

**SECURITY ACCESS AND CONTROL USING RSA  
ENCRYPTION ON THE 8051 MICRO CONTROLLER**

PROJECT WORK DONE AT  
**INFOGNANA SYSTEMS**

P - 788

SUBMITTED IN PARTIAL FULFILLMENT OF THE  
REQUIREMENTS FOR THE AWARD OF THE DEGREE OF  
**MASTER OF COMPUTER APPLICATIONS**  
OF BHARATHIAR UNIVERSITY, COIMBATORE.

SUBMITTED BY

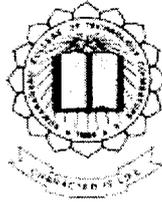
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May 2002

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(Affiliated to Bharathiar University)

Coimbatore – 641 006.

**CERTIFICATE**

This is to certify that the project work entitled  
**SECURITY ACCESS AND CONTROL USING RSA  
ENCRYPTION ON THE 8051 MICRO CONTROLLER**

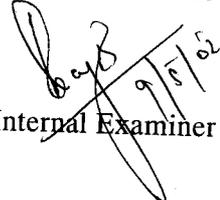
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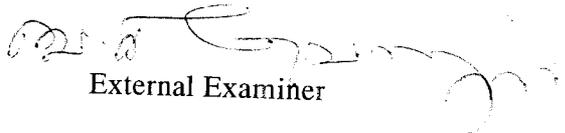
Submitted in partial fulfillment of the requirements for the award of the degree of  
Master of Computer Applications of Bharathiar University.

  
Professor and Head

  
Internal Guide

Submitted for the university examination held on 9/5/2002

  
Internal Examiner

  
External Examiner



April 25, 2002

**To Whomsoever It May Concern**

This is to certify that **Mr.Rajesh Ramachandran** of Kumaraguru College of Technology,Coimbatore has done a project with us on "**SECURITY ACCESS AND CONTROL USING RSA ENCRYPTION ON THE 8051 MICRO CONTROLLER (Code name:Info Crypt)**" for **TEXAS INSTRUMENTS (USA)** from December' 2001 to April' 2002.

He has successfully completed his **part of the project**. He was punctual and dedicated towards his project.

For **SRJ INFOGNANA SYSTEM (Pr) LTD**

**MANAGING DIRECTOR.**

## DECLARATION

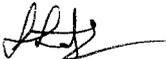
I here by declare that the project entitled **SECURITY ACCESS AND CONTROL USING RSA ENCRYPTION ON THE 8051 MICRO CONTROLLER** submitted to Bharathiar University as the project work of Master of Computer Applications Degree, is a record of original work done by me under the supervision and guidance of **Mr Babu Unnikrishnan**, Chief of Developments, INFOGNANA SYSTEMS, Coimbatore and **Mrs. Latha M.E.** Lecturer, Department of Computer Science and Engineering, Kumaraguru College of Technology, Coimbatore and this project work has not found the basis for the award of any Degree/Diploma/Associateship/Fellowship or similar title to any candidate of any University.

**Place: Coimbatore.**

**Date:** 30/04/2002



**Signature of the Student**

**Countersigned by:** 

## Acknowledgement

I express my profound respect and sincere gratitude to **Dr. K.K. Padmanaban Ph.D,** *Principal, Kumaraguru College of Technology, Coimbatore,* for his kind co-operation in allowing me to take up this project work.

I record my sincere thanks to **Dr. S. Thangasamy Ph.D,** *Head of the Department, Computer Science and Engineering, Kumaraguru College of Technology,* for allowing me to take up the project at *INFOGNANA SYSTEMS private Limited, Coimbatore*

I wish to extend my gratitude to **Mr. Babu UnniKrishnan,** *Chief of Developments INFOGNANA SYSTEMS private Limited, Coimbatore,* for allowing me to carry out the project at their organization and guiding me in completing the project successfully.

I am greatly privileged to express my deep gratitude to my guide **Mrs. Latha,M.E. ,** *Dept of Computer Science and Engineering, Kumaraguru College of Technology,* for her valuable advice and encouragement.

I also owe my sincere thanks to **Mrs. Geetha Vellingiri,** *Course coordinator, Master of Computer Applications, Kumaraguru College Of Technology, Coimbatore* for her guidance and immense support throughout my project work.

I express my sincere and heart felt thanks to **Mr. James G Urakkadan BE and Miss Priya. MCA,** of *INFOGNANA SYSTEMS private Limited, Coimbatore,* for their support in finishing the project. I express my sincere and heart felt thanks to Jose De Jesus Angel, Angel(Buenos Aires, Argentina) who has guided me through out this project with whom I was in constant touch via email. I also take immense pleasure in thanking everyone at INFOGNANA who were directly or indirectly involved in the success of this project.

*Rajesh Ramachandran*

## SYNOPSIS

The project entitled **SECURITY ACCESS AND CONTROL USING RSA ENCRYPTION ON THE 8051 MICRO CONTROLLER** which has been done partly for **INFOGNANA SYSTEMS** for their clientele **TEXAS INSTRUMENTS (USA)** is an embedded systems project by nature. The product in its hardware form encompassing software does encryption of textual data. Its ideal in situations where there is a security risk if conventional encrypting software is installed on the system. The product has been built in Borlands C++ on system and Keil C from Keil Software on micro controller.

Although not really embedded in nature into any particular device, the product can be built as part of any other system. The **software** for the project is divided into **two phases**

- i) Encryption of data and its interaction with the system
- ii) Connection of the Embedded device to a network (such as the internet) and its subsequent transmission using a protocol ideal for embedded systems.

This project is all about the Phase 1 i.e. Encryption of data and its interaction with the system.

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## 1.INTRODUCTION

## 1.1 PROJECT OVERVIEW

The requirements for a hardware solutions has increased duly in recent times owing to decrease in hardware costs and the advantages associated with hardware such as secrecy, compatibility, portability, ability to withstand external disturbances etc. This project aims to provide the software for the device under construction as specified by our clients Texas Instruments(USA).The software is under the testing phase at the moment and further improvements to it are being made.

### Objectives

Consider a situation whereby computers connected to a public network such as a Telephone line need to send confidential data .This can be done so using common encrypting software across all systems on the network. Modern Software Engineering has crossed all bounds that nowadays there exist Re-engineering tools which can be used to break into software thereby revealing details of the inner working of the software and other associated details.

Therefore the existence of even the most powerful encrypting software incorporating all the most sophisticated tampering mechanisms do not go fool proof. If broken into the consequences could prove fatal for any organization both Civilian as well as Military when espionage occurs

### Solution:

Since it can be seen that anything incorporated within the computer system does not remain safe, the solution is to have it external to the system. Thus the purpose of this project.

### A Brief Introduction to Micro controllers with relevance to Embedded Systems

As Microprocessors have become smaller and cheaper, more and more products have Microprocessors “embedded” in them to make them smart. Such products as VCR’s, Digital watches, elevators, automobile engines, thermostats, industrial control equipment and medical instruments are driven by these microprocessors **and their software**. The term embedded system means any computer system hidden in any of these products.

The size of embedded software written for micro controllers is small in size depending upon size of available memory(usually not extending more than a few hundred kilobytes of ROM) unlike software written for desktop computers. Therefore we cannot write any desktop applications such as word processing or image viewers for embedded systems. Embedded software for embedded systems are written to perform functions that are typical of micro controllers and in most cases these functions are limited in nature unlike desktop software. E.g. limited code to run a stepper motor, code to receive a character from another device and to send it to another, code to perform small computations like addition, subtraction, small encryption algorithms etc.

What is the difference between micro controllers and microprocessors?

Some people use the term micro controller for the very small end of the range of available microprocessors .Although there is no general accepted definition for micro controller, most people use it to mean a small, slow microprocessor with some RAM, and ROM, other than what is built in and a collection of pins that can be set high or low or sensed by the software directly.

Since the principles of programming a micro controller are the same as those for programming a microprocessor the term **microprocessor will mean both.**

What does it take to understand embedded systems programming?

Anyone can understand the structure of a micro controller ,its associated components ,how they are interrelated to each other.

Does any engineering background required for embedded systems programming?

Physical quantities such as voltage levels, speed of transfer, clock generation etc. are represented as **constants** in programming. Their conversion in to corresponding **analog** or **digital** signals are taken care of by the structure of the entire hardware .Therefore an embedded systems programmer need not bother about the technical details.

Lots of manufacturers supply Micro controllers, E.g.: Intel, Motorola, Hitachi, Arm, Philips, Atmel etc .

Their basic structure remains the same except for a few enhancements such as more memory or extra timer or extra port etc. They are accompanied by their instructions manual explaining how to program them. Understanding of the basic instruction set is more or less enough to understand micro controller programming.

Engineering study more or less explains how these signals of different types represented as constants are converted to hardware signals. They are of no relevance to Embedded systems programmers as mentioned above. In other words the micro controller is nothing but an **empty shell** requiring programmers to have a basic knowledge of its **design** and **instruction set** to be programmed as per requirements. Therefore no engineering knowledge is required to do embedded systems programming.

### About the Computer System

The IBM- PC is a versatile one in its design in the sense that we can connect external devices to it and interface it. This provision is made through the Serial, Parallel and USB Ports.

#### The Device

Code named **Info Crypt**, This device which is a Micro controller(explained in the System Study Chapter will be connected to the Serial Port and will incorporate the Encryption Algorithm. The Algorithm considered is **RSA** .Programming for this will cover the following Areas:

- User Interface Design
- Serial Port Programming(On System)
- Serial Port Programming(On Device)
- RSA Algorithm

#### The RSA Algorithm

An innovation by Ron Rivest, Adi Shamir & Leonard Adleman,this encryption algorithm is based upon a public key pair and a private key pair.

## Mechanics of RSA encryption:

The "key" of an RSA cipher is three numbers: The first is  $X_{pub}$ , the public exponent, the second is  $X_{priv}$ , the private exponent, and the third is  $Mod$ , the modulus. The message  $M$  (which must be shorter than  $Mod$ ) is interpreted as a number.

It is broken into chunks as necessary to meet the length requirement. This number is raised to the power of  $X_{pub}$ , modulo  $Mod$ , to give  $C$ , the cipher text.  $C$  may in turn be raised to the power of  $X_{priv}$ , modulo  $Mod$ , to give  $M$ . The public key is the pair  $(X_{pub}, Mod)$ . The private key is the pair  $(X_{priv}, Mod)$ . If Bob and Alice want private communications, they each generate a pair of keys, then may exchange public keys using a non-secure channel, such as email or telephone.

Thereafter, when Bob desires to send Alice a message, he can encrypt it using Alice's public key and send it via a non-secure channel. When Alice receives it, she uses her private key to decrypt it and read it. The nice part is that Sam, even though he has been able to read every message sent over the non-secure channel, cannot decrypt that message; he would need Alice's private key, which she has never had to send.

### Example

$P = 61$     <= first prime number (destroy this after computing  $E$  and  $D$ )  
 $Q = 53$     <= second prime number (destroy this after computing  $E$  and  $D$ )  
 $PQ = 3233$  <= modulus (give this to others)  
 $E = 17$     <= public exponent (give this to others)  
 $D = 2753$  <= private exponent (keep this secret!)

Your public key is  $(E, PQ)$ .

Your private key is  $D$ .

The encryption function is:  $\text{encrypt}(T) = (T^E) \bmod PQ$   
 $= (T^{17}) \bmod 3233$

The decryption function is:  $\text{decrypt}(C) = (C^D) \bmod PQ$   
 $= (C^{2753}) \bmod 3233$

To encrypt the plain text value 123, do this:

$$\begin{aligned} \text{encrypt}(123) &= (123^{17}) \bmod 3233 \\ &= 337587917446653715596592958817679803 \bmod 3233 \\ &= 855 \end{aligned}$$

To decrypt the cipher text value 855, do this:

$$\begin{aligned} \text{decrypt}(855) &= (855^{2753}) \bmod 3233 \\ &= \end{aligned}$$

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= 123

## 1.2 ORGANIZATION PROFILE

Infognana Systems, a Coimbatore based company with a liaison office in Dallas ,Texas ,USA is headed by a group of US based NRI' s working for Texas Instruments undertaking embedded projects across a wide range of development platforms. The company is about 2 years old and the projects undertaken are the low end types. The reason being that Embedded systems programming is not very familiar to many in the IT Industry. By undertaking small projects programmers are able to understand embedded systems more and its underlying concepts.

The Organization has a workforce of 7 budding programmers of which 6 are undertaking projects as well are in training. Their prime focus are on the markets of USA and Israel. Their current projects include Anti Lock Braking System design, Cruise Control Design, Encryption, Industrial Printing automation design(undertaken for a local company here in Coimbatore) and small scale Device Driver Development.

The Organization at the moment concentrates on software only and will be employing experienced people in hardware design in the near future for which interviews are being conducted.

## 2. SYSTEM STUDY & ANALYSIS

## 2.1 Existing System available & its limitations

As indicated above, The existing system which in the general sense has a lot of limitations requires a hardware implementation running its corresponding software which will ensure complete secrecy of data transmitted over any public network.

What if the device gets into the wrong hands?

There are no known methods at present in which the code stored in a devices ROM is obtainable. Of course this fact can not be overlooked. But the degree of security is far more higher than conventional encrypting software.

## 2.2 Proposed System

A Hardware product which is to be connected to the serial port, incorporating RSA Encryption which in turn will be routed back into the system for further processing or normal transmission to destination machine through the network.

## 2.3 Requirements of the new System

### a) Software

- Easy to use interface is the primary concern. The user should not fear that he \ she is using a complicated device and so must be very careful in its usage. nor should any complications be felt while using the device lest they should switch to conventional methods of Encryption.
- The System should not interfere in the normal working of other processes nor cause any Operating System violations.
- The System should operate on devices with a varying degree of Baud Rates (The rate at which Data is transmitted in a given interval of time).

- Provision for connection should by default at COM Port 1 and extended to cover at least 3 more ports i. e COM Port 2,COM Port 3 & COM Port 4.
- Since this is a Technical Software an extensive Help system is required to guide new users in its usage.
- After usage any intermediate files created by the software should be removed from the system to avoid access by unauthorized users.

## b) Generation of Error Reports

includes the following two categories of Errors encountered in Serial Transmission:

### a)Initialization Error

occurs as a result of improper settings in the transmission parameters such as

- Port Selection
- Framing
- No of Stop Bits
- Baud Rate Selection

### b)Transmission Errors

occurs as a result of data Transmission viz.

- Framing Errors
- Parity Errors
- Overrun Errors
- Timeout

### c) Log Creation

A Text File is created recording the following details

- Most recent date on which Info Crypt was used
- Time
- Duration

## 2.4 User Characteristics

Ideal for Military and Industrial usage .This product can be used in situations where by its catastrophic to use conventional encrypting software as mentioned in the System Study & limitations page.

