,#CHAR4+1
    JB     ACC.0,LRC
    MOV     @RO,#BLANK_CODE
    RET

```

```

LRC:

```

```

    MOV     @RO,#DASH_CODE
    RET

```

```

LOAD_RMIN:

```

```

    MOV     DPTR,#DISPL_TBL
    MOV     RO,#MINRT
    MOV     A,@RO
    MOVC   A,@A+DPTR
    MOV     RO,#DISP
    MOV     @RO,A
    MOV     RO,#MINRT+1
    MOV     A,@RO
    MOVC   A,@A+DPTR
    MOV     RO,#DISP+1
    MOV     @RO,A
    RET

```

```

LOAD_RHOU:

```

```

    MOV     DPTR,#DISPL_TBL
    MOV     RO,#HRSRT
    MOV     A,@RO
    MOVC   A,@A+DPTR
    MOV     RO,#CHAR2
    MOV     @RO,A
    MOV     RO,#HRSRT+1
    MOV     A,@RO
    MOVC   A,@A+DPTR
    MOV     RO,#CHAR2+1
    MOV     @RO,A
    RET

```

```

LOAD_RWEEK:

```

```

    MOV     DPTR,#WEEKJMP
    MOV     RO,#WD
    MOV     A,@RO
    MOV     B,#03
    MUL    AB
    JMP     @A+DPTR

```

```

WEEKJMP:

```

```

    LJMP   WEEK0
    LJMP   WEEK1
    LJMP   WEEK2
    LJMP   WEEK3
    LJMP   WEEK4
    LJMP   WEEK5
    LJMP   WEEK6

```

```

WEEK0:
    MOV     RO,#CHAR3
    MOV     @RO,#N_CODE
    INC     RO
    MOV     @RO,#U_CODE
    INC     RO
    MOV     @RO,#S_CODE
    RET

WEEK1:
    MOV     RO,#CHAR3
    MOV     @RO,#N_CODE
    INC     RO
    MOV     @RO,#O_CODE
    INC     RO
    MOV     @RO,#M_CODE
    RET

WEEK2:
    MOV     RO,#CHAR3
    MOV     @RO,#E_CODE
    INC     RO
    MOV     @RO,#U_CODE
    INC     RO
    MOV     @RO,#T_CODE
    RET

WEEK3:
    MOV     RO,#CHAR3
    MOV     @RO,#D_CODE
    INC     RO
    MOV     @RO,#E_CODE
    INC     RO
    MOV     @RO,#W_CODE
    RET

WEEK4:
    MOV     RO,#CHAR3
    MOV     @RO,#R_CODE
    INC     RO
    MOV     @RO,#H_CODE
    INC     RO
    MOV     @RO,#T_CODE
    RET

WEEK5:
    MOV     RO,#CHAR3
    MOV     @RO,#I_CODE
    INC     RO
    MOV     @RO,#R_CODE
    INC     RO
    MOV     @RO,#F_CODE
    RET

WEEK6:
    MOV     RO,#CHAR3
    MOV     @RO,#T_CODE
    INC     RO

```

```
MOV    @RO,#A_CODE
INC    RO
MOV    @RO,#S_CODE
RET
```

LOAD\_RYEAR:

```
MOV    DPTR,#DISPL_TBL
MOV    RO,#YEARRT
MOV    A,@RO
MOVC   A,@A+DPTR
MOV    RO,#DISP
MOV    @RO,A
MOV    RO,#YEARRT+1
MOV    A,@RO
MOVC   A,@A+DPTR
MOV    RO,#DISP+1
MOV    @RO,A
RET
```

LOAD\_RMON:

```
MOV    DPTR,#DISPL_TBL
MOV    RO,#MONTRT
MOV    A,@RO
MOVC   A,@A+DPTR
MOV    RO,#CHAR2
MOV    @RO,A
MOV    RO,#MONTRT+1
MOV    A,@RO
MOVC   A,@A+DPTR
MOV    RO,#CHAR2+1
MOV    @RO,A
RET
```

LOAD\_RDATE:

```
MOV    DPTR,#DISPL_TBL
MOV    RO,#DATERT
MOV    A,@RO
MOVC   A,@A+DPTR
MOV    RO,#CHAR3
MOV    @RO,A
MOV    RO,#DATERT+1
MOV    A,@RO
MOVC   A,@A+DPTR
MOV    RO,#CHAR3+1
MOV    @RO,A
RET
```

CLFL:

```
CLR    FLINC
CLR    FLENT
CLR    FLDD
CLR    FLK5
CLR    FLK6
CLR    FLTEST
CLR    FLDURLOADED
CLR    FLWDS
RET
```

-----  
; TRANSFERS THE CONTROL TO THE REQUIRED ROUTINE  
-----

CONTROL:

LJMP SFK0  
LJMP SFK1  
LJMP SFK2  
LJMP SFK3  
LJMP SFK4  
LJMP SFK5  
LJMP SFK6

SFK2:

MOV R7,#00  
CLR FLTEST  
SETB FLDO  
DJNZ R3,T2  
MOV R3,#08

T2:

JMP TEST4

SFK3:

MOV R7,#01H  
CLR FLTEST  
SETB FLDO  
SETB FLK5  
JMP TEST4  
; JMP XSTART

SFK4:

MOV R7,#02H  
CLR FLTEST  
SETB FLDO  
SETB FLINC  
JMP TEST4  
; JMP XSTART

SFK5:

MOV R7,#03H  
CLR FLTEST  
SETB FLDO  
SETB FLENT  
JMP TEST4  
; JMP XSTART

SFK0:

MOV R7,#04H  
JMP TEST4  
SJMP \$

SFK1:

MOV R7,#05H  
JMP TEST4  
SJMP \$

SFK6:

MOV R7,#06H  
JMP TEST4  
SJMP \$

```

SFK7:
      MOV     R7,#07H
      JMP     TEST4
      SJMP    $

```

```

-----
; REGISTER R3 CONTAINS THE MODE AND REGISTER R4 CONTAINS SUBMODE
; R3 IS CONTROLLED BY KEY 1 (MAXI FUNCTION OF 7)
; R4 IS CONTROLLED BY KEY 2 (MAXI FUNCTION OF 7)
-----

```

```

TINX:
      MOV     DPTR,#CNTMAIN
      MOV     B,#03H
      MOV     A,R3
      MUL    AB
      JMP     @A+DPTR

```

```

CNTMAIN:
      LJMP   RUN
      LJMP   CON7
      LJMP   CON6
      LJMP   CON5
      LJMP   CON4
      LJMP   CON3
      LJMP   CON2
      LJMP   CON1
      LJMP   RUN

```

```

RUN:
      MOV     R7,#0
      JNB    FLK5,RUN1
      CPL    FLK6

```

```

RUN1:
      CLR    FLD0
      CLR    FLK5
      JMP    X

```

```

CON1:
      MOV     R0,#CHAR2
      MOV     @R0,#S_CODE
      INC    R0
      MOV     @R0,#T_CODE
      JMP    SUBCNT

```

```

LOFUN1:
      MOV     R0,#FUN1
      MOV     A,@R0
      MOV     R4,A
      RET

```

```

SUBCNT:
      CALL   LOFUN1
      MOV     DPTR,#SUBCOOL
      MOV     B,#03H
      MOV     A,R4
      MUL    AB
      JMP     @A+DPTR

```

```

SUBCOOL:
    LJMP    SUCON6
    LJMP    SUCON5
    LJMP    SUCON4
    LJMP    SUCON3
    LJMP    SUCON2
    LJMP    SUCON1
    LJMP    SUCONO

SUCON6:
    CLR     FLDD
    JMP     X

SUCONO:
    MOV     RO,#CHAR3
    MOV     @RO,#R_CODE
    INC     RO
    MOV     @RO,#E_CODE
    INC     RO
    MOV     @RO,#Y_CODE
    MOV     DPTR,#BYEARX
    CALL    DOG
    JNB     FLINC,SUCO1
    CALL    YEAR
    CALL    DOG

SUCO1:
    JNB     FLENT,SUCO
    DJNZ    R4,SUCOX
    MOV     R4,#06

SUCOX:
    CALL    LOADY
    CALL    SAFUN1
    CLR     FLINC
    CLR     FLENT
    JMP     SUBCNT

SUCO:
    CLR     FLDD
    CLR     FLINC
    CLR     FLENT
    JMP     X

SAFUN1:
    MOV     RO,#FUN1
    MOV     A,R4
    MOV     @RO,A
    RET

LOADY:
    MOV     DPTR,#BYEARX
    MOVX    A,@DPTR
    MOV     B,A
    ANL     A,#0FH
    MOV     DPTR,#RTC+10
    MOVX    @DPTR,A
    MOV     A,B
    SWAP    A
    ANL     A,#0FH
    INC     DPTR
    MOVX    @DPTR,A
    RET

```