The Users interface acts silently in the background and a button pops up when text files with the following extensions is opened i. e

- MS Word Files
- Acrobat PDF Files
- Word Pad Files, Note Pad Files

Upon clicking the button The program to interface with the device is invoked. The user has to set the parameters i. e

- COM Port Selection
- Baud Rate Selection

At the same time the files contents are loaded in the Transmitting Window of interface software. When the send button is selected the data is transmitted to the device and the encrypted resulted can be viewed in the Receivers Window.

All Efforts have been made to make the software as user friendly as possible in the best possible way.

### 3. PROGRAMMING ENVIRONMENT

### 3.1 Hardware Configuration (Minimum Requirements)

#### On System:

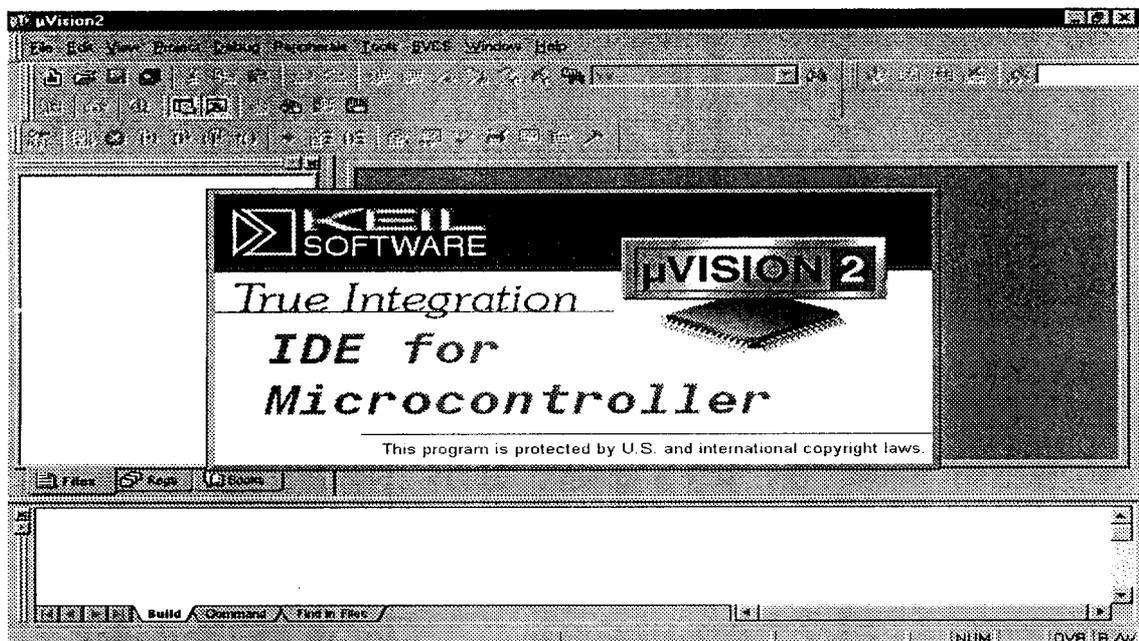
- Pentium 233 MHz
- 32 MB RAM
- 1 RS 232 Configured Serial Port
- 1 MB of Hard Disk for Program Storage

#### External:

- MCS-51 NMOS single-chip 8-bit micro controller with  
32 I/O lines, 2 Timers/Counters, 5 Interrupts/2 priority levels  
4 KB ROM, 128 Bytes on-chip RAM.

#### Micro controller Programming

**mu-vision 2** from Keil Software: This is a cross compiler that supports assembly language programming as well as C programming for the 8051 micro controller from a wide range of manufacturers. The programmer has a choice to code in a normal High Level language or in Assembly. After compilation a Hex file can be generated since only Hex codes can be understood by the micro controller. This Hex file can be downloaded in to the simulation kit for execution. The IDE is as shown below.



## RS 232 Configured Cables

D Type( 9 Pin Connectors)

Length : approximately not more than meters in length

## 3.2 Software Requirements

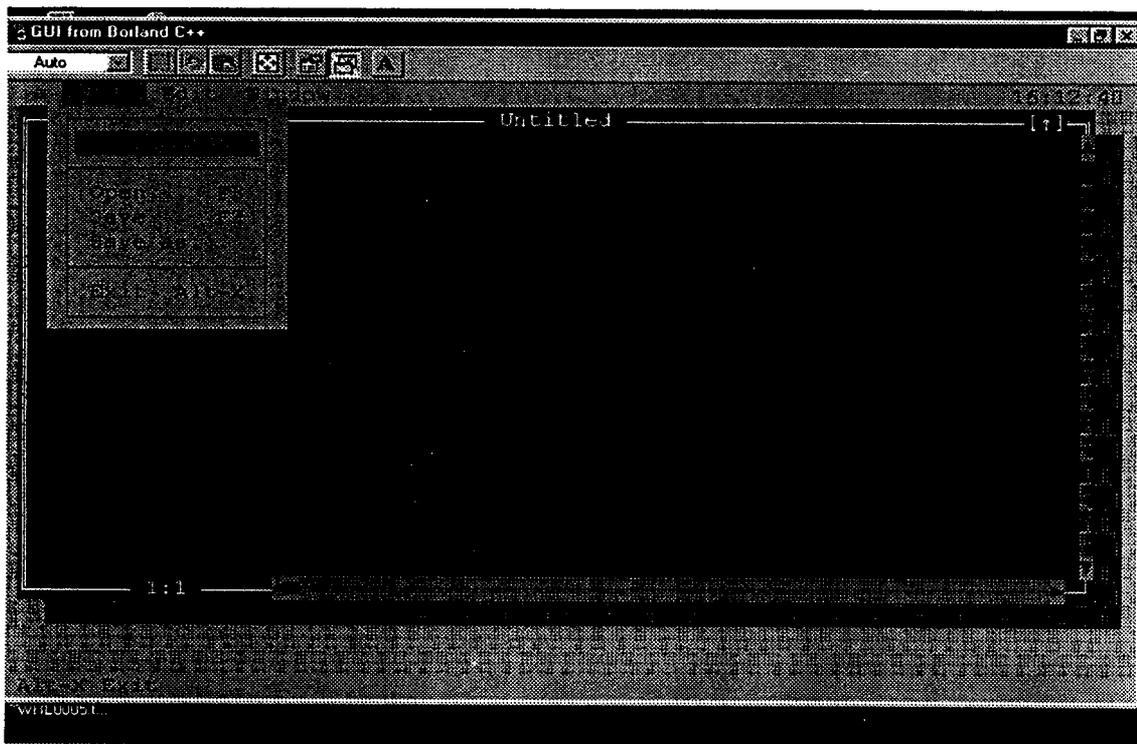
### On System Programming

**Borland C++ ver 3.1** with Application Framework Creation for DOS  
with extended support libraries for Serial Port Programming  
from Jean J Labrosse with his book

Brief description about software tools used

#### Borland C++

The C++ Compiler from Borland provides efficient construction of programs following The OOP's paradigm. Unlike other compilers from other firms, Borlands compiler supports n creation of user interface components such as Menu Bars, Menu Items, Input Box, Buttons etc. A sample application is as shown below.



Why choose Borland C++ than other compilers like Visual C++, Visual Basic etc.

True, that it will be much easier to design user interfaces as well as code for Serial port programming in these platforms however since they are dependant on the Windows Platform as these tools have been designed to be they cannot be ported to non-Microsoft Platforms. A working version in Java will be implemented when this phase is successful to make it platform independent.

How were the User Interface Components built in C++

**Borland C++ extension to Turbo Vision**(an application framework for creating DOS character mode applications. Turbo Vision is in part a user interface toolkit. It has components that let you construct dialog boxes, overlay windows, build menu based applications etc. In addition Turbo Vision specifies how these components will work together to form a full application as shown in the sample application above.

The advantages of DOS based Turbo Vision compared either Windows development include

- ❖ Applications can run on a wider range of machines because character mode user interfaces require less power.
- ❖ Applications require less development effort ,which makes it easier to recoup your costs even when a niche market is targeted.
- ❖ Turbo Vision is an ideal upgrade path for improving the interface of existing DOS character-mode applications.

Turbo Vision is a C++ class library and it fully uses C++ capabilities. Turbo Vision is an **event driven system** which means it responds to all mouse events.

## About extended support libraries from Jean J Labrosse

The complexities involved in Serial port programming in C++ are high since no standard commands are available to implement them with one single command unlike other languages like Visual Basic and Visual C++. There are lots of support libraries available from Corporations, University Archives and individuals but none proved to be more useful than the one supplied by **Jean J Labrosse** along with his book **Embedded Systems Building Blocks, Ready to use modules in C**.

Reasons:

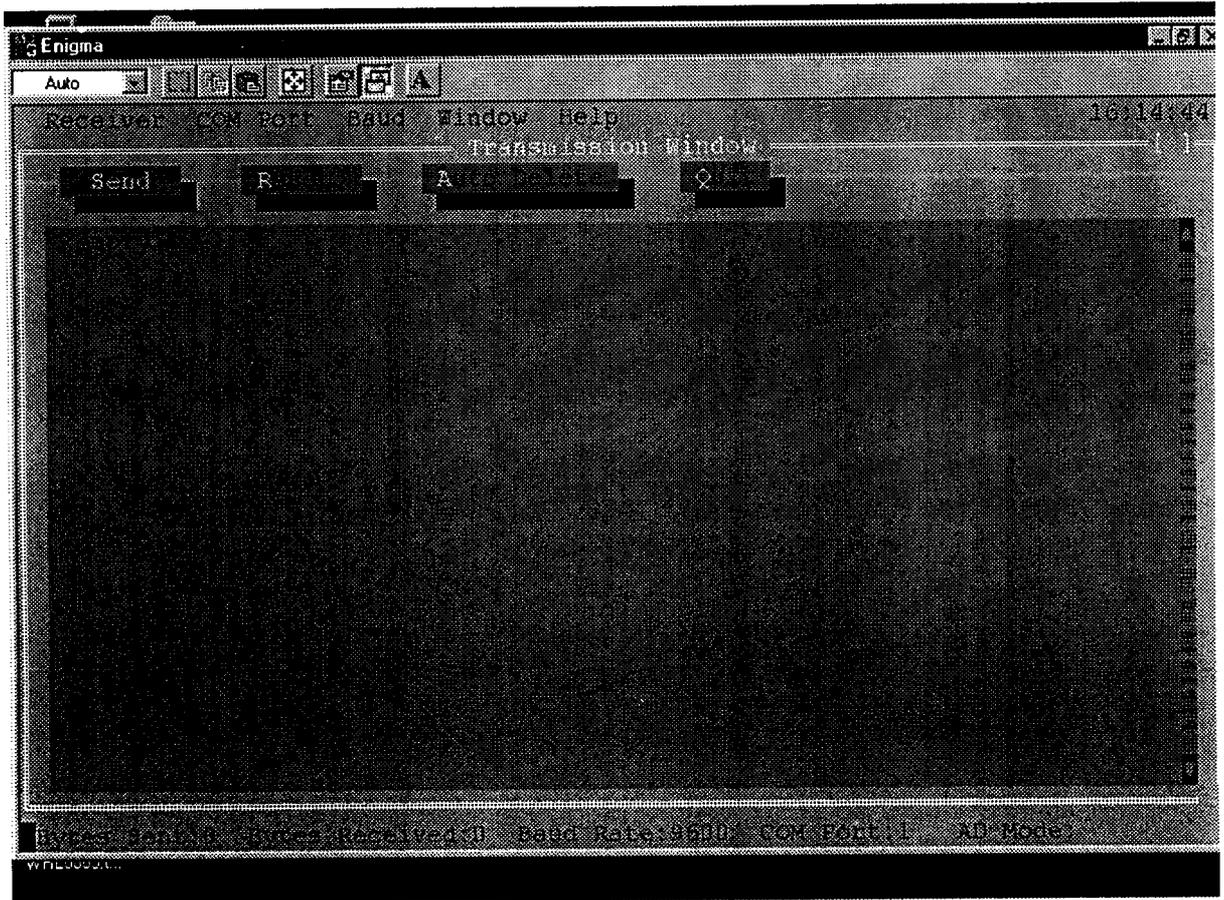
Support for other interfaces like

- RS 232C
- RS 485
- Synchronous Serial Data Transfer
- Parallel Port Programming

## 4. SYSTEM DESIGN AND DEVELOPMENT

## 4.1 Input Design

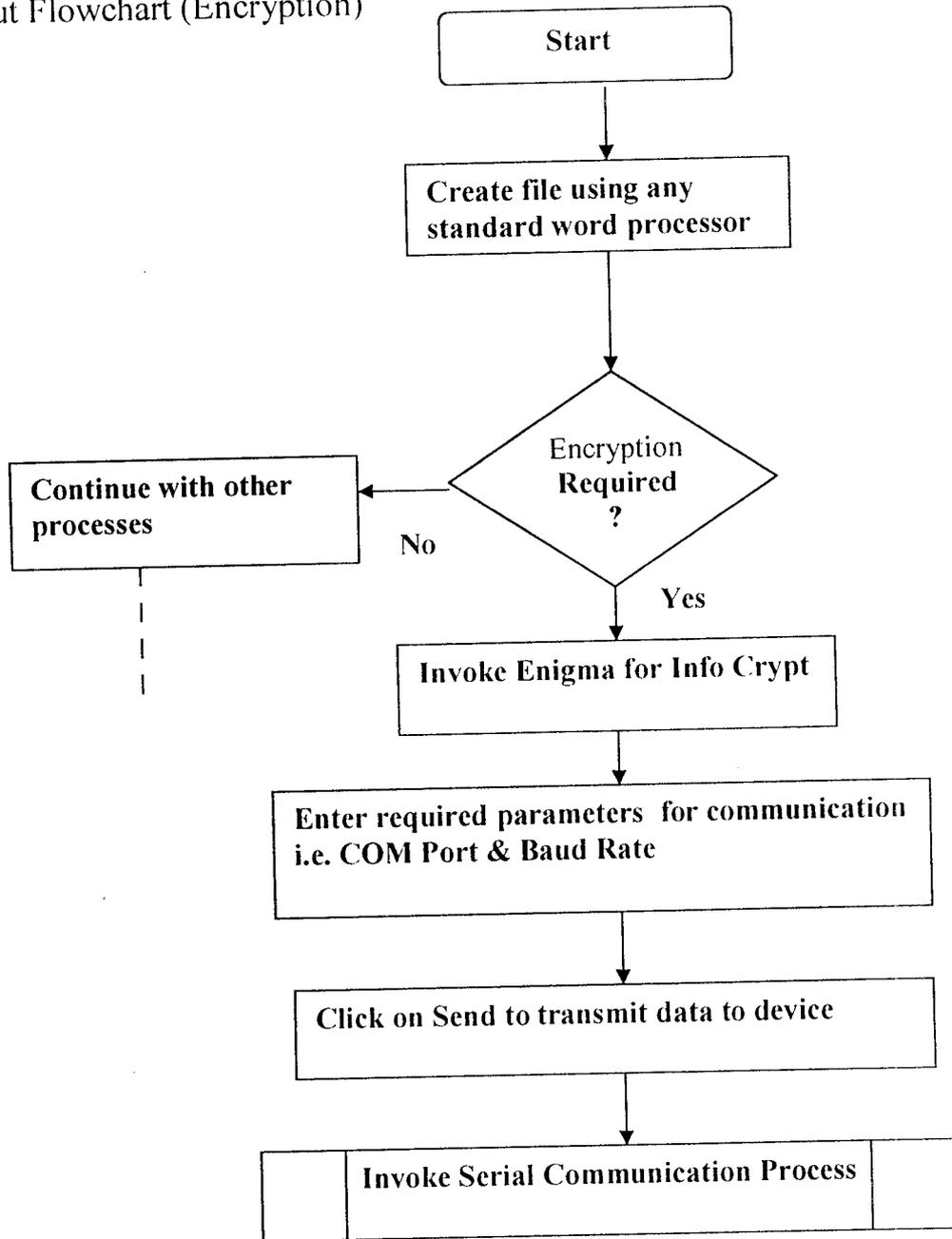
Input to Enigma is through the transmit window ,which will in turn be used as input to Info Crypt after setting all required parameters as shown below.



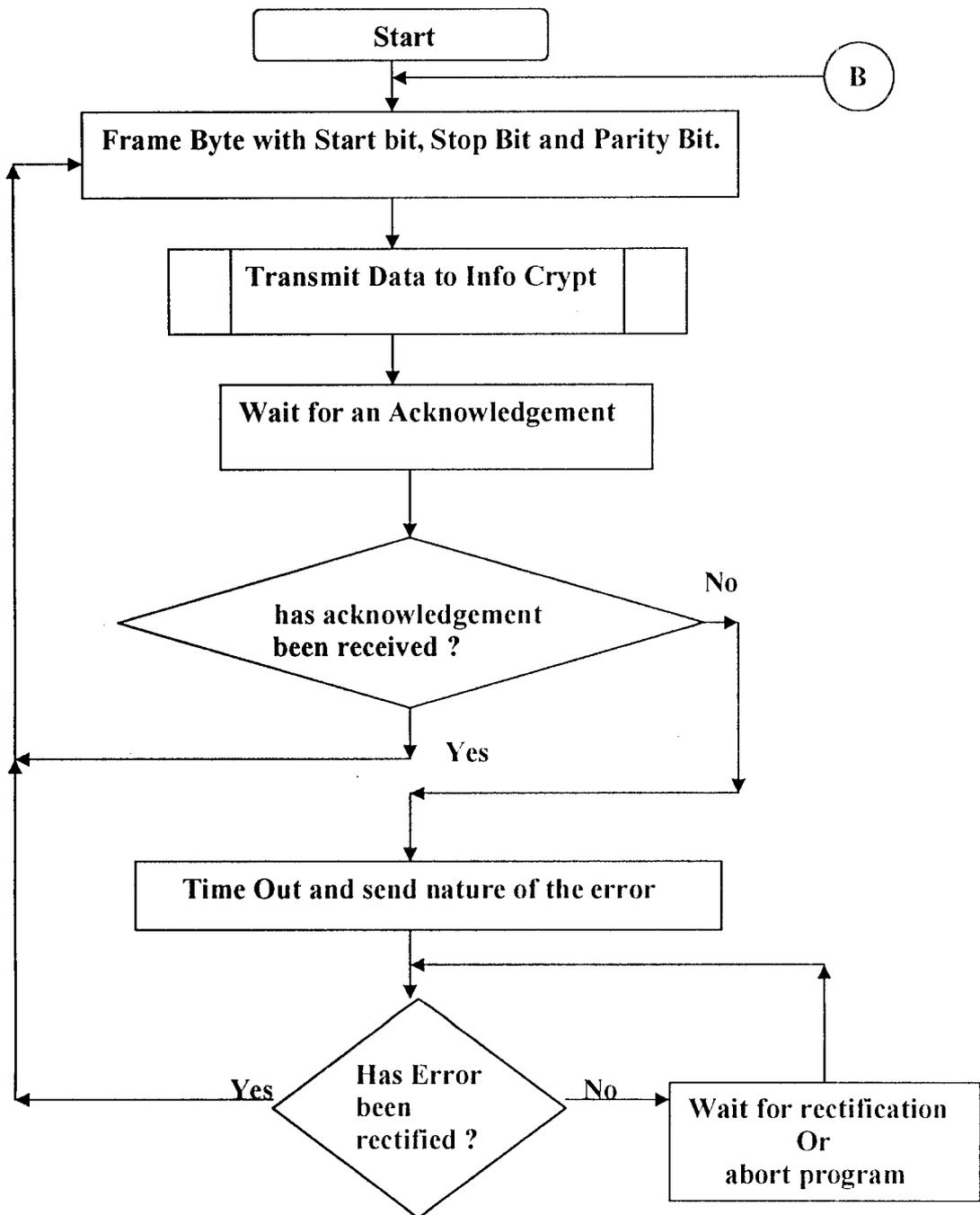
## 4.2 Process Design

In terms of flowcharts as shown below.

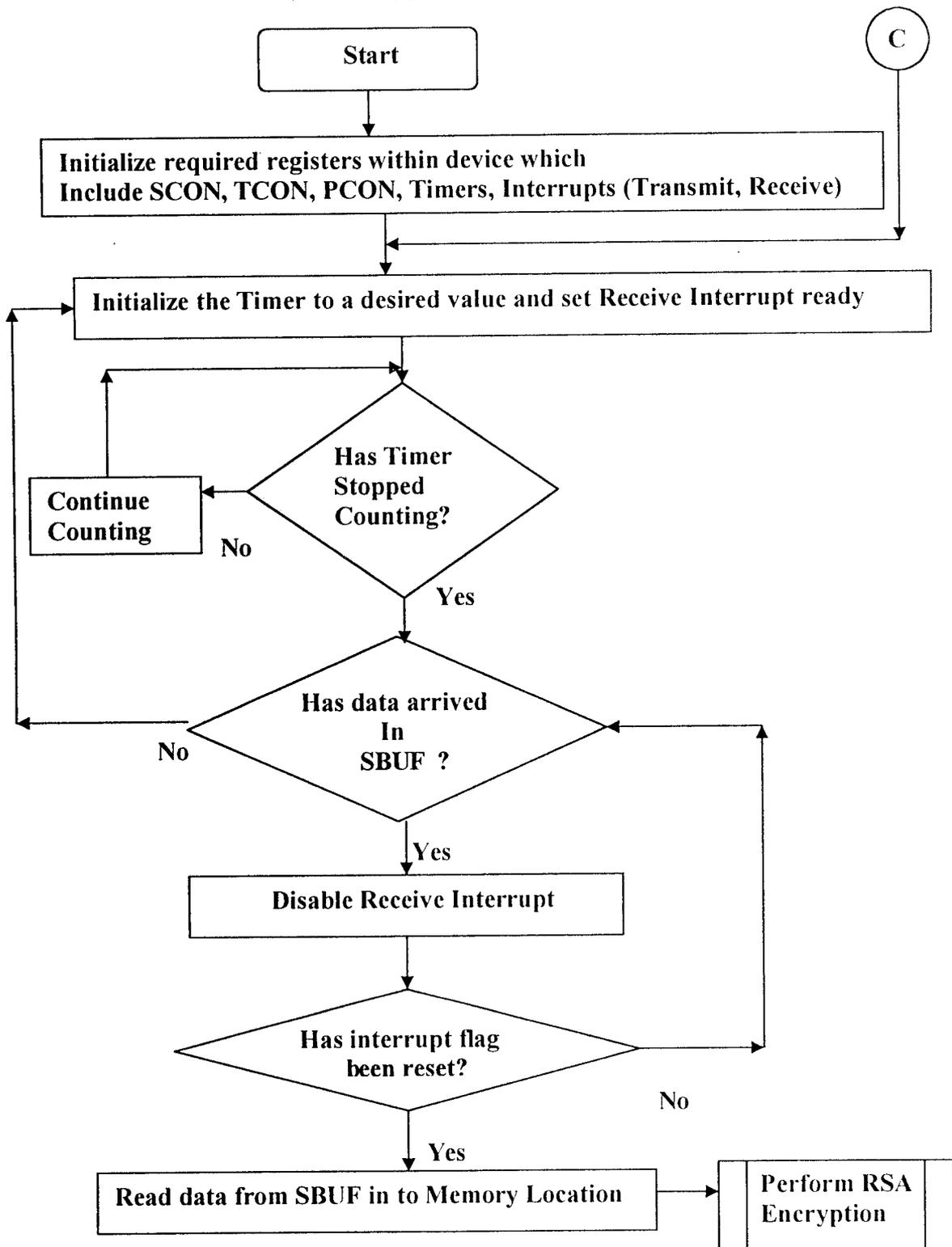
Input Flowchart (Encryption)



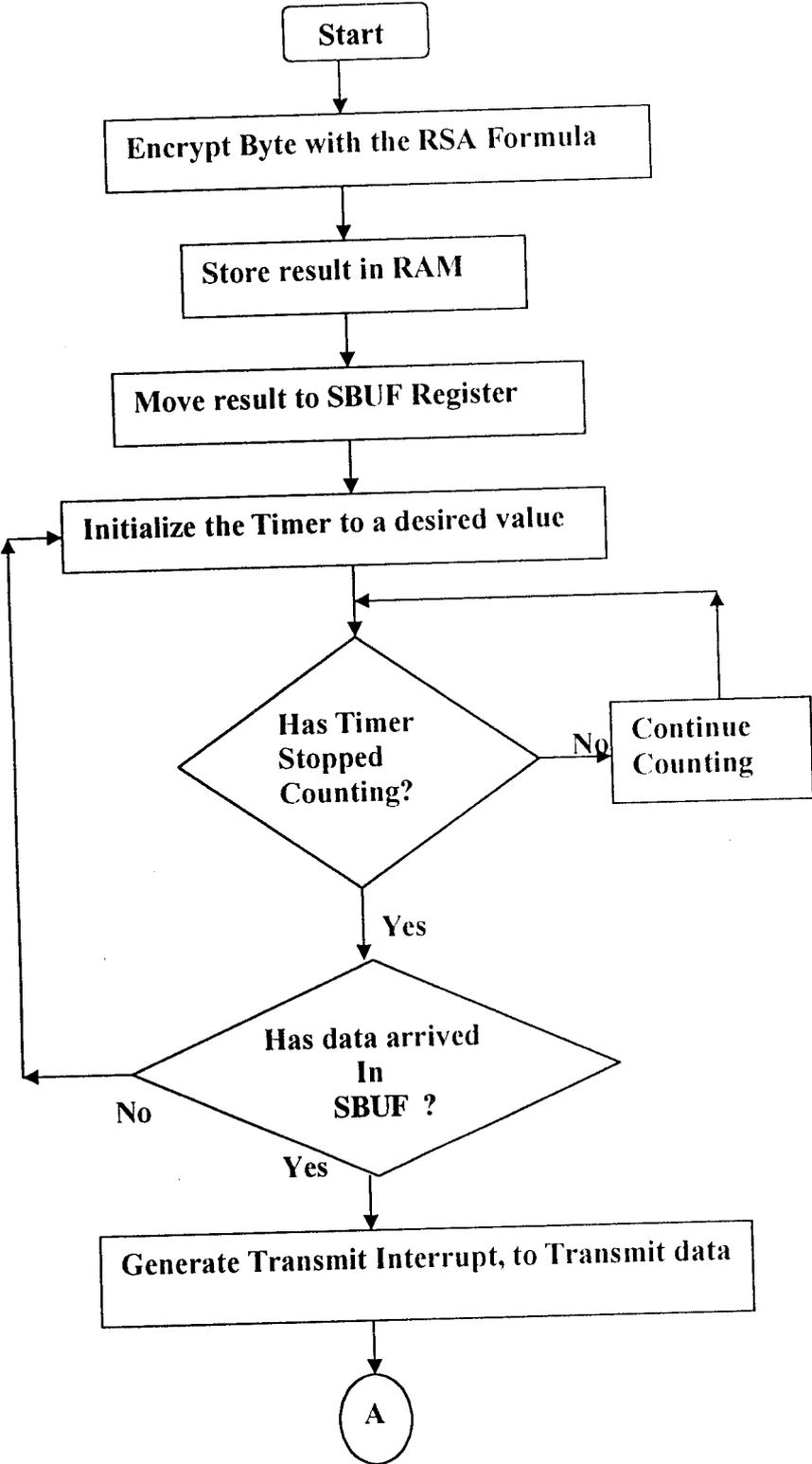
## Serial Communications Sub-System Flowchart