```

DOG:
    MOVX    A,@DPTR
    MOV     RO,#BUFFER
    MOV     @RO,A
    CALL    FILL_NUM
    RET

SUCON1:
    MOV     RO,#CHAR3
    MOV     @RO,#N_CODE
    INC     RO
    MOV     @RO,#O_CODE
    INC     RO
    MOV     @RO,#M_CODE
    MOV     DPTR,#BMONTH
    CALL    DOG
    JNB     FLINC,SUC11
    CALL    MDN
    CALL    DOG

SUC11:
    JNB     FLENT,SUC1
    DJNZ   R4,SUC1X
    MOV     R4,#06

SUC1X:
    CALL    LOADMO
    CALL    SAFUN1
    CLR     FLINC
    CLR     FLENT
    JMP     SUBCNT

SUC1:
    CLR     FLDO
    CLR     FLINC
    CLR     FLENT
    JMP     X

LOADMO:
    MOV     DPTR,#BMONTH
    MOVX   A,@DPTR
    MOV     B,A
    ANL    A,#0FH
    MOV     DPTR,#RTC+B
    MOVX   @DPTR,A
    MOV     A,B
    SWAP   A
    ANL    A,#0FH
    INC     DPTR
    MOVX   @DPTR,A
    RET

SUCON2:
    MOV     RO,#CHAR3
    MOV     @RO,#T_CODE
    INC     RO
    MOV     @RO,#A_CODE
    INC     RO
    MOV     @RO,#D_CODE
    MOV     DPTR,#BDAYX
    CALL    DOG
    JNB     FLINC,SUC21
    CALL    DAY
    CALL    DOG

```

```

SUC21:
    JNB     FLENT,SUC2
    DJNZ   R4,SUC2X
    MOV    R4,#06

SUC2X:
    CALL   LOADD
    CALL   SAFUN1
    CLR    FLINC
    CLR    FLENT
    JMP    SUBCNT

SUC2:
    CLR    FLDO
    CLR    FLINC
    CLR    FLENT
    JMP    X

LOADD:
    MOV    DPTR,#BDAYX
    MOVX   A,@DPTR
    MOV    B,A
    ANL   A,#0FH
    MOV    DPTR,#RTC+6
    MOVX   @DPTR,A
    MOV    A,B
    SWAP  A
    ANL   A,#0FH
    INC   DPTR
    MOVX   @DPTR,A
    RET

SUCON3:
    MOV    R0,#CHAR3
    MOV    @R0,#U_CODE
    INC   R0
    MOV    @R0,#O_CODE
    INC   R0
    MOV    @R0,#H_CODE
    MOV    DPTR,#BHOURS
    CALL   DOG
    JNB   FLINC,SUC31
    CALL   HOU
    CALL   DOG

SUC31:
    JNB   FLENT,SUC3
    DJNZ   R4,SUC3X
    MOV    R4,#06

SUC3X:
    CALL   LOADH
    CALL   SAFUN1
    CLR    FLINC
    CLR    FLENT
    JMP    SUBCNT

SUC3:
    CLR    FLDO
    CLR    FLINC
    CLR    FLENT
    JMP    X

```

```

LOADH:
    MOV     DPTR,#BHOURS
    MOVX   A,@DPTR
    MOV     B,A
    ANL    A,#0FH
    MOV     DPTR,#RTC+4
    MOVX   @DPTR,A
    MOV     A,B
    SWAP   A
    ANL    A,#0FH
    INC    DPTR
    MOVX   @DPTR,A
    RET

SUCON4:
    MOV     RO,#CHAR3
    MOV     @RO,#N_CODE
    INC    RO
    MOV     @RO,#I_CODE
    INC    RO
    MOV     @RO,#M_CODE
    MOV     DPTR,#BMIN5
    CALL   DOG
    JNB    FLINC,SUC41
    CALL   MIN
    CALL   DOG

SUC41:
    JNB    FLENT,SUC4
    DJNZ   R4,SUC4X
    MOV     R4,#06

SUC4X:
    CALL   LOADMI
    CALL   SAFUN1
    CLR    FLINC
    CLR    FLENT
    JMP    SUBCNT

SUC4:
    CLR    FLDO
    CLR    FLINC
    CLR    FLENT
    JMP    X

LOADMI:
    MOV     DPTR,#BMIN5
    MOVX   A,@DPTR
    MOV     B,A
    ANL    A,#0FH
    MOV     DPTR,#RTC+2
    MOVX   @DPTR,A
    MOV     A,B
    SWAP   A
    ANL    A,#0FH
    INC    DPTR
    MOVX   @DPTR,A
    RET

SUCON5:
    PUSH   5
    MOV     RO,#FUN3
    MOV     A,@RO
    MOV     R5,A

```

```

SUC5X:
    CALL    LOAD_WEEKX
    MOV     A,R5
    MOV     RO,#DISP
    MOV     DPTR,#DISPL_TBL
    MOVC   A,@A+DPTR
    MOV     @RO,A
    MOV     A,#00
    MOVC   A,@A+DPTR
    INC     RO
    MOV     @RO,A

    JNB     FLENT,SUC5X1
    CALL    LOADW
    DJNZ    R4,SUC5X4
    MOV     R4,#06

SUC5X4:
    CALL    SAFUN1
    CLR     FLENT
    CLR     FLINC
    POP     5
    JMP     SUBCNT

SUC5X1:
    JNB     FLINC,SUC5X2
    INC     R5
    CJNE   R5,#07,SUC5X3
    MOV     R5,#00

SUC5X3:
    CALL    SAFUN3
    CLR     FLENT
    CLR     FLINC
    POP     5
    JMP     SUBCNT

SUC5X2:
    CALL    SAFUN1
    CALL    SAFUN3
    CLR     FLDD
    CLR     FLENT
    CLR     FLINC
    POP     5

    JMP     X

SAFUN3:
    MOV     RO,#FUN3
    MOV     A,R5
    MOV     @RO,A
    RET

LOADW:
    MOV     A,R5
    ANL    A,#0FH
    MOV     DPTR,#RTC+12
    MOVX   @DPTR,A
    RET

LOAD_WEEKX:
    MOV     DPTR,#WEEKJMP
    MOV     A,R5
    MOV     B,#03
    MUL    AB
    JMP    @A+DPTR

```

```

FIND_CODES:
    MOV     DPTR,#DISPL_TBL
    MOVC   A,@A+DPTR
    MOV     R0,R4$
    MOV     @R0,A
    RET

MIN:
    PUSH   5
    CLR    C
    MOV    DPTR,#MINS
    MOVX   A,@DPTR
    INC    A
    MOV    B,A
    MOV    A,#59
    SUBB   A,B
    JNC    TOT
    MOV    B,#0

TOT:
    MOV    A,B
    MOVX   @DPTR,A
    MOV    R5,A
    CALL   BINTIN
    MOV    DPTR,#BMIN5
    MOV    A,R5
    MOVX   @DPTR,A
    POP    5
    RET

HOU:
    PUSH   5
    CLR    C
    MOV    DPTR,#HOURS
    MOVX   A,@DPTR
    INC    A
    MOV    B,A
    MOV    A,#23
    SUBB   A,B
    JNC    TOT1
    MOV    B,#0

TOT1:
    MOV    A,B
    MOVX   @DPTR,A
    MOV    R5,A
    CALL   BINTIN
    MOV    DPTR,#BHOURS
    MOV    A,R5
    MOVX   @DPTR,A
    POP    5
    RET

MON:
    PUSH   5
    CLR    C
    MOV    DPTR,#MONTH
    MOVX   A,@DPTR
    INC    A
    MOV    B,A
    MOV    A,#12

    SUBB   A,B
    JNC    TOT2
    MOV    B,#1

```

TOT2:

```
MOV     A,B
MOVX   @DPTR,A
MOV     R5,A
CALL   BINTIN
MOV     DPTR,#BMONTH
MOV     A,R5
MOVX   @DPTR,A
POP     5
RET
```

DAY:

```
PUSH   5
CLR    C
MOV    DPTR,#DAYX
MOVX  A,@DPTR
INC    A
MOV    B,A
MOV    A,#31
SUBB  A,B
JNC   TOT3
MOV    B,#1
```

TOT3:

```
MOV     A,B
MOVX   @DPTR,A
MOV     R5,A
CALL   BINTIN
MOV     DPTR,#BDAYX
MOV     A,R5
MOVX   @DPTR,A
POP     5
RET
```

YEAR:

```
PUSH   5
CLR    C
MOV    DPTR,#YEARX
MOVX  A,@DPTR
INC    A
MOV    B,A
MOV    A,#99
SUBB  A,B
JNC   TOT4
MOV    B,#1
```

TOT4:

```
MOV     A,B
MOVX   @DPTR,A
MOV     R5,A
CALL   BINTIN
MOV     DPTR,#BYEARX
MOV     A,R5
MOVX   @DPTR,A
POP     5

RET
```

```

DUX:
    PUSH    5
    CLR     C
    MOV     DPTR,#DURX
    MOVX    A,@DPTR
    INC     A
    MOV     B,A
    MOV     A,#59
    SUBB    A,B
    JNC     TOTS
    MOV     B,#0

TOTS:
    MOV     A,B
    MOVX    @DPTR,A
    MOV     R5,A
    CALL    BINTIN
    MOV     DPTR,#BDURX
    MOV     A,R5
    MOVX    @DPTR,A
    POP     5
    RET

BINTIN:
    PUSH    R3#
    PUSH    R4#
    MOV     R3,#0
    MOV     R4,#8H

BIN2BCD2:
    CLR     C
    MOV     A,R5
    RLC     A
    MOV     R5,A
    MOV     A,R3
    ADDC    A,R3
    DA      A
    MOV     R3,A
    DBNZ    R4,BIN2BCD2
    MOV     R5,3
    POP     R4#
    POP     R3#
    RET

FILL_NUM:
    PUSH    R3#
    PUSH    R4#
    MOV     R4,#DISP
    MOV     R3,#BUFFER
    MOV     A,#0FH
    MOV     R0,R3#
    ANL     A,@R0
    CALL    FIND_CODES
    INC     R4
    MOV     R0,R3#
    MOV     A,@R0
    SWAP    A
    ANL     A,#0FH
    CALL    FIND_CODES
    POP     R4#
    POP     R3#
    RET

```

```

;-----
; CONTROL FUNCTION TWO SETS
;-----

```

```

CON2:
    MOV     R4,#06
    CALL   SAFUN1
    MOV     DFTR,#SORT_COUNT
    MOVX   A,@DFTR
    CJNE   A,#MAX_TIME,D_FULL1
    CALL   D_FULL
    JMP     TUC3

```

```

D_FULL1:
    CALL   DISP_COUNT
    JNB    FLK5,X1X
    JMP    SOR_START

```

```

X1X:
    JMP    SUBCNT2

```

```

LOFUN2:
    MOV     R0,#FUN2
    MOV     A,@R0
    MOV     R4,A
    RET

```

```

SUBCNT2:
    CALL   DISP_COUNT
    CALL   LOFUN2
    MOV     DFTR,#SUBCOOL2
    MOV     B,#03H
    MOV     A,R4
    MUL    AB
    JMP    @A+DFTR

```

```

SUBCOOL2:
    LJMP   TUCON3
    LJMP   TUCON2
    LJMP   TUCON1
    LJMP   TUCON0

```

```

TUCON0:
    MOV     RO,#CHAR3
    MOV     @RO,#U_CODE
    INC     RO
    MOV     @RO,#O_CODE
    INC     RO
    MOV     @RO,#H_CODE
    MOV     DPTR,#BHOURS
    CALL   DOG
    JNB    FLINC,TUC31
    CALL   HOU
    CALL   DOG

```

```

TUC31:
    JNB    FLENT,TUC3
    DJNZ   R4,TUC3X
    MOV     R4,#03

```

```

TUC3X:
    CALL    SAFUN2
    CLR     FLINC
    CLR     FLENT
    JMP     SUBCNT2

TUC3:
    CLR     FLDO
    CLR     FLINC
    CLR     FLENT
    JMP     X

TUCON1:
    MOV     RO, #CHAR3
    MOV     @RO, #N_CODE
    INC     RO
    MOV     @RO, #I_CODE
    INC     RO
    MOV     @RO, #M_CODE
    MOV     DFTR, #BMIN5
    CALL    DOG
    JNB     FLINC, TUC41
    CALL    MIN
    CALL    DOG

TUC41:
    JNB     FLENT, TUC4
    DJNZ   R4, TUC4X
    MOV     R4, #03

TUC4X:
    CALL    SAFUN2
    CLR     FLINC
    CLR     FLENT
    JMP     SUBCNT2

TUC4:
    CLR     FLDO
    CLR     FLINC
    CLR     FLENT
    JMP     X

D_FULL:
    MOV     RO, #DISP
    MOV     @RO, #BLANK_CODE
    INC     RO
    MOV     @RO, #L_CODE
    INC     RO
    MOV     @RO, #U_CODE
    INC     RO
    MOV     @RO, #F_CODE
    INC     RO
    MOV     @RO, #BLANK_CODE
    RET

SAFUN2:
    MOV     RO, #FUN2
    MOV     A, R4
    MOV     @RO, A
    RET

```

```

TUCON2:
    MOV     R0,#CHAR3
    MOV     @R0,#R_CODE
    INC     R0
    MOV     @R0,#U_CODE
    INC     R0
    MOV     @R0,#D_CODE
    MOV     DPTR,#BDURX
    CALL    DOG
    JNB     FLINC,TUC31X
    CALL    DUX
    CALL    DOG

TUC31X:
    JNB     FLENT,TUC3X1
    DJNZ   R4,TUC3XX
    MOV     R4,#03

TUC3XX:
    CALL    SAFUN2
    CLR     FLINC
    CLR     FLENT
    JMP     SUBCNT2

TUC3X1:
    CLR     FLDO
    CLR     FLINC
    CLR     FLENT
    JMP     X

TUCON3:
    CLR     FLINC
    CLR     FLENT
    CLR     FLDO
    JMP     X

FILL_NUM1:
    PUSH   R3$
    PUSH   R4$
    MOV     R4,#CHAR2
    MOV     R3,#BUFFER
    MOV     A,#0FH
    MOV     R0,R3$
    ANL    A,@R0
    CALL    FIND_CODES
    INC     R4
    MOV     R0,R3$
    MOV     A,@R0
    SWAP   A
    ANL    A,#0FH
    CALL    FIND_CODES
    POP    R4$
    POP    R3$
    RET

DISP_COUNT:
    PUSH   5
    MOV     DPTR,#SORT_COUNT
    MOVX   A,@DPTR
    MOV     R5,A
    CALL    BINTIN
    MOV     R0,#BUFFER

```

```

MOV     @R0,5
CALL   FILL_NUM1
POP    5
RET

```

```

;-----
; THIS PROCEDURE SORTS THE GIVEN VALUE IMMEDIATELY AFTER KEYING IN
; R5 KEEPS TRACK OF THE COUNT OF THE VALUE
;-----

```

SOR\_START:

```

PUSH    3
PUSH    4
PUSH    5

MOV     RO,#HOU_BUFF
MOV     DPTR,#BHOURLS
MOVX    A,@DPTR
MOV     @RO,A
INC     RO
MOV     DPTR,#BMIN5
MOVX    A,@DPTR
MOV     @RO,A
INC     RO
MOV     DPTR,#BDURX
MOVX    A,@DPTR
MOV     @RO,A

MOV     DPTR,#SORT_COUNT
MOVX    A,@DPTR
MOV     R5,A

CJNE   R5,#0,CONTINUE
CALL   HOU_CHK
MOV     DPTR,#ST_TIME_BUFF
MOVX    A,@DPTR,A
CALL   MIN_CHK
INC     DPTR
MOVX    A,@DPTR,A
INC     DPTR
CALL   DURATION
MOVX    A,@DPTR,A
CALL   PUT_COUNT
POP     5
POP     4
POP     3
JMP    XX

```

PUT\_COUNT:

```

MOV     DPTR,#SORT_COUNT
MOVX    A,@DPTR
INC     A
MOVX    A,@DPTR,A
RET

```

HOU\_CHK:

```

MOV     RO,#HOU_BUFF
MOV     A,@RO
RET

```

```

MIN_CHK:
    MOV     RO,#MIN_BUFF
    MOV     A,@RO
    RET

DURATION:
    MOV     RO,#DU_BUFF
    MOV     A,@RO
    RET

CONTINUE:
    JMP     CHK_EQU
CONTINUE2:
    CLR     C
    DJNZ   R5,HITLER
    SETB   FLLER
HITLER:
    CALL   HOU_CHK
    MOV    R3,A
    CALL   ADDR_CHK_HOU
    MOV    B,A
    SUBB  A,R3
    JC    MINUTES1
    MOV    A,B
    CJNE  A,R3#,CONTINUE1

    CALL   ADDR_CHK_MIN
    MOV    R4,A
    CALL   MIN_CHK
    CJNE  A,R4#,MINUTES
    POP    5
    POP    4
    POP    3

    JMP    XX

MINUTES1:
    INC    R5
    CALL   ADDR_CALC
    CALL   HOU_CHK
    MOVX   @DPTR,A
    INC    DPTR
    CALL   MIN_CHK
    MOVX   @DPTR,A
    INC    DPTR
    CALL   DURATION
    MOVX   @DPTR,A
    CALL   PUT_COUNT
    CLR    FLLER
    POP    5
    POP    4
    POP    3

    JMP    XX

MINUTES2:
    CALL   ADDR_CALC
    CALL   HOU_CHK
    MOVX   @DPTR,A
    INC    DPTR

```

P 207

```

        CALL    MIN_CHK
        MOVX   @DPTR,A
        INC   DPTR
        CALL  DURATION
        MOVX  @DPTR,A
        CALL  PUT_COUNT
        CLR   FLLER
        RET

CONTINUE1:
        CALL  EXCHANGE
        JNB   FLLER,HITLER1
        CALL  MINUTES2
HITLER1:
        INC   R5
        DJNZ  R5,CONTINUE2
        POP   5
        POP   4
        POP   3

        JMP   XX

MINUTES:
        CLR   C
        CALL  MIN_CHK
        MOV   R4,A
        CALL  ADDR_CHK_MIN
        SUBB  A,R4
        JC   MINUTES1
        CALL  EXCHANGE
        JNB   FLLER,HITLER2
        CALL  MINUTES2
HITLER2:
        INC   R5
        DJNZ  R5,HITLER3
        POP   5
        POP   4
        POP   3

        JMP   XX

HITLER3:
        JMP   CONTINUE2

ADDR_CHK_HOU:
        CALL  ADDR_CALC
        MOVX  A,@DPTR
        RET
ADDR_CHK_MIN:
        CALL  ADDR_CALC
        INC   DPTR
        MOVX  A,@DPTR
        RET
ADDR_CHK_DUR:
        CALL  ADDR_CALC
        INC   DPTR
        INC   DPTR
        MOVX  A,@DPTR
        RET

```

EXCHANGE:

```

MOV     R0,#TEMP_HOU
CALL   ADDR_CHK_HOU
MOV     @R0,A
INC     R0
CALL   ADDR_CHK_MIN
MOV     @R0,A
INC     R0
CALL   ADDR_CHK_DUR
MOV     @R0,A
INC     R5
CALL   ADDR_CALC
MOV     R0,#TEMP_HOU
MOV     A,@R0
MOVX   @DPTR,A
INC     R0
INC     DPTR
MOV     A,@R0
MOVX   @DPTR,A
INC     R0
INC     DPTR
MOV     A,@R0
MOVX   @DPTR,A
DEC     R5
RET

```

ADDR\_CALC:

```

CLR     C
MOV     DPTR,#ST_TIME_BUFF
MOV     B,#03
MOV     A,R5
MUL    AB
ADD     A,DPL
JC      ADDR_CALC1
MOV     DPL,A
RET

```

ADDR\_CALC1:

```

MOV     DPL,A
INC     DPH
RET

```

CHK\_EQU:

```

CALL   HOU_CHK
MOV     R3,A
CALL   MIN_CHK
MOV     R4,A

```

CHK\_EQU1:

```

DEC     R5
CALL   ADDR_CHK_HOU
CJNE   A,R3#,ZORROR
CALL   ADDR_CHK_MIN
CJNE   A,R4#,ZORROR
POP     5
POP     4
POP     3
JMP    XX

```

ZORROR:

```
INC      R5
DJNZ    R5,CHK_EQU1
MOV     DPTR,#SORT_COUNT
MOVX    A,@DPTR
MOV     R5,A
JMP     CONTINUE2
```

XX:

```
CLR     FL00
CLR     FLK5
CALL    DISP_COUNT

JMP     X
```

```
-----
;PROCEDURE TO DELETE THE VALUES IN THE BUFFER
;-----
```

CON3:

```
MOV     R4,#03
CALL    SAFUN2
CALL    L_SORT_C_A

PUSH    5
PUSH    6

MOV     DPTR,#SORT_COUNT
MOVX    A,@DPTR
CJNE   A,#00,STARX
CALL    FILL_ZERO
JMP     XTR2
```

STARX:

```
MOV     DPTR,#SORT_COUNT1
MOVX    A,@DPTR
MOV     R5,A
INC     A
MOV     R6,A
JZ      VINMGA
```

VINMGA:

```
JNB     FLK5,VINMGA1

MOV     DPTR,#DEL_DATA
INC     R5
MOV     A,R5
MOVX    @DPTR,A
DEC     R5
CALL    START_DEL
CALL    LOAD_SORT_COUNT2
MOV     DPTR,#SORT_COUNT1
MOVX    A,@DPTR
MOV     R5,A
MOV     DPTR,#SORT_COUNT
MOVX    A,@DPTR
JZ      VINMGA11
```

VINMGA1:

```
CALL ADDR_CALC
MOVX A,@DPTR
MOV RO,#BUFFER
INC R5
MOV @RO,A
DEC R5
CALL FILL_NUM1
CALL ADDR_CALC
INC DPTR
MOVX A,@DPTR
MOV RO,#BUFFER
MOV @RO,A
CALL FILL_NUM
CALL ADDR_CALC
INC DPTR
INC DPTR
MOVX A,@DPTR
MOV RO,#BUFFER
MOV @RO,A
CALL FILL_NUM2
MOV RO,#CHAR4
MOV @RO,#D_CODE
```

```
JNB FLENT,XTR2
```

```
DEC R6
CJNE R6,#00,XTR3
CALL LOAD_SORT_COUNT1
JMP XTR2
```

XTR3:

```
DEC R5
MOV A,R5
MOV DPTR,#SORT_COUNT1
MOVX @DPTR,A
```

XTR2:

```
CLR FLDO
CLR FLENT
CLR FLK5
```

```
POP 6
POP 5
```

```
JMP X
```

VINMGA11:

```
CALL FILL_ZERO
JMP XTR2
```

LOAD\_SORT\_COUNT2:

```
MOV DPTR,#SORT_COUNT
MOVX A,@DPTR
CJNE A,#01,DEE1
JMP LOAD_SORT_COUNT1
```

```

DEE1:
    MOVX    A,@DPTR
    JZ      DEE
    DEC     A
    DEC     A

DEE:
    INC     DPTR
    MOVX    @DPTR,A
    RET

LOAD_SORT_COUNT1:
    MOV     DPTR,#SORT_COUNT
    MOVX    A,@DPTR
    JZ      LSC1
    DEC     A

LSC1:
    INC     DPTR
    MOVX    @DPTR,A
    RET

FILL_NUM2:
    PUSH    R3#
    PUSH    R4#
    MOV     R4,#CHAR3
    MOV     R3,#BUFFER
    MOV     A,#OFH
    MOV     R0,R3#
    ANL     A,@R0
    CALL    FIND_CODES
    INC     R4
    MOV     R0,R3#
    MOV     A,@R0
    SWAP    A
    ANL     A,#OFH
    CALL    FIND_CODES
    POP     R4#
    POP     R3#
    RET

FILL_ZERO:
    MOV     R0,#DISP
    MOV     @R0,#Y_CODE
    INC     R0
    MOV     @R0,#T_CODE
    INC     R0
    MOV     @R0,#P_CODE
    INC     R0
    MOV     @R0,#M_CODE
    INC     R0
    MOV     @R0,#E_CODE
    INC     R0
    MOV     @R0,#BLANK_CODE
    INC     R0
    MOV     @R0,#BLANK_CODE
    INC     R0
    MOV     @R0,#BLANK_CODE
    INC     R0
    MOV     @R0,#BLANK_CODE
    RET

```

```

:-----:
: THIS PROCEDURE REMOVES THE POINTED DATA FROM THE BUFFER AND
: REORDERS THE BUFFER. THE COUNT OF DATA POINTED SHOULD BE PASSED
: THROUGH THE PROCEDURE REGISTER R5
:-----:

```

```

START_DEL:
    PUSH    5
    MOV     DPTR,#DEL_DATA
    MOVX   A,@DPTR
    MOV     R5,A
    MOV     DPTR,#SORT_COUNT
    MOVX   A,@DPTR
    CJNE   A,R5#,STAR
    MOV     R5,#00

```

```

STAR2:
    CALL    LOAD_BUFF_DEL
    CALL    DIVE_BUFF_DEL
    INC     R5
    MOV     DPTR,#SORT_COUNT
    MOVX   A,@DPTR
    CJNE   A,R5#,STAR2
    JMP     STAR1

```

```

STAR:
    CALL    LOAD_BUFF_DEL
    CALL    DIVE_BUFF_DEL
    INC     R5
    MOV     DPTR,#SORT_COUNT
    MOVX   A,@DPTR
    CJNE   A,R5#,STAR

```

```

STAR1:
    CALL    DEC_COUNT
    POP     5
    RET

```

```

DEC_COUNT:
    MOV     DPTR,#SORT_COUNT
    MOVX   A,@DPTR
    JZ     DC1
    DEC     A

```

```

DC1:
    MOVX   @DPTR,A
    RET

```

```

LOAD_BUFF_DEL:
    INC     R5
    MOV     R0,#HOU_BUFF
    CALL    ADDR_CHK_HOU
    MOV     @R0,A
    INC     R0
    CALL    ADDR_CHK_MIN
    MOV     @R0,A
    INC     R0
    CALL    ADDR_CHK_DUR
    MOV     @R0,A
    RET

```