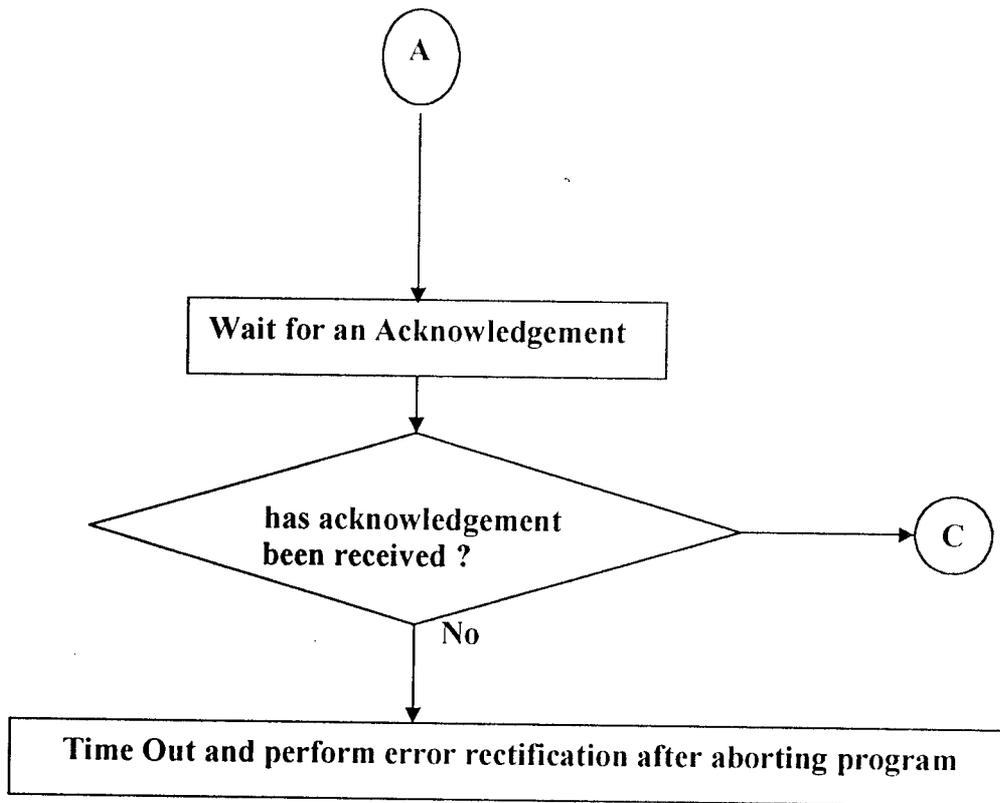


## Serial Communication(Info Crypt)

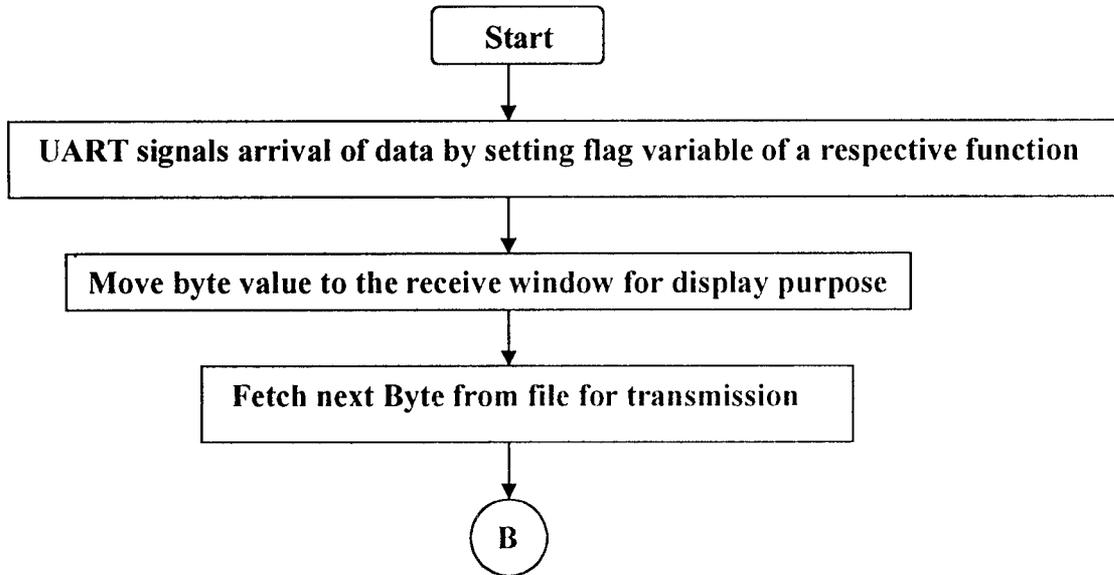


# RSA Encryption



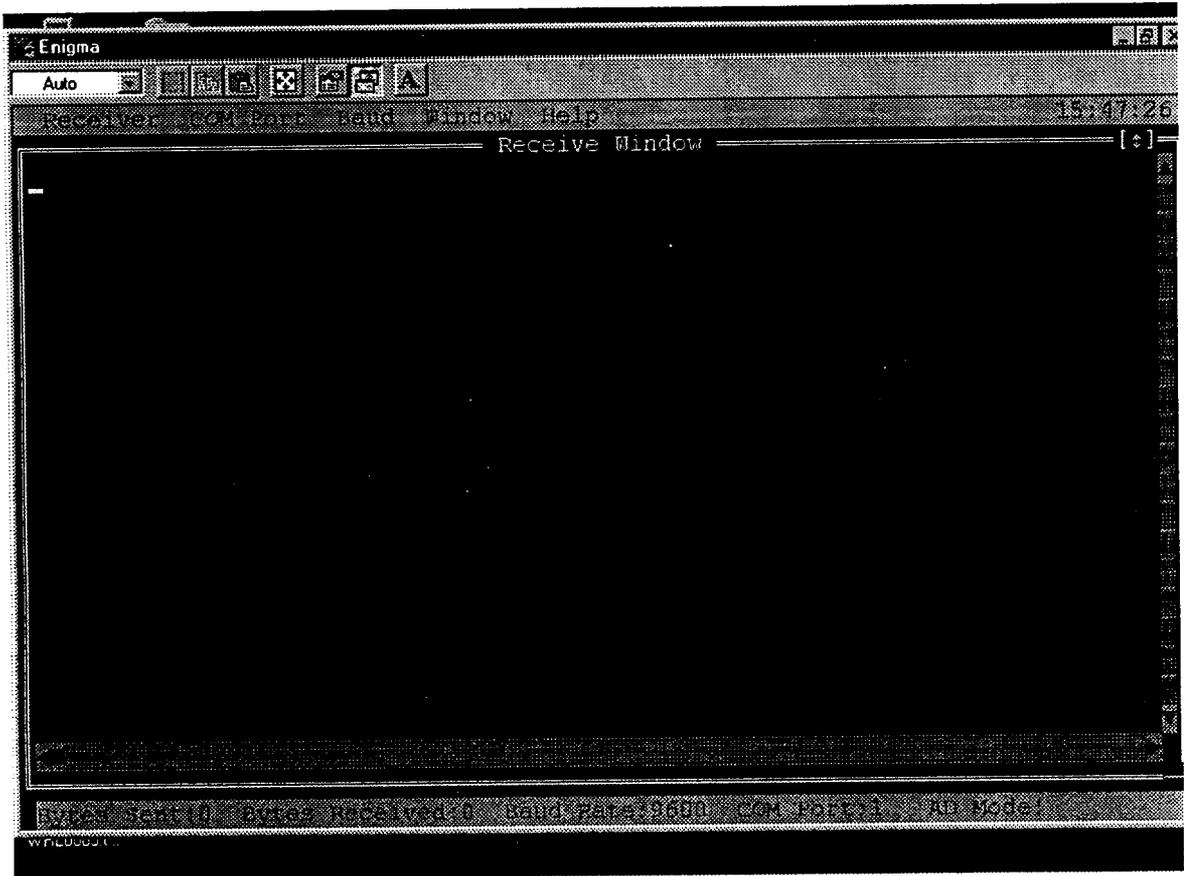


## Upon Reception of Data in System



### 4.3 Output Design

The output to enigma is Cipher Text which will appear in the receivers window as shown below



### Analysis

The Cipher text produced should provide a sufficient challenge to anyone who would like to break the code.

## 5.SYSTEM TESTING AND IMPLEMENTATION

## 5.1 System Testing

### Main Test Criteria:

Successful Encryption of data to be viewed in the Receivers window.

#### 5.1.1 Stages in Testing(Unit Testing)

a)Successful loading of file into to Enigma, its output to be viewed in the transmit window.

Result:	Problems	Remedy	Conclusion
Successful	Appearance of yet unknown symbols towards end of each line.	Not decide as yet	No mistakes in data been received

b)Transmission of individual byte to device

Result	Problems	Conclusion
Successful	None so far	Correct Error reports are been received as expected of Serial Transmission in case of errors encountered else transmission successful.

c)Receival of byte in Info Crypt

Result	Problems	Conclusion
Successful	None so far.	Byte received correctly and transferred to correct memory location.

d)Encryption of byte

Result	Problems	Conclusion
Successful	None so far	Correct Encryption of byte .

e)Transmission of encrypted byte to system

Result	Problems	Conclusion
Successful	None so far	Correct receival of byte into the system

## 5.1.2 Other Test Criteria(for small individual modules)

### Secondary Operations

which includes the following

#### i)Reset

This option resets Enigma to the default values

#### ii)Quit

### User Interfaces

which includes

#### i)Zooming of Windows

#### ii)Tiling of Windows

#### iii)Next

#### iv)Previous

#### v)Toggle

#### vi)Appearance of Error Messages, Help Window & About Boxes.

### General Conclusion

All working correctly as per requirements.

### Unknown Factor

Clogging of the system with huge volumes of data as file sizes get larger. This is yet to be uncovered through further testing.

### 5.1.3 Integration Testing

#### Results

The various unit-tested modules were integrated and tested in accordance to their relation with other modules and they were found to be working in perfect harmony

### 5.1.4 Validation Testing

#### Results

#### a) Operating Systems

Enigma worked well with the following Operating Systems

- Windows 95
- Windows 97
- Windows 98
- Windows ME
- Windows NT/2000

#### b) Serial Ports

Enigma was also tried on 4 serial Ports and found to be working correctly

#### c) RS 232 Connectors

Type D:

Tested to a distance of **3 meters** and found to be responding correctly.

**Condition!**

**Only a Cable correctly configured for Info Crypt can be used  
for communication purpose else no results will be displayed.**

d) On Existing Encryption Software

Enigma worked successfully and other party encryption software too worked  
successfully **without any interference** from Enigma.

e) On other software.....

like games, image processors, audio and media players, voice recognition  
systems etc. **No interference** was to be found

## 5.2 System Implementation

To successfully implement the system developed, planning is necessary. Proper planning is done to take care of the following:

- ◆ The implication of the system as a real time system.
- ◆ Resources available for the system using the product.
- ◆ Changeover:

Changeover is the process of shifting from the existing system to the new system. The changeover from the existing system to the new system takes place after system testing and found to meet all requirements needed by the company.

### Implementation procedures of Info Crypt

- ❖ Install Enigma through the set up program. Existence of Enigma on system should not pose a security threat as no coding algorithms are present.
- ❖ Connect RS 232 Cables to the Systems Serial port and in turn connect Info Crypt to the system.
- ❖ Use as Plug and Play with concerned applications.

### 5.3 System Refinements & Feedback

Moments of meeting held on 10<sup>th</sup> April 2002

Topic : General Discussion about Info Crypt

Meeting called by: Rajesh Ramachandran

Objectives: To discuss the progress made so far on Enigma & Info Crypt and to bring  
in new ideas to the product

Members: 6

Main Suggestion to existing product: To include a **File Save Option** to save the  
contents in the receivers window in to a  
file.

Arguments: Saving of an encrypted file in the system is hazardous and will violate the  
principle of what Info Crypt is designed for. However so as not to be too  
restrictive this option maybe provided for with the user keeping in mind of  
the dangers of keeping the file on system.

Other Suggestions: To provide for encryption for sound, pictures and moving files on  
the same product.

## Building of the product

Upon successful testing of the product which was concluded on the 24<sup>th</sup> of April, the product will be built in to a more compact device incorporating its own power supply, casing ,wiring etc. This is the responsible of the more Technical competent Hardware design team of qualified engineers.

### **Expected date of submission to Client**

June 20<sup>th</sup>.

CONCLUSION

## Conclusion

The first phase of the project is fully functional as per requirements although the fact that clogging of the system cannot be overlooked by huge volumes of data due to the slow nature of serial transmission. However the product is still under testing on simulation kits and no obscurities have been uncovered so far.

There are so many products in the form of chips which incorporate Encryption algorithms available in the market. While undertaking this project we learnt how it could be done and the significant advantages of doing so. The following objectives were obtained.

- ❖ Encryption on an external system providing good security
- ❖ Even if system gets in to unauthorized hands, there is no way of breaking the software containing the code using hacking tools since its not resident on the system
- ❖ Even if Info Crypt gets in to unauthorized hands there are no known methods of reading ROM Resident code.

Since the first phase of the project is more or less successful the second phase will commence soon i.e Connection of the Embedded device to a network(such as the internet)and its subsequent transmission using a protocol ideal for embedded systems.

**SCOPE FOR FUTURE DEVELOPMENT**

## Scope for future Development

Connection of Info Crypt is possible to only one system which means at any given time only one file can be encrypted at a time. For parallel processing of several files many devices may have to be attached to many serial ports connected to the system which will prove to be quite inconvenient .A more broader **RS 485 standard** can be used which follows polling i.e. each device connected to a common serial port will be repeatedly polled for data transmission at a fixed time intervals.

Scope also exists for encryption of non textual files like pictures ,media etc though not possible on the same product with the same encryption algorithm owing to memory space restrictions. In other words Info Crypt can take several forms to encrypt non textual matter incorporating more suitable algorithms. This process of doing so is underway by examining conventional software which do so.

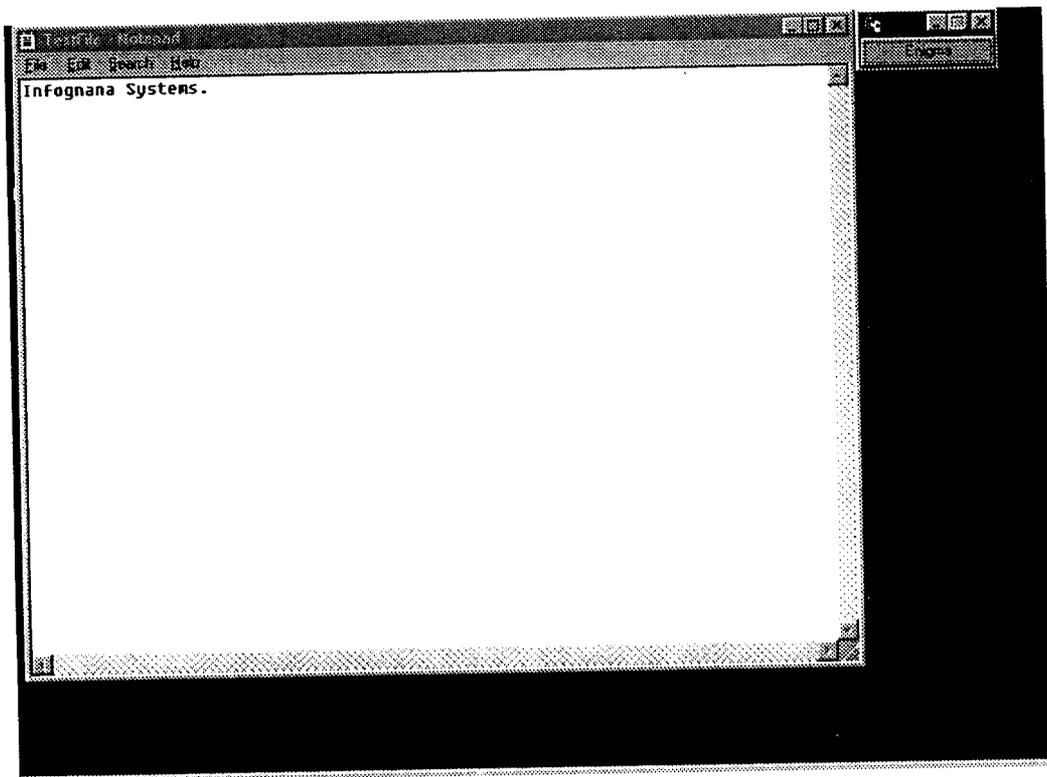
## Internet Resources

- i) [www.microlink.co.uk/rs232.html](http://www.microlink.co.uk/rs232.html)
- ii) [www.howstuffworks.com/serial-port1.htm](http://www.howstuffworks.com/serial-port1.htm)
- iii) [www.taltech.com/TALtech\\_web/resources/intro-sc.html](http://www.taltech.com/TALtech_web/resources/intro-sc.html)
- iv) [www.primenumbers.com](http://www.primenumbers.com)

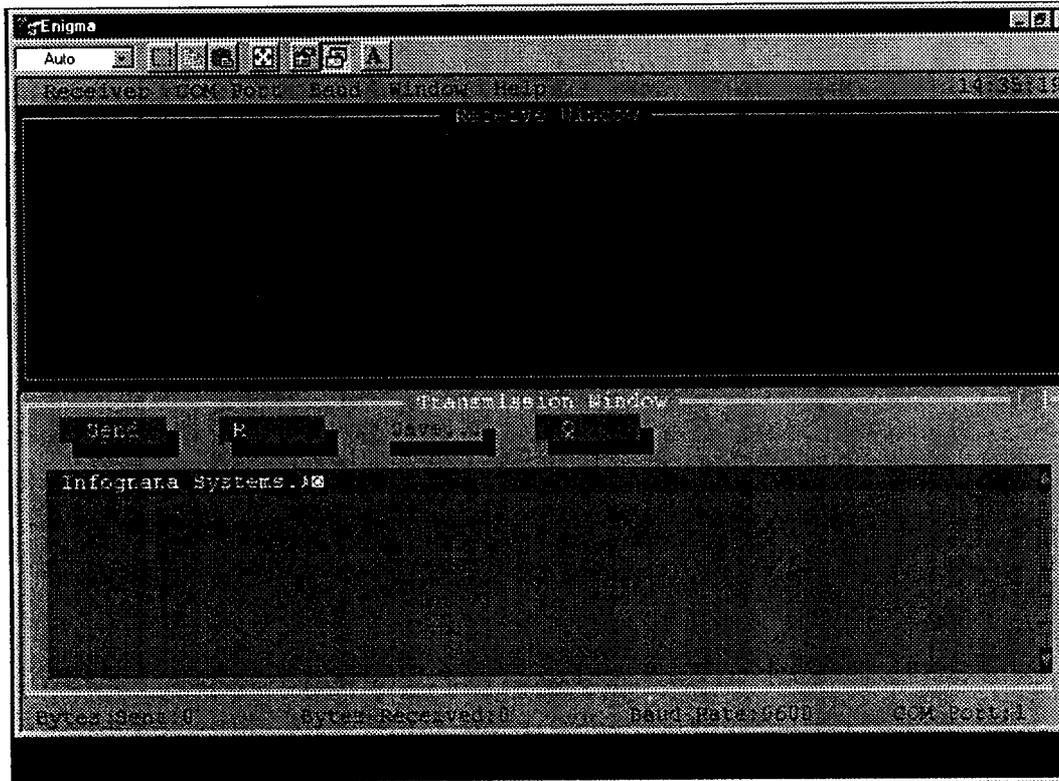
## **APPENDIX**

The following sample outputs labeled from (ii) onwards are the subject of this report.

Output (i) is the result of Windows Programming done in Visual C++.

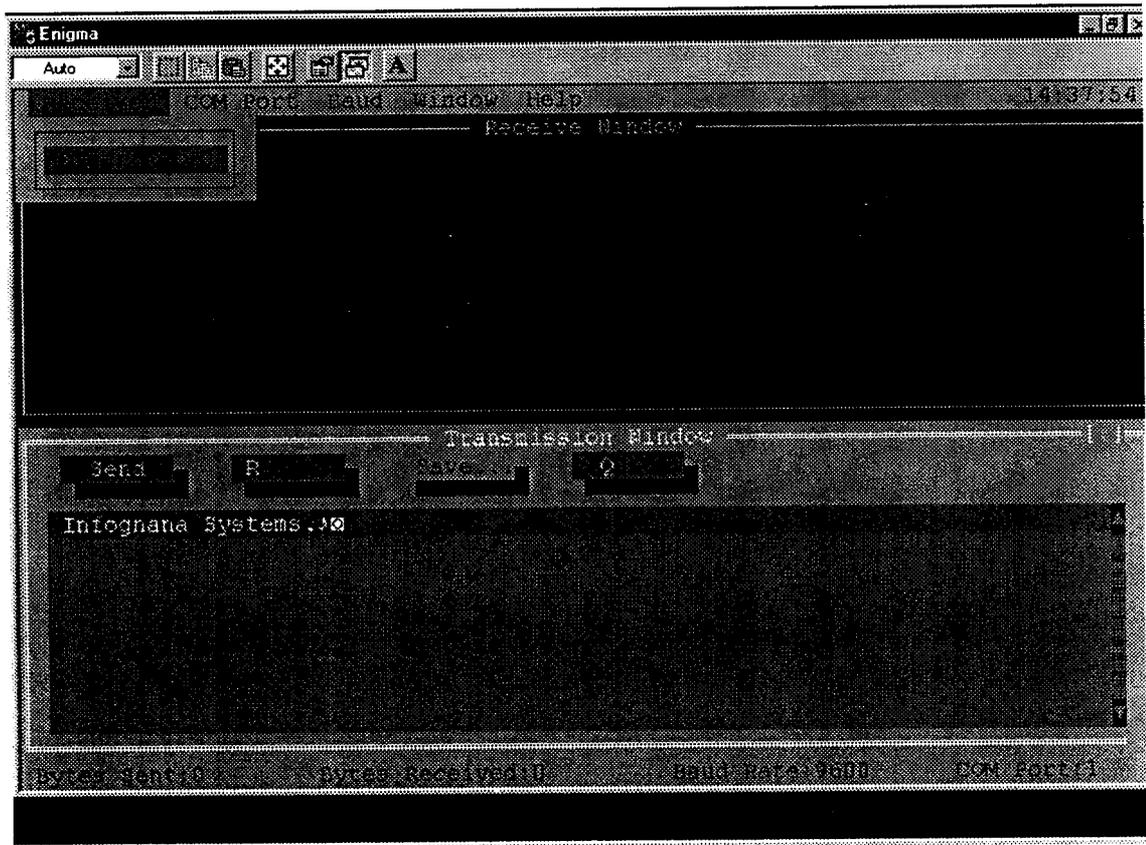


(ii) This is the default screen that pops up when the enigma button is clicked. The screen is split in to two windows a receive window and Transmission window as shown above.



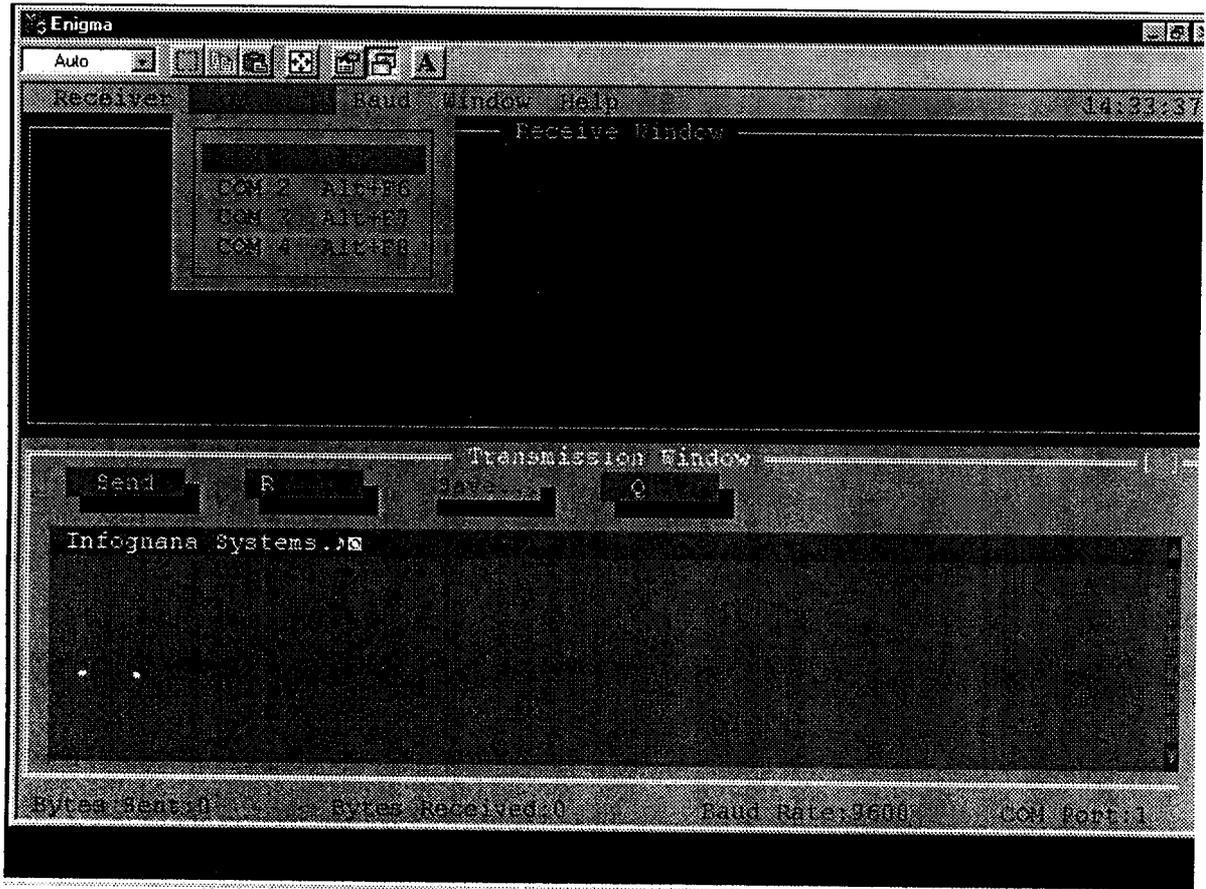
Other components include a Menu Bar, Commands on the Transmission Window and a Status bar. By default the Save button on the Transmission window is dimmed. Note that data found in the word processors window is loaded into the Transmission Window.

(iii)



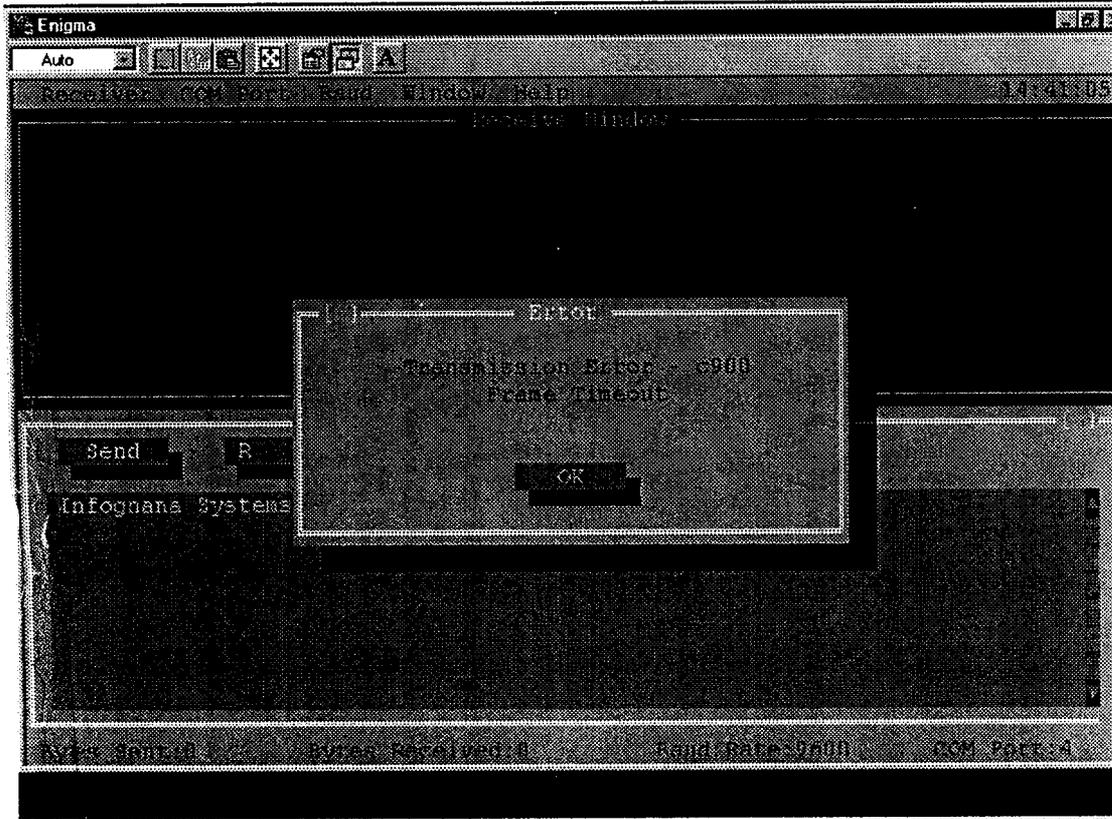
Bringing down Receiver on the Menu Bar and clicking on Clear will clear the contents of the Receive Window from previous sessions of Enigma though this is not necessary since it is done so when ever Enigma is executed.

(iv)



Select the COM Port to which Enigma is connected to as shown above.