```

DIVE_BUFF_DEL:
    DEC     R5
    CALL   ADDR_CALC
    MOV     R0,#HOU_BUFF
    MOV     A,@R0
    MOVX   @DPTR,A
    INC     R0
    INC     DPTR
    MOV     A,@R0
    MOVX   @DPTR,A
    INC     R0
    INC     DPTR
    MOV     A,@R0
    MOVX   @DPTR,A
    RET

```

```

;-----
; CONTROL FUNCTION FOUR SETS
;-----

```

```

CON4:
    CALL   L_SORT_C_A
    MOV     DPTR,#SORT_COUNTX
    MOVX   A,@DPTR
    CJNE   A,#MAX_MON,D_FULL2
    CALL   D_FULL
    JMP     SUC1Z

```

```

D_FULL2:
    CALL   DISP_COUNTX
    JNB    FLK5,X1XX
    JMP     SOR_STARTZ

```

```

X1XX:
    JMP     SUBCNT3

```

```

LOFUN4:
    MOV     R0,#FUN4
    MOV     A,@R0
    MOV     R4,A
    RET

```

```

SUBCNT3:
    CALL   LOFUN4
    MOV     DPTR,#SUBCOOL3
    MOV     B,#03H
    MOV     A,R4
    MUL    AB
    JMP     @A+DPTR

```

```

SUBCOOL3:
    LJMP   TUCONX2
    LJMP   TUCONX1
    LJMP   TUCONX0

```

```

TUCONX2:
    CLR    FLDO
    JMP    X

```

```

SAFUN4:
    MOV     RO,#FUN4
    MOV     A,R4
    MOV     @RO,A
    RET

TUCONX0:
    MOV     RO,#CHAR3
    MOV     @RO,#N_CODE
    INC     RO
    MOV     @RO,#O_CODE
    INC     RO
    MOV     @RO,#M_CODE
    MOV     DPTR,#BMONTH
    CALL    DOG
    JNB     FLINC,SUC11XZ
    CALL    MON
    CALL    DOG

SUC11XZ:
    JNB     FLENT,SUC1Z
    DJNZ    R4,SUC1XZ
    MOV     R4,#02

SUC1XZ:
    CALL    SAFUN4
    CLR     FLINC
    CLR     FLENT
    JMP     SUBCNT3

SUC1Z:
    CLR     FLDO
    CLR     FLINC
    CLR     FLENT
    JMP     X

TUCONX1:
    MOV     RO,#CHAR3
    MOV     @RO,#T_CODE
    INC     RO
    MOV     @RO,#A_CODE
    INC     RO
    MOV     @RO,#D_CODE
    MOV     DPTR,#BDAYX
    CALL    DOG
    JNB     FLINC,SUC21XZ
    CALL    DAY
    CALL    DOG

SUC21XZ:
    JNB     FLENT,SUC2Z
    DJNZ    R4,SUC2XZ
    MOV     R4,#02

SUC2XZ:
    CALL    SAFUN4
    CLR     FLINC
    CLR     FLENT
    JMP     SUBCNT3

SUC2Z:
    CLR     FLDO
    CLR     FLINC
    CLR     FLENT
    JMP     X

```

```

DISP_COUNTX:
    PUSH    5
    MOV     DPTR,#SORT_COUNTX
    MOVX   A,@DPTR
    MOV     R5,A
    CALL   BINTIN
    MOV     RO,#BUFFER
    MOV     @RO,5
    CALL   FILL_NUM1
    POP     5
    RET

```

```

;-----
;PROCEDURE TO SORT
;-----

```

```

SOR_STARTZ:
    PUSH    3
    PUSH    4
    PUSH    5

    MOV     RO,#HOU_BUFFX
    MOV     DPTR,#BMONTH
    MOVX   A,@DPTR
    MOV     @RO,A
    INC     RO
    MOV     DPTR,#BDAYX
    MOVX   A,@DPTR
    MOV     @RO,A

    MOV     DPTR,#SORT_COUNTX ;previously sorted value
    MOVX   A,@DPTR           ;(count) is loaded into register r5
    MOV     R5,A

    CJNE   R5,#0,CONTINUEY ;check count for 0 if so write
    CALL   HOU_CHKY         ;the value to the buffer
    MOV     DPTR,#ST_TIME_BUFFX
    MOVX   @DPTR,A
    CALL   MIN_CHKY
    INC     DPTR
    MOVX   @DPTR,A
;
;
;
    CALL   DURATION
    MOVX   @DPTR,A
    CALL   PUT_COUNTY      ;put the inc count value in
    POP     5              ;the storage space
    POP     4
    POP     3
    JMP     XZ

```

```

PUT_COUNTY:
    MOV     DPTR,#SORT_COUNTX
    MOVX   A,@DPTR
    INC     A
    MOVX   @DPTR,A
    RET

```

```

HOU_CHKY:
    MOV     RO,#HOU_BUFFX
    MOV     A,@RO
    RET

```

```

MIN_CHKY:
    MOV     R0,#MIN_BUFFX
    MOV     A,@R0
    RET

; DURATION:
;     MOV     R0,#DU_BUFF
;     MOV     A,@R0
;     RET

CONTINUEY:
    JMP     CHK_EQUY      ;check in the buffer,for equal value

CONTINUEY2:
                                ;if found so discard it
    CLR     C
    DJNZ   R5,HITLERY
    SETB   FLLERX

HITLERY:
                                ;check for equality of hour (month) part
    CALL   HOU_CHKY
    MOV    R3,A
    CALL   ADDR_CHK_HOUY
    MOV    B,A
    SUBB  A,R3
    JC    MINUTESY1      ;if the carry occurs place the data
    MOV    A,B            ;in that place
    CJNE  A,R3#,CONTINUEY1
                                ;if they are equal sort min (day)
    CALL   ADDR_CHK_MINY
    MOV    R4,A
    CALL   MIN_CHKY
    CJNE  A,R4#,MINUTESY
    POP   5
    POP   4
    POP   3

    JMP    XZ

MINUTESY1:
    INC    R5
    CALL   ADDR_CALCY
    CALL   HOU_CHKY
    MOVX   @DPTR,A
    INC    DPTR
    CALL   MIN_CHKY
    MOVX   @DPTR,A
;
;
;
    INC    DPTR
    CALL   DURATION
    MOVX   @DPTR,A
    CALL   PUT_COUNTY
    CLR    FLLERX
    POP   5
    POP   4
    POP   3

    JMP    XZ

```

## MINUTESY2:

```

CALL ADDR_CALCY
CALL HOU_CHKY
MOVX @DPTR,A

INC DPTR
CALL MIN_CHKY
MOVX @DPTR,A
: INC DPTR
: CALL DURATION
: MOVX @DPTR,A
CALL PUT_COUNTY
CLR FLLERX
RET

```

## CONTINUEY1:

```

CALL EXCHANGEZ
JNB FLLERX,HITLERY1
CALL MINUTESY2

```

## HITLERY1:

```

INC R5
DJNZ R5,CONTINUEY2
POP 5
POP 4
POP 3

JMP XZ

```

## MINUTESY:

```

CLR C
CALL MIN_CHKY
MOV R4,A
CALL ADDR_CHK_MINY
SUBB A,R4
JC MINUTESY1
CALL EXCHANGEZ
JNB FLLERX,HITLERY2
CALL MINUTESY2

```

## HITLERY2:

```

INC R5
DJNZ R5,HITLERY3
POP 5
POP 4
POP 3

JMP XZ

```

## HITLERY3:

```

JMP CONTINUEY2

```

## ADDR\_CHK\_HOUY:

```

CALL ADDR_CALCY
MOVX A,@DPTR
RET

```

## ADDR\_CHK\_MINY:

```

CALL ADDR_CALCY
INC DPTR
MOVX A,@DPTR
RET

```

```

: ADDR_CHK_DUR:
:     CALL    ADDR_CALCY
:     INC     DPTR
:     INC     DPTR
:     MOVX    A,@DPTR
:     RET
EXCHANGEZ:
    MOV     RO,#TEMP_HOUX
    CALL    ADDR_CHK_HOUY
    MOV     @RO,A
    INC     RO
    CALL    ADDR_CHK_MINY
    MOV     @RO,A
:
:     INC     RO
:     CALL    ADDR_CHK_DUR
:     MOV     @RO,A
:     INC     R5
    CALL    ADDR_CALCY
    MOV     RO,#TEMP_HOUX
    MOV     A,@RO
    MOVX    @DPTR,A
    INC     RO
    INC     DPTR
    MOV     A,@RO
    MOVX    @DPTR,A
:
:     INC     RO
:     INC     DPTR
:     MOV     A,@RO
:     MOVX    @DPTR,A
    DEC     R5
    RET
ADDR_CALCY:
    CLR     C
    MOV     DPTR,#ST_TIME_BUFFX
    MOV     B,#02
    MOV     A,R5
    MUL     AB
    ADD     A,DPL
    JC     ADDR_CALCY1
    MOV     DPL,A
    RET
ADDR_CALCY1:
    MOV     DPL,A
    INC     DPH
    RET
CHK_EQUY:
    CALL    HOU_CHKY
    MOV     R3,A
    CALL    MIN_CHKY
    MOV     R4,A
CHK_EQUY1:
    DEC     R5
    CALL    ADDR_CHK_HOUY
    CJNE    A,R3#,ZORRORZ
    CALL    ADDR_CHK_MINY
    CJNE    A,R4#,ZORRORZ
    POP     5
    POP     4
    POP     3
    JMP     XZ

```