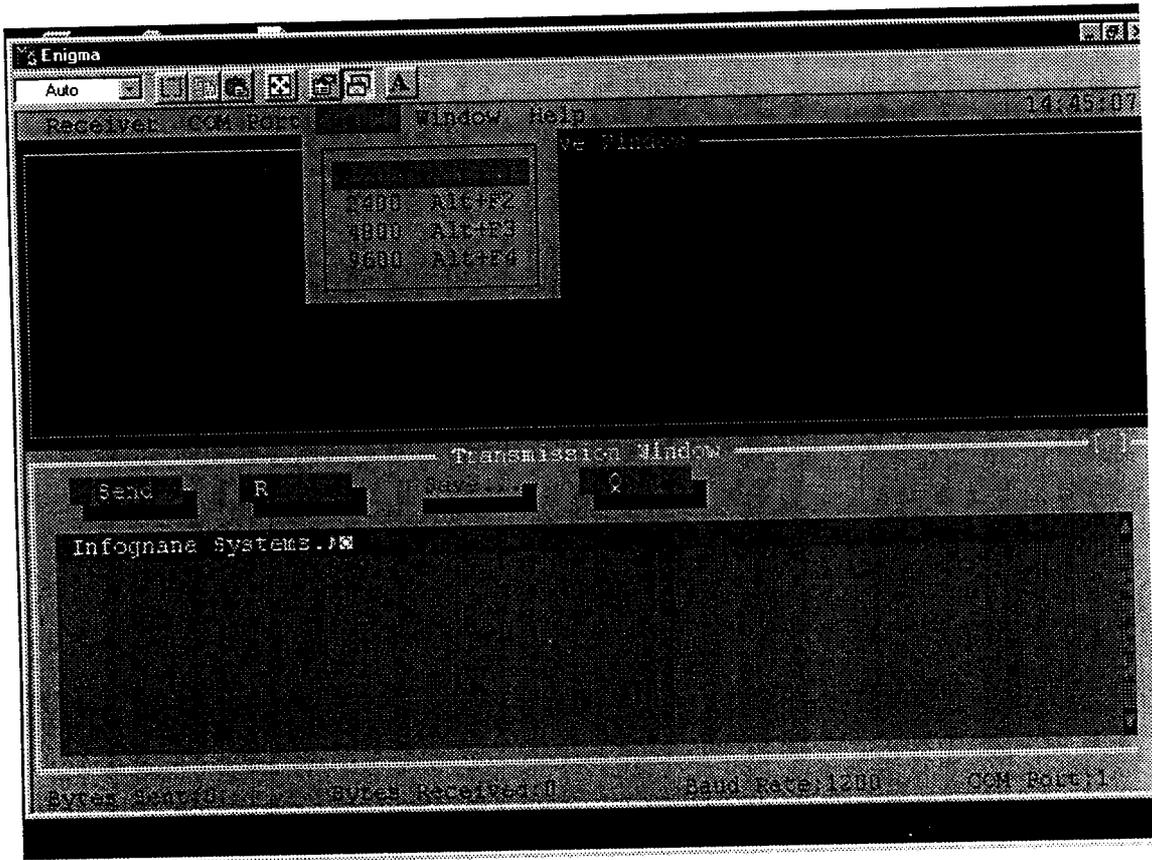
(v)



Assuming the Port Selected is not available, a Transmission Error will be displayed.

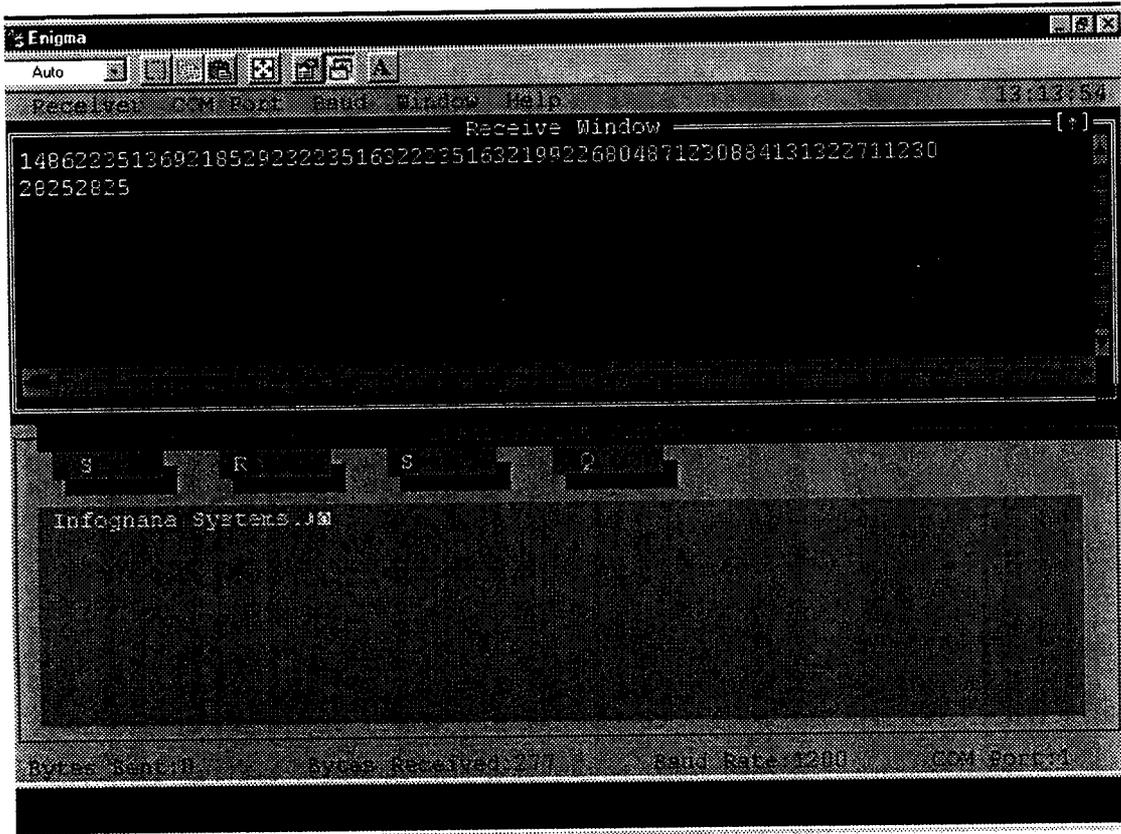
Select an available port to which Info Crypt is connected to.

(vi)



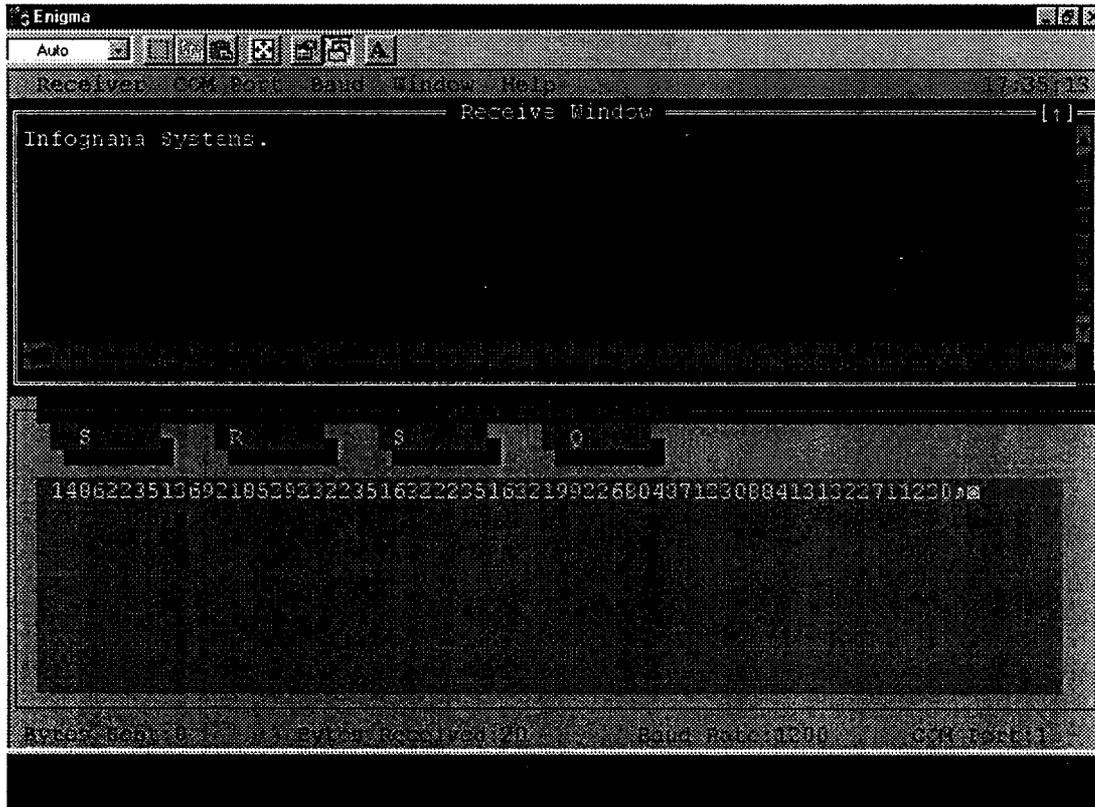
Select Baud Rate from Baud Menu

(vii)



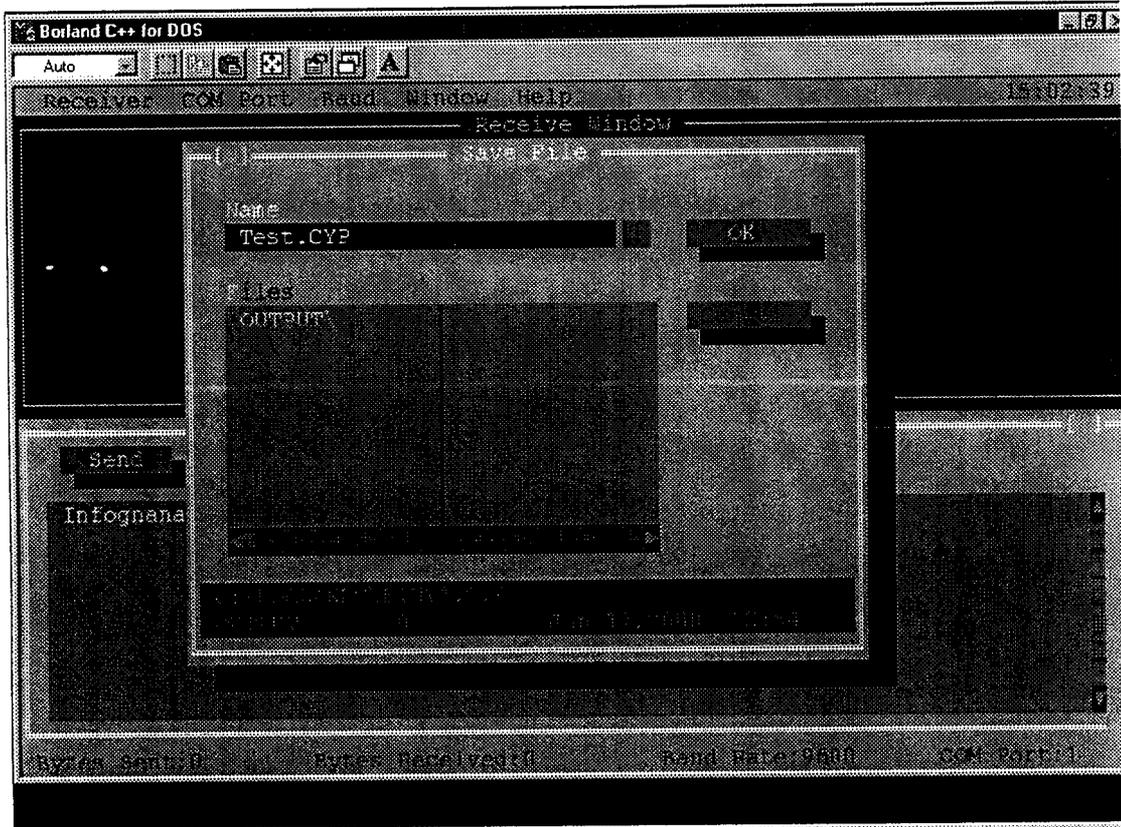
As seen above data in the Transmitt window has been encrypted by Info Crypt and its result viewed in the Receive Window. Save has also been highlighted. The contents can be saved into a file.

(viii)



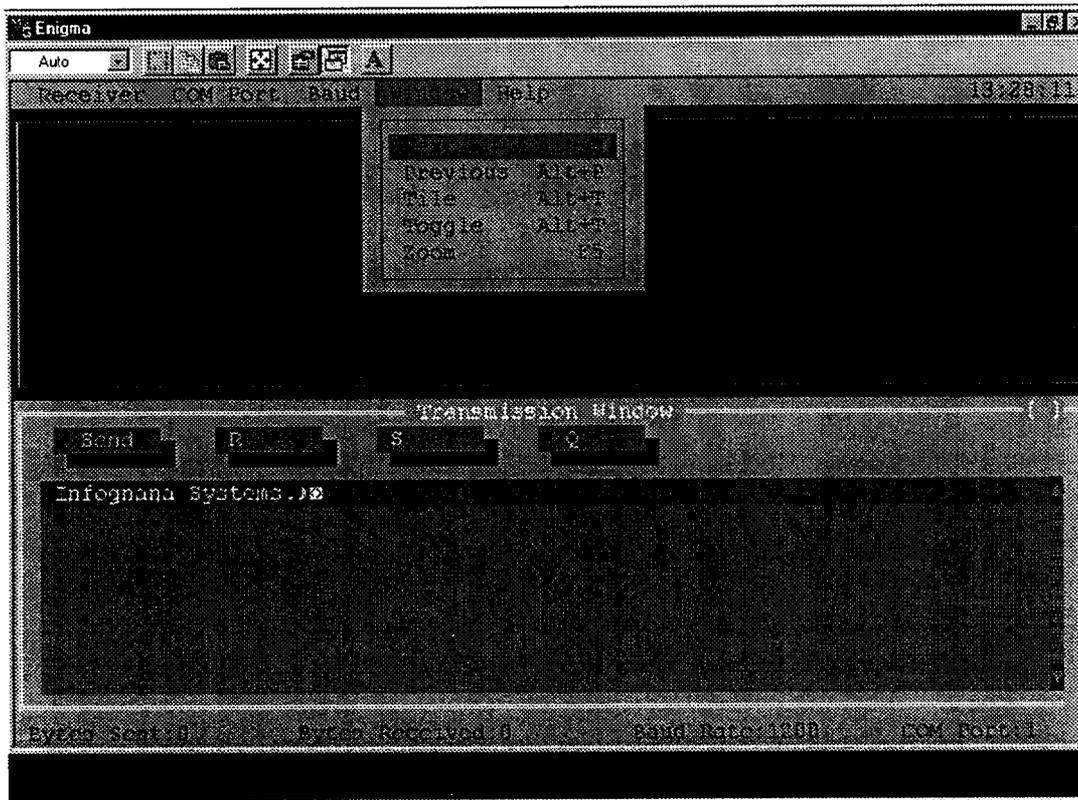
The same holds true for decryption as shown above.

(ix)



When contents are to be saved the Save Dialog Box appears with the default extension .CYP for encrypted data and .DYP for decrypted data. The receiver's window is automatically cleared of contents and the Status Bar values restored to default values.