```
ZORRORZ:
    INC     R5
    DJNZ   R5,CHK_EQUY1
    MOV    DPTR,#SORT_COUNTX
    MOVX   A,@DPTR
    MOV    R5,A
    JMP    CONTINUEY2
```

```
XZ:
    CLR    FLDD
    CLR    FLK5
    CALL  DISP_COUNTX

    JMP    X
```

```
-----
;PROCEDURE DELETES TWO BYTES BUFFER
;-----
```

```
CONS:
    PUSH   5
    PUSH   6

    MOV    DPTR,#SORT_COUNTX
    MOVX   A,@DPTR
    CJNE  A,#00,STARXX
    CALL  FILL_ZERO
    JMP    XTR2X
```

```
STARXX:
    MOV    DPTR,#SORT_COUNTX1
    MOVX   A,@DPTR
    MOV    R5,A
    INC    A
    MOV    R6,A
    JZ     VINMGAX
```

```
VINMGAX:
    JNB   FLK5,VINMGA1X

    MOV    DPTR,#DEL_DATAX
    INC    R5
    MOV    A,R5
    MOVX   @DPTR,A
    DEC    R5
    CALL  START_DELX
    CALL  LOAD_SORT_COUNTX2
    MOV    DPTR,#SORT_COUNTX1
    MOVX   A,@DPTR
    MOV    R5,A
    MOV    DPTR,#SORT_COUNTX
    MOVX   A,@DPTR
    JZ     VINMGA11X
```

```
VINMGA1X:
    CALL  ADDR_CALCY
    MOVX   A,@DPTR
    MOV    R0,#BUFFER
    INC    R5
    MOV    @R0,A
    DEC    R5
    CALL  FILL_NUM1
    CALL  ADDR_CALCY
```

```

        INC     DPTR
        MOVX   A,@DPTR
        MOV    RO,#BUFFER
        MOV    @RO,A
        CALL   FILL_NUM
        MOV    RO,#CHAR3
        MOV    @RO,#L_CODE
        INC    RO
        MOV    @RO,#E_CODE
        INC    RO
        MOV    @RO,#D_CODE

        JNB    FLENT,XTR2X

        DEC    R6
        CJNE   R6,#00,XTR3X
        CALL   LOAD_SORT_COUNTX1
        JMP    XTR2

XTR3X:  DEC    R5
        MOV    A,R5
        MOV    DPTR,#SORT_COUNTX1
        MOVX   @DPTR,A

XTR2X:  CLR    FLDD
        CLR    FLENT
        CLR    FLK5

        POP    6
        POP    5

        JMP    X

VINMGA11X:
        CALL   FILL_ZERO
        JMP    XTR2X

LOAD_SORT_COUNTX2:
        MOV    DPTR,#SORT_COUNTX
        MOVX   A,@DPTR
        CJNE   A,#01,DEE1X
        JMP    LOAD_SORT_COUNTX1

DEE1X:  MOVX   A,@DPTR
        JZ     DEEX
        DEC    A
        DEC    A

DEEX:   INC    DPTR
        MOVX   @DPTR,A
        RET

LOAD_SORT_COUNTX1:
        MOV    DPTR,#SORT_COUNTX
        MOVX   A,@DPTR
        JZ     LSC1X
        DEC    A

```

```

LSC1X:      INC      DPTR
            MOVX    @DPTR,A
            RET

```

```

;-----
; THIS PROCEDURE REMOVES THE POINTED DATA FROM THE BUFFER AND
; REORDERS THE BUFFER. THE COUNT OF DATA POINTED SHOULD BE PASSED
; THROUGH THE PROCEDURE REGISTER R5
;-----

```

```

START_DELX:
            PUSH    5
            MOV     DPTR,#DEL_DATAX
            MOVX   A,@DPTR
            MOV     R5,A
            MOV     DPTR,#SORT_COUNTX
            MOVX   A,@DPTR
            CJNE  A,R5#,STARX11
            MOV     R5,#00

```

```

STARX2:
            CALL   LOAD_BUFF_DELX
            CALL   DIVE_BUFF_DELX
            INC    R5
            MOV     DPTR,#SORT_COUNTX
            MOVX   A,@DPTR
            CJNE  A,R5#,STARX2
            JMP    STARX1

```

```

STARX11:
            CALL   LOAD_BUFF_DELX
            CALL   DIVE_BUFF_DELX
            INC    R5
            MOV     DPTR,#SORT_COUNTX
            MOVX   A,@DPTR
            CJNE  A,R5#,STARX11

```

```

STARX1:
            CALL   DEC_COUNTX
            POP    5
            RET

```

```

DEC_COUNTX:
            MOV     DPTR,#SORT_COUNTX
            MOVX   A,@DPTR
            JZ     DC1X
            DEC    A

```

```

DC1X:
            MOVX   @DPTR,A
            RET

```

```

LOAD_BUFF_DELX:
            INC    R5
            MOV     RO,#HOU_BUFFX
            CALL   ADDR_CHK_HOU
            MOV     @RO,A
            INC    RO
            CALL   ADDR_CHK_MIN
            MOV     @RO,A
            RET

```

DIVE\_BUFF\_DELX:

```
DEC     R5
CALL    ADDR_CALCY
MOV     RO,#HOU_BUFFX
MOV     A,@RO
MOVX    @DPTR,A
INC     RO
INC     DPTR
MOV     A,@RO
MOVX    @DPTR,A
RET
```

```
-----
; PROCEDURE CLEARS THE BUFFER
; PROGRAM ASKS FOR THE PASS-WORD & IF FOUND EQUAL CLEARS THE RAM
; -----
```

CON6:

```
MOV     DPTR,#SORT_COUNT
MOVX    A,@DPTR
CJNE    A,#00,ONE
MOV     DPTR,#SORT_COUNTX
MOVX    A,@DPTR
CJNE    A,#00,ONE
CALL    CC1
CLR     FLDO
CLR     FLENT
CLR     FLINC

JMP     X
```

ONE:

```
MOV     RO,#CHAR2
MOV     @RO,#BLANK_CODE
INC     RO
MOV     @RO,#S_CODE
INC     RO
MOV     @RO,#S_CODE
INC     RO
MOV     @RO,#A_CODE
INC     RO
MOV     @RO,#F_CODE
MOV     DPTR,#BYEARX
CALL    DOG
JNB     FLINC,SUC01Z
CALL    YEAR
CALL    DOG
```

SUC01Z:

```
JNB     FLENT,SUC0Z
CALL    CLEAR_CODE
```

SUC0Z:

```
CLR     FLDO
CLR     FLINC
CLR     FLENT
JMP     X
```

CLEAR\_CODE:

```
MOV     DPTR,#BYEARX
MOVX    A,@DPTR
CJNE    A,#99H,CC2
JMP     CC1
```

```

CC2:      MOV     RO,#CHAR2
          MOV     @RO,#BLANK_CODE
          INC     RO
          MOV     @RO,#BLANK_CODE
          MOV     RO,#CHAR3
          MOV     @RO,#R_CODE
          INC     RO
          MOV     @RO,#R_CODE
          INC     RO
          MOV     @RO,#E_CODE
          RET

```

```

CC1:      MOV     RO,#DISP
          MOV     @RO,#BLANK_CODE
          INC     RO
          MOV     @RO,#BLANK_CODE
          MOV     RO,#CHAR2
          MOV     @RO,#R_CODE
          INC     RO
          MOV     @RO,#A_CODE
          INC     RO
          MOV     @RO,#E_CODE
          INC     RO
          MOV     @RO,#L_CODE
          INC     RO
          MOV     @RO,#C_CODE
          MOV     DPTR,#SORT_COUNT
          MOV     A,#00
          MOVX   @DPTR,A
          MOV     DPTR,#SORT_COUNTX
          MOVX   @DPTR,A
          MOV     DPTR,#STORE_WEEK
          MOVX   @DPTR,A
          RET

```

```

;-----
;PROCEDURE KNOCKS OFF THE DAY
;-----

```

```

CON7:     PUSH    5
          CALL   LOAD_WE

```

```

CON7X:    CALL   LOAD_FUN5

          JNB   FLENT,FOLLOW
          SETB  FLWDS

```

```

FOLLOW:   CALL   WE_DA_SET

          JNB   FLINC,FOL1
          INC   R5
          CJNE R5,#07,FOL2
          MOV   R5,#00

```

```

FOL2:
    CALL    SAVE_FUN5
    CLR     FLENT
    CLR     FLINC
    JMP     CON7X

FOL1:
    CLR     FLENT
    CLR     FLINC
    CLR     FLDD
    CALL    SAVE_WE
    POP     5

    JMP     X

LOAD_WE:
    MOV     DPTR,#STORE_WEEK
    MOVX    A,@DPTR
    MOV     RO,#FLSET_WE_DAY
    MOV     @RO,A
    RET

SAVE_WE:
    MOV     DPTR,#STORE_WEEK
    MOV     RO,#FLSET_WE_DAY
    MOV     A,@RO
    MOVX    @DPTR,A
    RET

LOAD_FUN5:
    MOV     RO,#FUN5
    MOV     A,@RO
    MOV     R5,A
    RET

SAVE_FUN5:
    MOV     RO,#FUN5
    MOV     A,R5
    MOV     @RO,A
    RET

WE_DA_SET:
    MOV     DPTR,#WEEKJMPX
    MOV     A,R5
    MOV     B,#03
    MUL    AB
    JMP     @A+DPTR

WEEKJMPX:
    LJMP   WEEK0X
    LJMP   WEEK1X
    LJMP   WEEK2X
    LJMP   WEEK3X
    LJMP   WEEK4X
    LJMP   WEEK5X
    LJMP   WEEK6X

```

```

WEEKOX:
    MOV     RO,#CHAR3
    MOV     @RO,#N_CODE
    INC     RO
    MOV     @RO,#U_CODE
    INC     RO
    MOV     @RO,#S_CODE

    JNB     FLWDS,WX01
    CPL

```

```

WX01:
    JNB     29H.0,WX0
    CALL    SET_DAY
    CLR     FLWDS
    RET

```

```

WX0:
    CALL    RESET_DAY
    CLR     FLWDS
    RET

```

```

WEEK1X:
    MOV     RO,#CHAR3
    MOV     @RO,#N_CODE
    INC     RO
    MOV     @RO,#O_CODE
    INC     RO
    MOV     @RO,#M_CODE

    JNB     FLWDS,WX11
    CPL

```

```

WX11:
    JNB     29H.1,WX1
    CALL    SET_DAY
    CLR     FLWDS
    RET

```

```

WX1:
    CALL    RESET_DAY
    CLR     FLWDS
    RET

```

```

WEEK2X:
    MOV     RO,#CHAR3
    MOV     @RO,#E_CODE
    INC     RO
    MOV     @RO,#U_CODE
    INC     RO
    MOV     @RO,#T_CODE

    JNB     FLWDS,WX21
    CPL

```

```

WX21:
    JNB     29H.2,WX2
    CALL    SET_DAY
    CLR     FLWDS
    RET

```

```

WX2:
    CALL    RESET_DAY
    CLR
    RET

WEEK3X:
    MOV     RO,#CHAR3
    MOV     @RO,#D_CODE
    INC     RO
    MOV     @RO,#E_CODE
    INC     RO
    MOV     @RO,#W_CODE

    JNB     FLWDS,WX31
    CPL
    29H.3

WX31:
    JNB     29H.3,WX3
    CALL    SET_DAY
    CLR
    RET

WX3:
    CALL    RESET_DAY
    CLR
    RET

WEEK4X:
    MOV     RO,#CHAR3
    MOV     @RO,#R_CODE
    INC     RO
    MOV     @RO,#H_CODE
    INC     RO
    MOV     @RO,#T_CODE

    JNB     FLWDS,WX41
    CPL
    29H.4

WX41:
    JNB     29H.4,WX4
    CALL    SET_DAY
    CLR
    RET

WX4:
    CALL    RESET_DAY
    CLR
    RET

WEEK5X:
    MOV     RO,#CHAR3
    MOV     @RO,#I_CODE
    INC     RO
    MOV     @RO,#R_CODE
    INC     RO
    MOV     @RO,#F_CODE

    JNB     FLWDS,WX51
    CPL
    29H.5

```

```

WX51:
    JNB     29H.5,WX5
    CALL   SET_DAY
    CLR    FLWDS
    RET

WX5:
    CALL   RESET_DAY
    CLR    FLWDS
    RET

WEEK6X:
    MOV    RO,#CHAR3
    MOV    @RO,#T_CODE
    INC    RO
    MOV    @RO,#A_CODE
    INC    RO
    MOV    @RO,#S_CODE

    JNB    FLWDS,WX61
    CPL    29H.6

WX61:
    JNB    29H.6,WX6
    CALL   SET_DAY
    CLR    FLWDS
    RET

WX6:
    CALL   RESET_DAY
    CLR    FLWDS
    RET

SET_DAY:
    MOV    RO,#DISP
    MOV    @RO,#N_CODE
    INC    RO
    MOV    @RO,#O_CODE
    INC    RO
    MOV    @RO,#BLANK_CODE
    INC    RO
    MOV    @RO,#BLANK_CODE
    RET

RESET_DAY:
    MOV    RO,#DISP
    MOV    @RO,#F_CODE
    INC    RO
    MOV    @RO,#F_CODE
    INC    RO
    MOV    @RO,#O_CODE
    INC    RO
    MOV    @RO,#BLANK_CODE
    RET

DISPL_TBL:
;**** NUMERIC DISPLAY CODES ****
;****   h g f e d c b a   ****
    DB    03FH    ;0
    DB    006H    ;1
    DB    05BH    ;2

```

```

DB      04FH      ; 3
DB      066H      ; 4
DB      06DH      ; 5
DB      07DH      ; 6
DB      007H      ; 7
DB      07FH      ; 8
DB      06FH      ; 9
DB      077H      ; A
DB      07CH      ; B
DB      039H      ; C
DB      05EH      ; D
DB      079H      ; E
DB      071H      ; F

```

```

; ** ALPHABET DISPLAY CODES **

```

```

ZERO_CODE      EQU      03FH
EQUAL_CODE     EQU      048H
ONE_CODE       EQU      006H
TWO_CODE       EQU      05BH
THREE_CODE     EQU      04FH
SIX_CODE       EQU      07DH
A_CODE         EQU      077H
B_CODE         EQU      07CH
C_CODE         EQU      039H
C1_CODE        EQU      058H
D_CODE         EQU      05EH
E_CODE         EQU      079H
F_CODE         EQU      071H
G_CODE         EQU      03DH
H_CODE         EQU      076H
I_CODE         EQU      030H
J_CODE         EQU      00EH
K_CODE         EQU      070H
L_CODE         EQU      038H
M_CODE         EQU      055H
N_CODE         EQU      054H
O_CODE         EQU      05CH
P_CODE         EQU      073H
R_CODE         EQU      050H
S_CODE         EQU      06DH
T_CODE         EQU      078H
U_CODE         EQU      01CH
W_CODE         EQU      01DH
Y_CODE         EQU      06EH
Z_CODE         EQU      05BH
BLANK_CODE     EQU      000H
DASH_CODE      EQU      040H
DASH1_CODE     EQU      008H
STAR_CODE      EQU      07BH

```