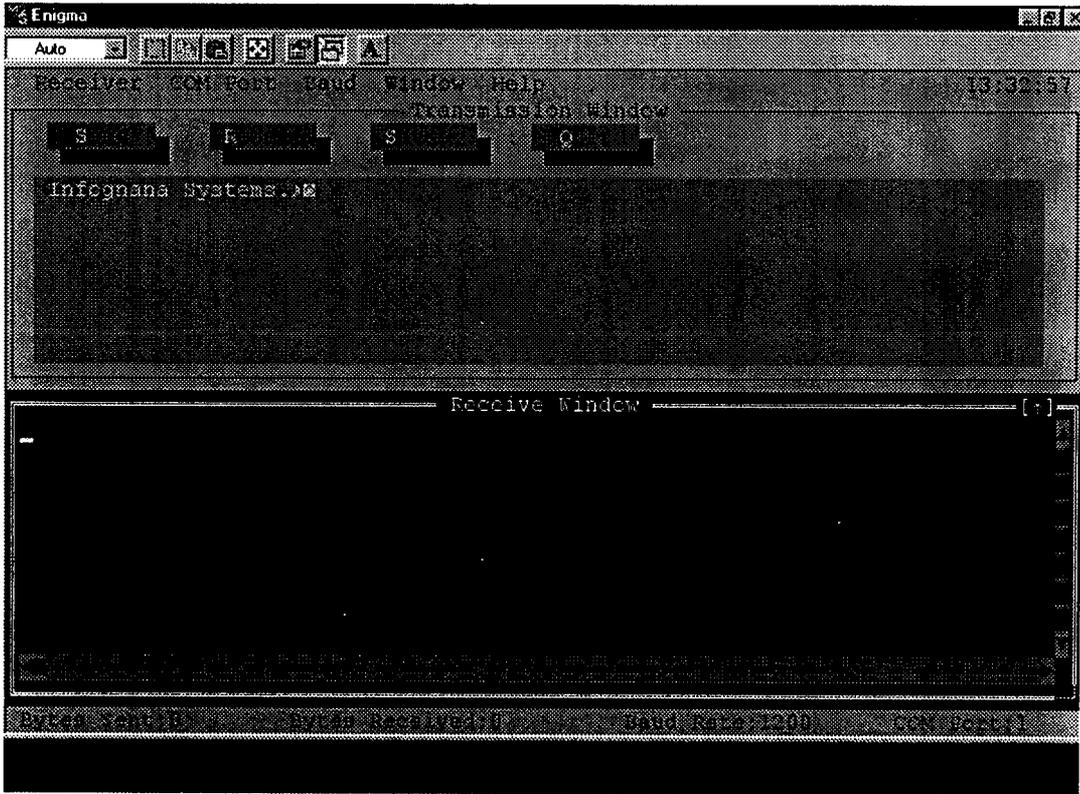
(x)



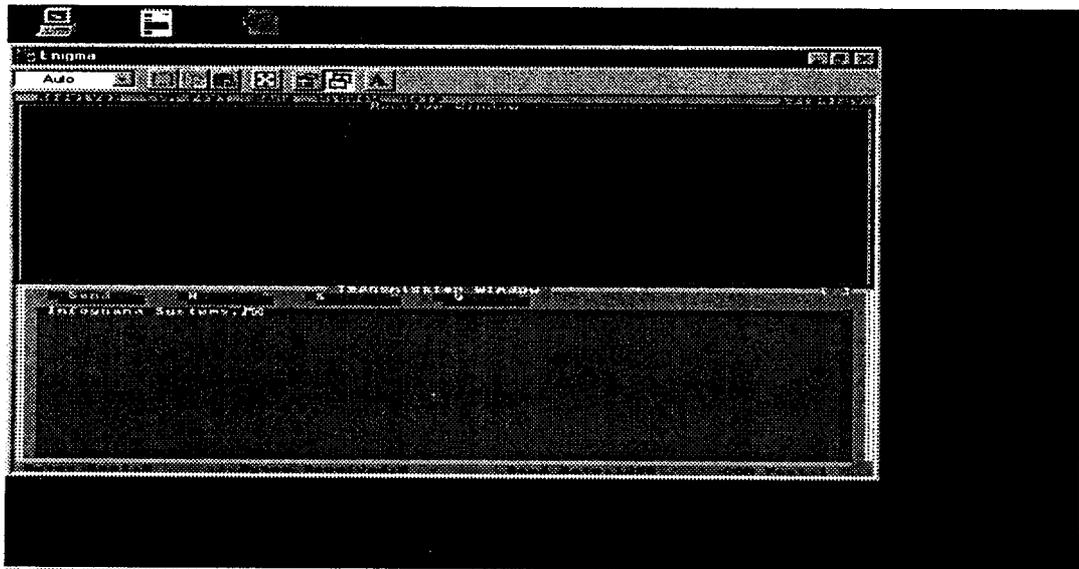
The Window Menu provides a set of window settings commands.

- **Next** and **Previous** will take you to the next or previous window depending upon where the cursor's current position is

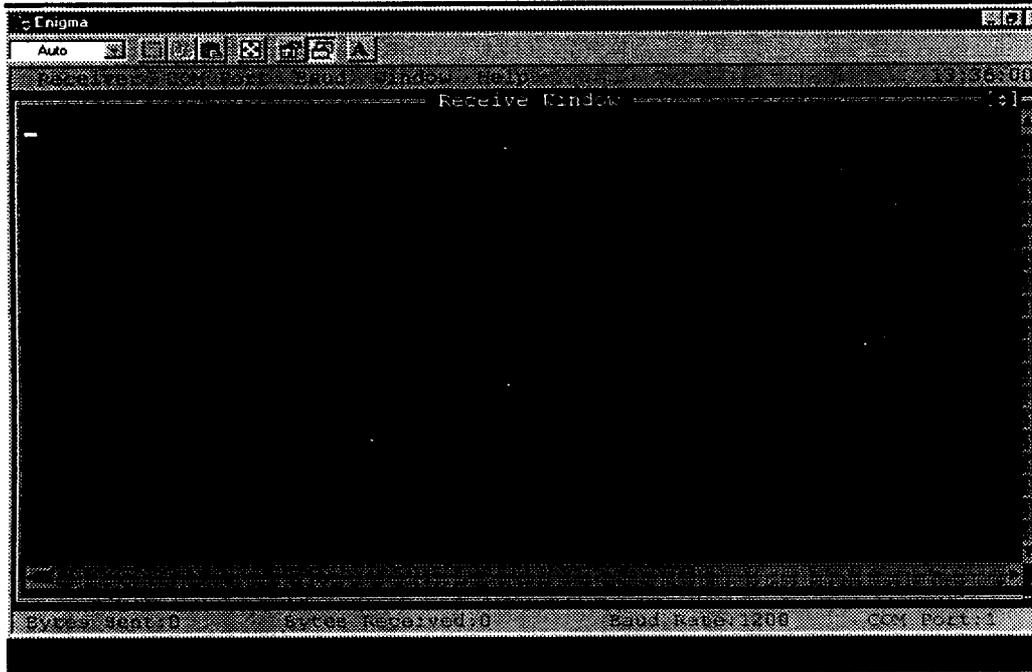
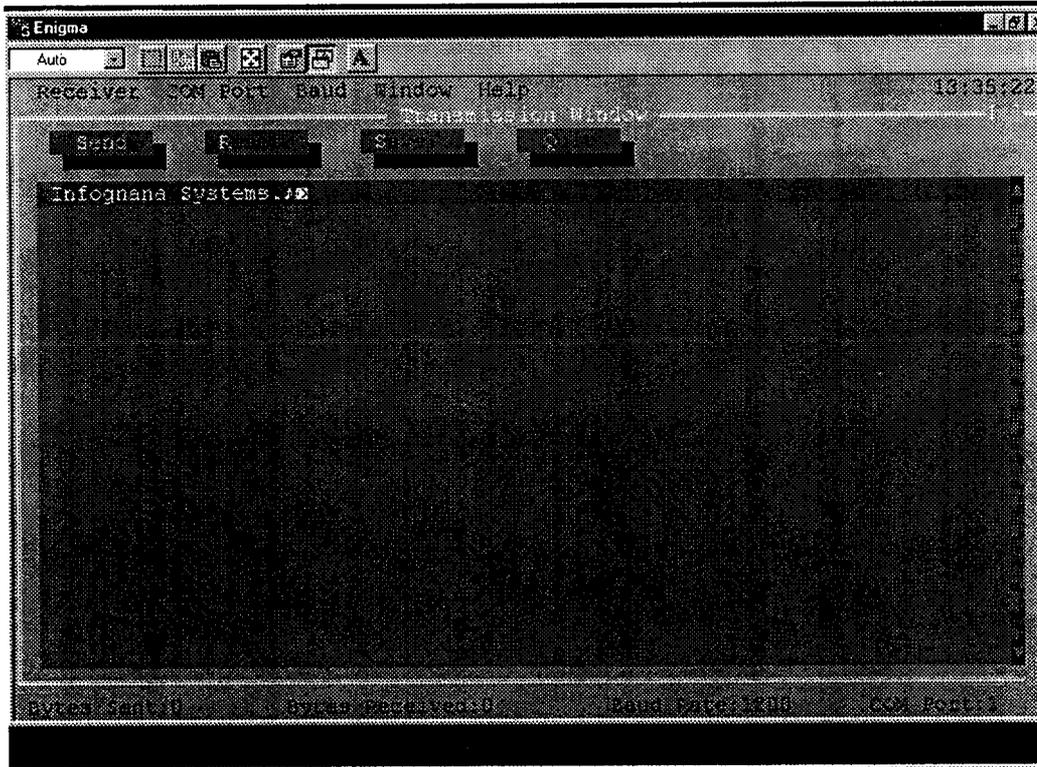
- **Tile** reverses the position of the windows as shown below



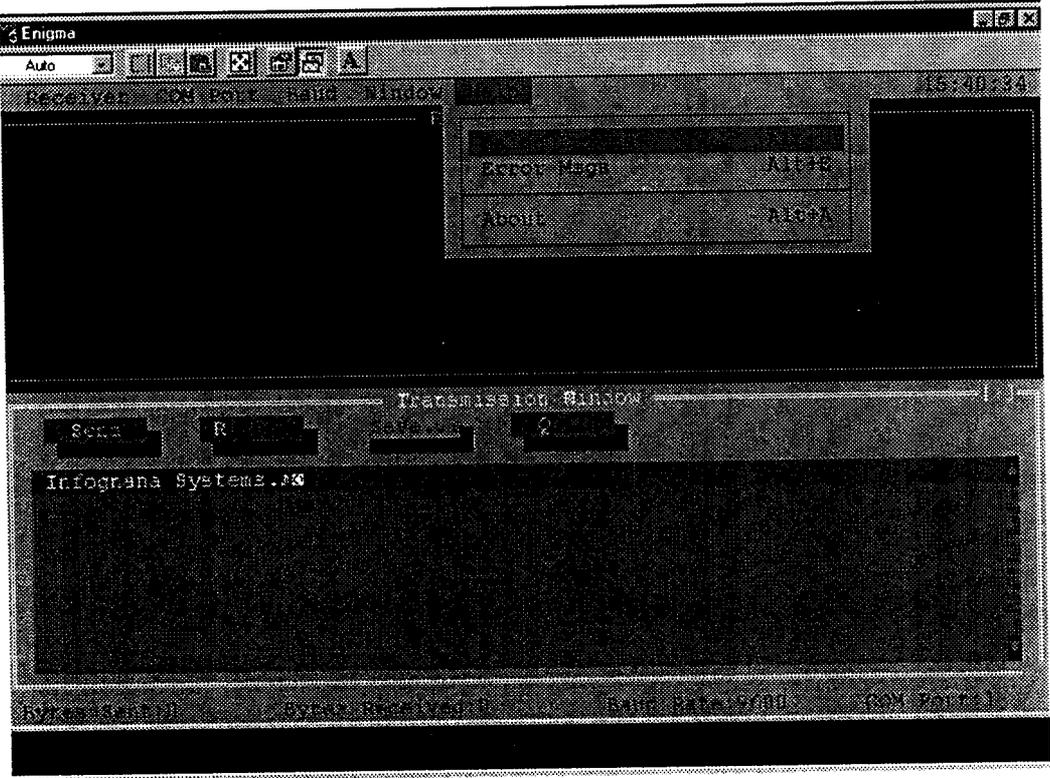
- **Toggle** will bring the appearance of the font to 8\*8 as shown below



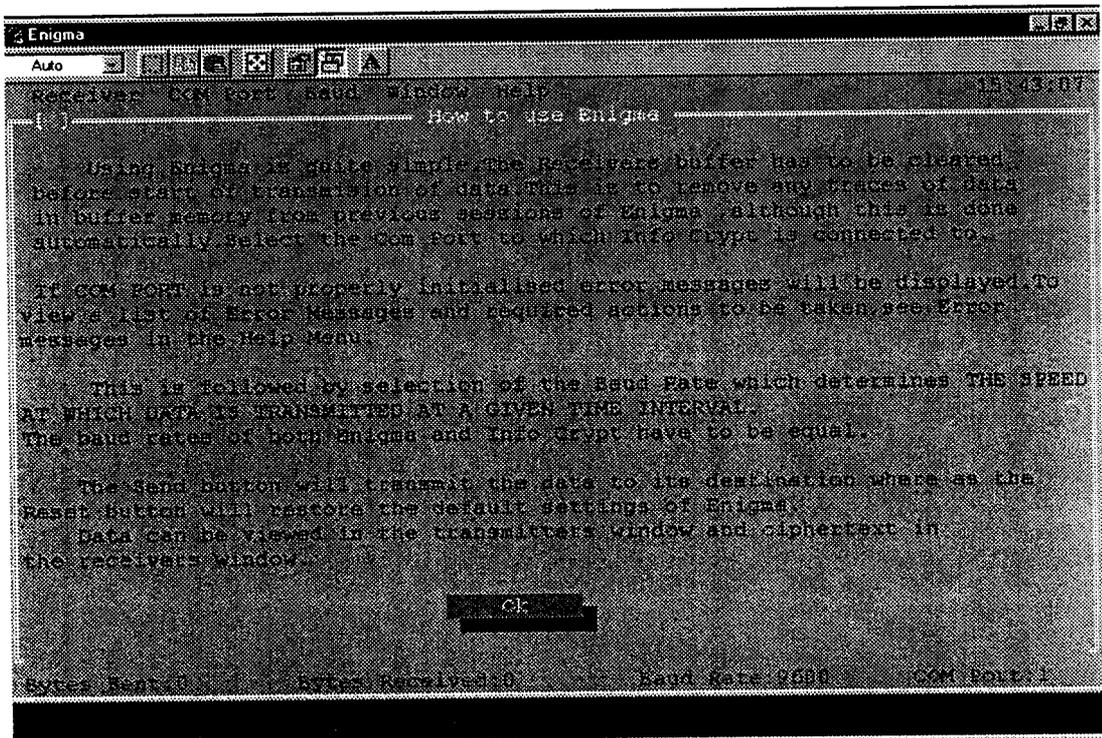
Zoom will zoom the window currently focused on to full screen as shown below