```

END

```

*Conclusion...*



## CHAPTER VII

### CONCLUSION

In this project a programmable timer has been designed, fabricated and tested successfully. A microcontroller has been used for controlling the programmable timer.

The software developed enables the unit to operate in the following 8 modes.

1. Time setting mode
2. Alarm setting mode
3. Alarm deleting mode
4. Holiday setting mode
5. Holiday deleting mode
6. Reset mode
7. Day setting mode
8. Display mode

The special feature of the project is that only **4 keys** are used for all operations.

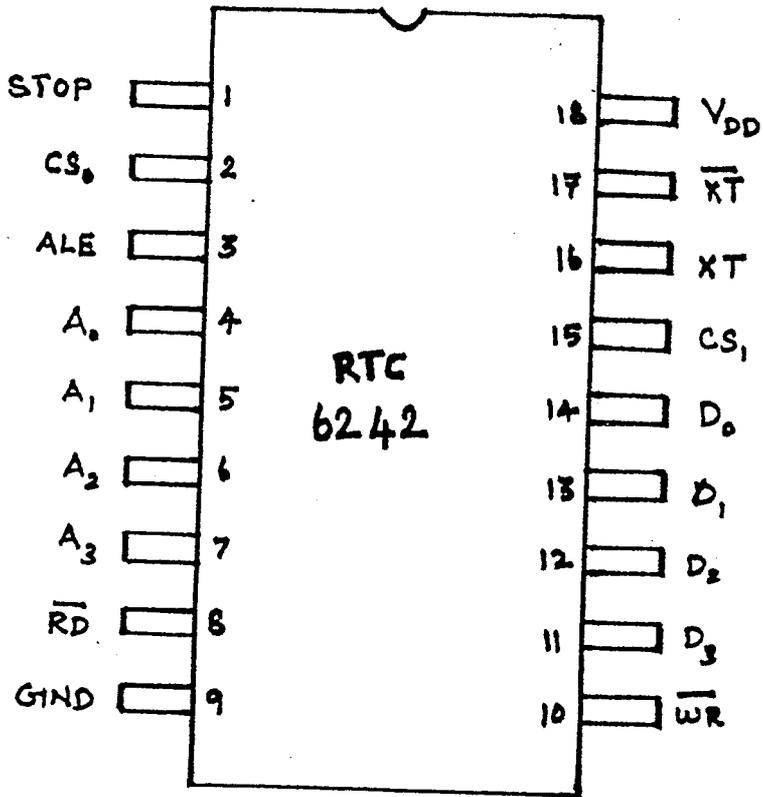
In view of the multiple facilities offered by the timer it has a lot of applications in industries where time controlled operations are performed. Using this timer control can be done automatically.

It can be used effectively to ring bell at the end of the period in educational institutions automatically.

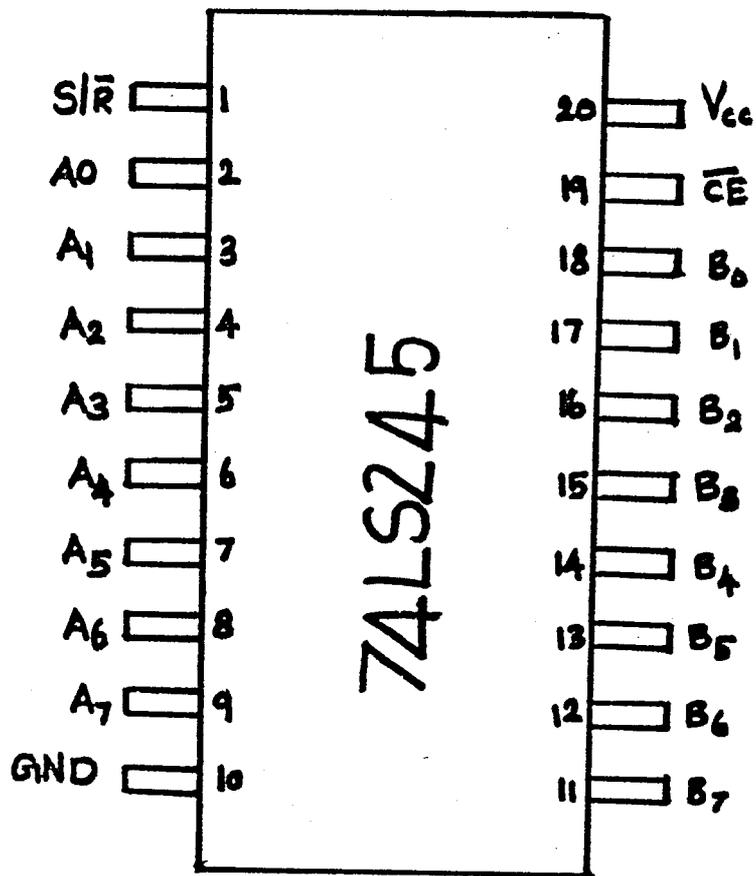
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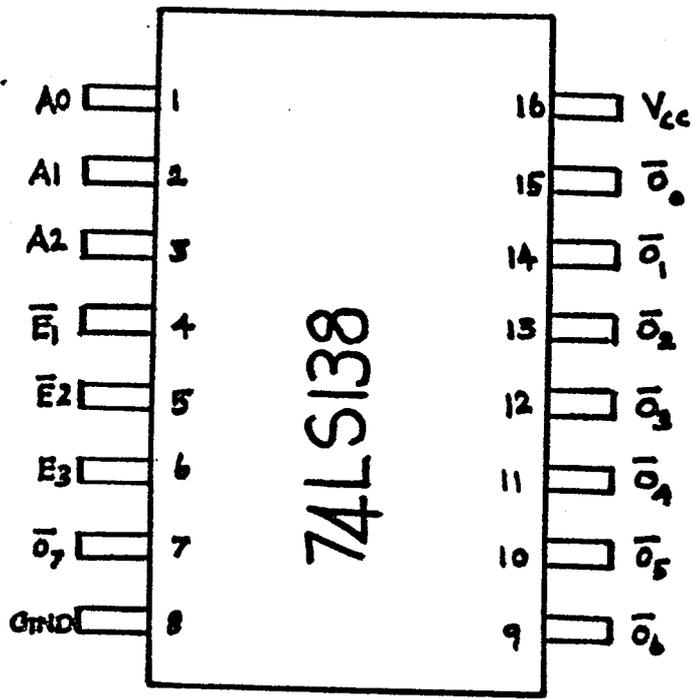
# APPENDIX



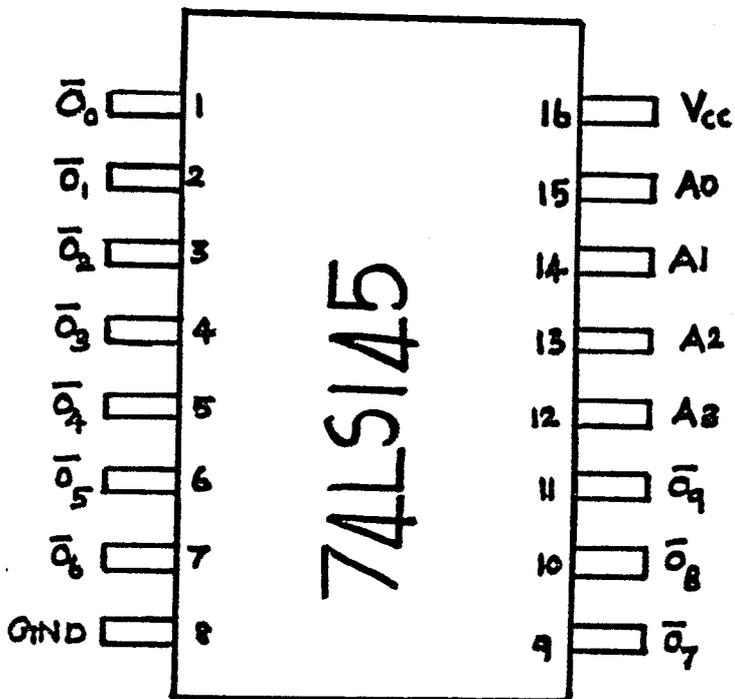
REAL TIMECLOCK CHIP



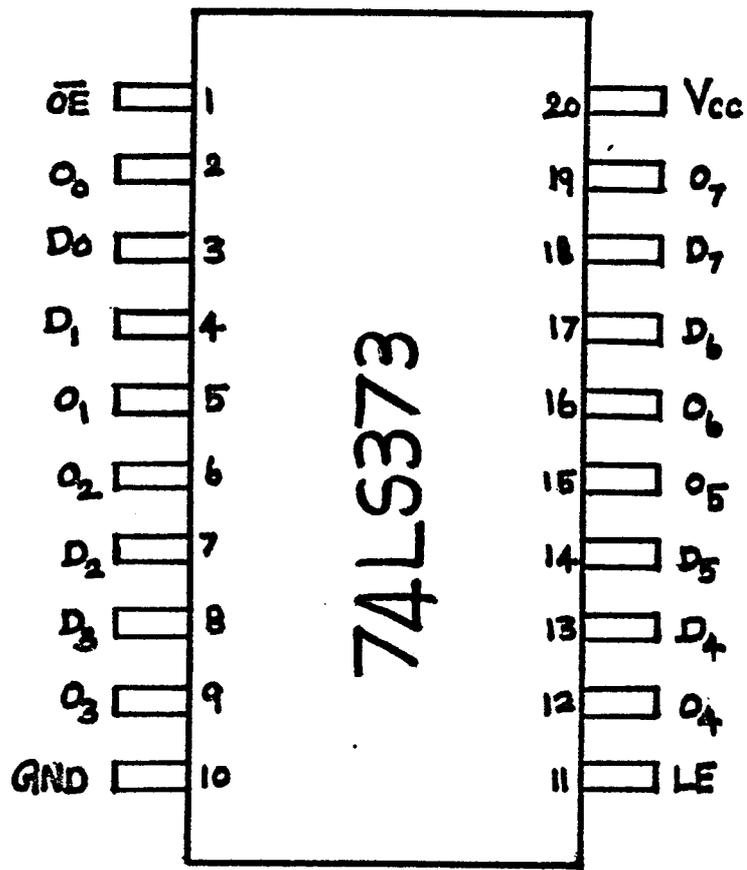
OCTAL TRANSCEIVER



3x8 DECODER



1 OF 10 DECODER



OCTAL LATCH/DEMULTIPLEXER