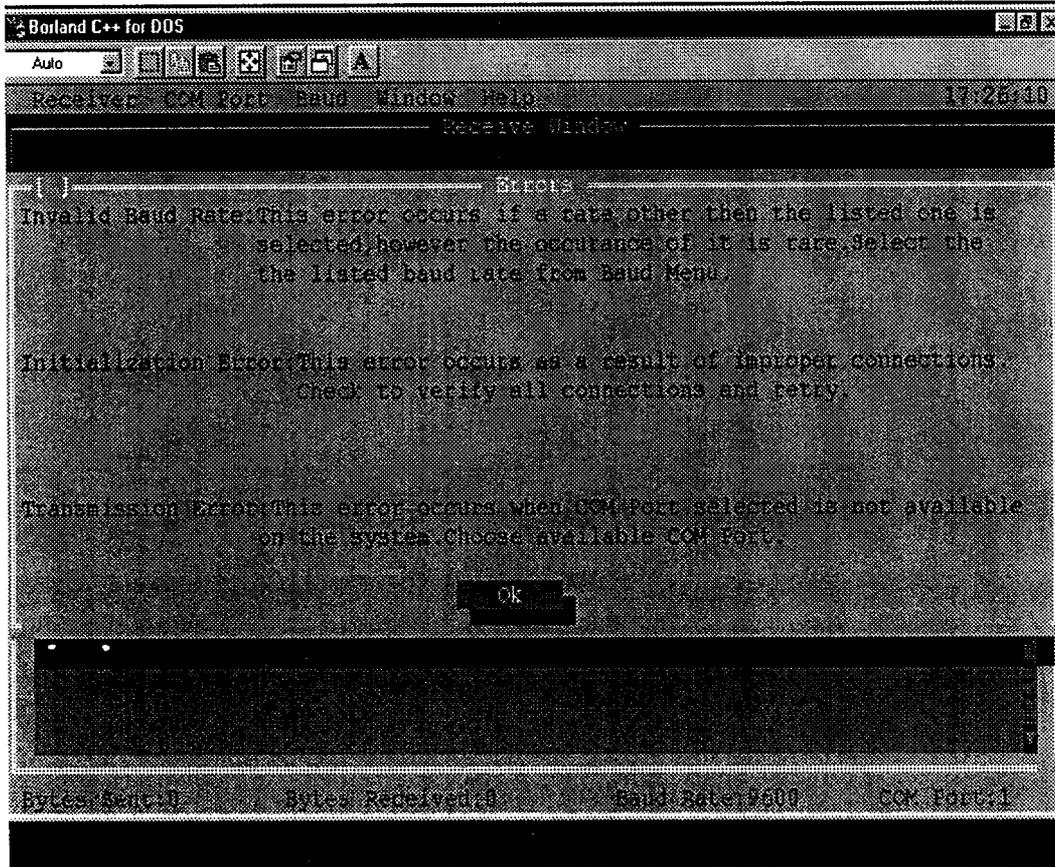
(xi) The Help Menu provides help related to two divisions



- Using Enigma:Relates how to use the product in a one page display as shown below

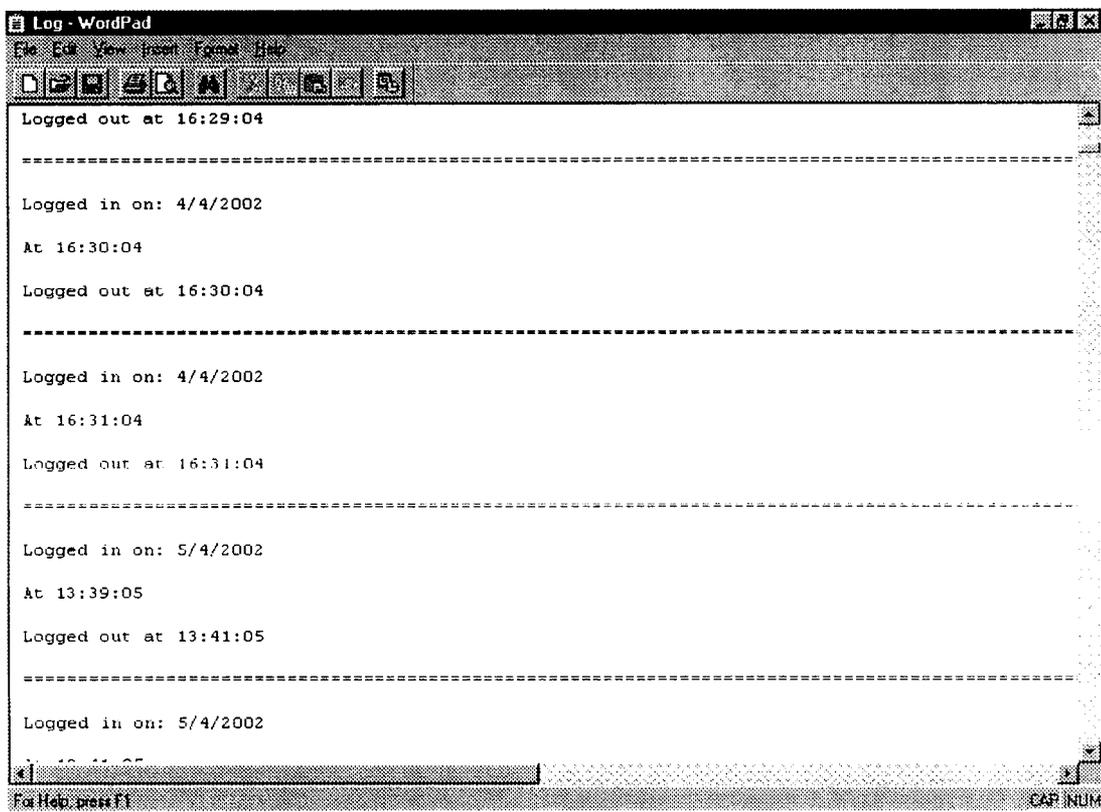


- **Error Messages:** relates to the possible errors likely in Serial Transmission and remedial solution to be followed.

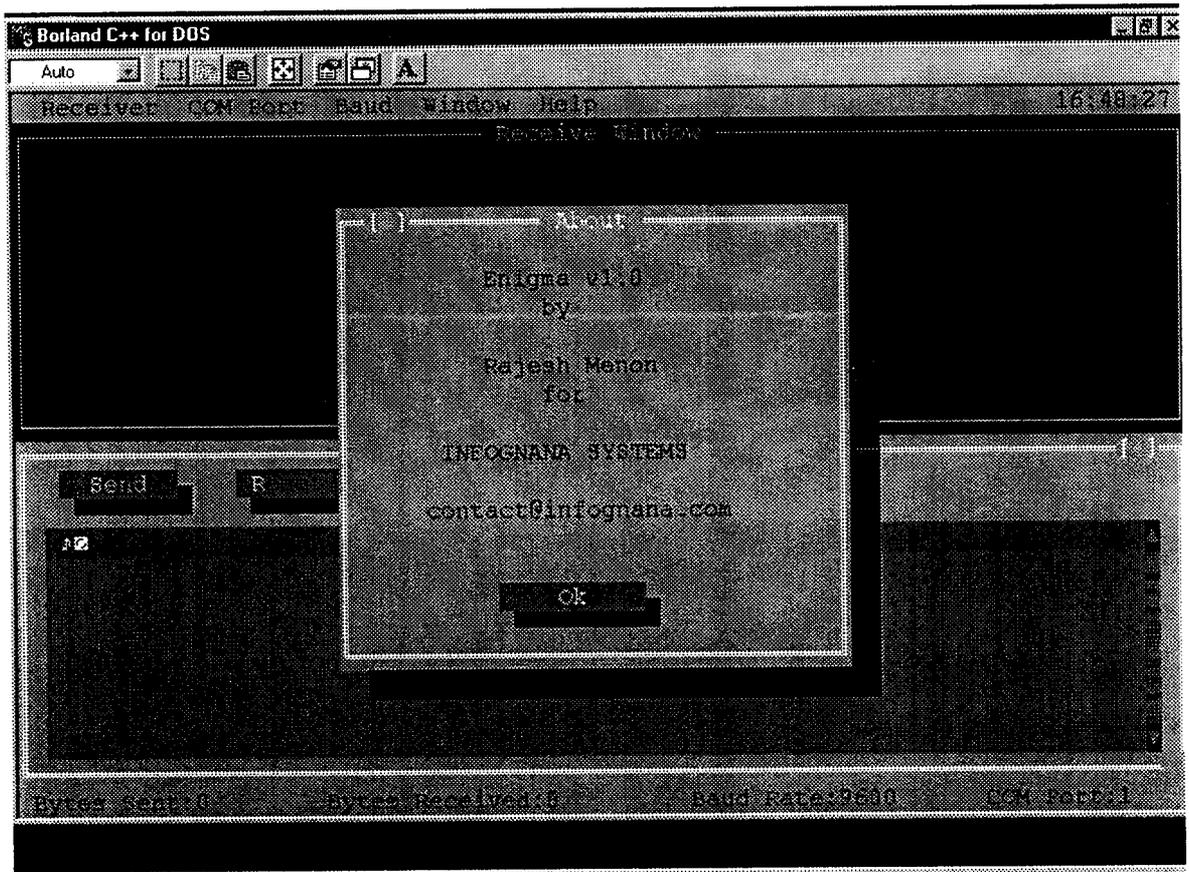


(xii) Enigma creates a log file in the background recording the following events

- Log in Date
- Log in time
- Logged out time.



(xiii)



*CHAPTER 8*

*SCOPE FOR FUTURE  
ENHANCEMENTS*

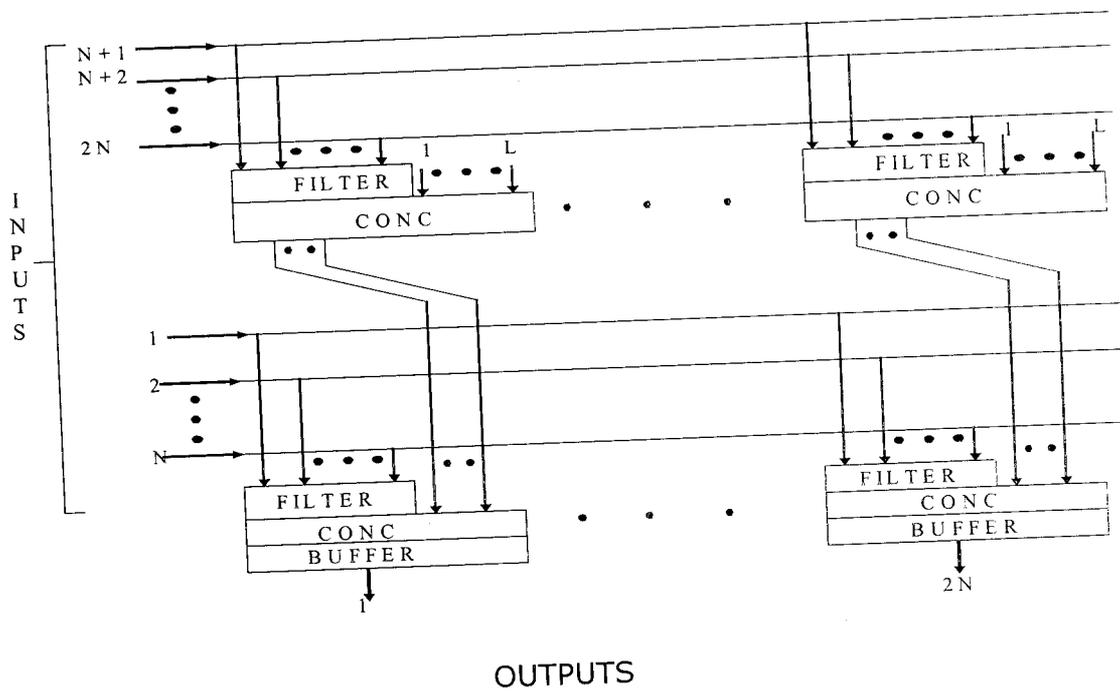
## SCOPE FOR FUTURE ENHANCEMENTS

- 1) The knockout switch provides direct interconnection paths from the switch inputs to the outputs, allowing great simplification of the buffer design and thus achieves a more efficient switch.
- 2) The packet loss in any network is inevitable whether it is caused by transmission errors or buffer overflow. By allowing the packet switch itself to introduce a small amount of additional packet loss, the concentrator required at each switch output can be reduced from  $N*N$  to  $N*8$  for arbitrarily large  $N$ . An  $N*8$  concentrator is designed based on knockout matches commonly used in tournaments.
- 3) A new buffer sharing scheme joins the buffer associated with each of the concentrator output lines to form a simple first-in first-out buffer.
- 4) The lost packet rate of the knockout switch can be made as small as desired and the latency is the smallest achievable by any switch.
- 5) The interconnect allows:
  - ✓ easy modular growth
  - ✓ simple maintenance procedures
  - ✓ design that can be made fault tolerant

## 8.1 MODULARITY

Often in the design of a switch, the cost and complexity of the switch fabric play a secondary role to other factors such as the ability to grow the switch in a modular fashion, to maintain the switch without great difficulty and to provide the required degree of fault tolerance.

In addition to growing gracefully from  $2 \times 2$  to  $N \times N$ , the knockout switch can grow modularly from  $N \times N$  to  $JN \times JN$ ,  $J=2,3,\dots$ . One way to do this illustrated in the fig where we have provided each concentrator in the switch with  $L$  additional inputs for a total of  $N+L$  inputs and  $L$  outputs. The interface for each output in a  $JN \times JN$  knockout switch consists of  $J$  separate  $N$ -bus interfaces daisy chained together. Specifically, each of the  $J$  interfaces for the one output contains a row of  $N$  packet filters and a  $(N+L)$ -to- $L$  concentrator, with only the first interface containing the shared buffer structure with shifter and  $L$  FIFO buffers. These  $J$  individual components for each output are connected together by attaching the  $L$  outputs of the concentrator in the  $j^{\text{th}}$  interface to the  $L$  extra inputs on the concentrator in the  $(j-1)^{\text{st}}$  interface. In effect, we have a convenient way of growing the knockout switch using a single  $(N+L)$ -to- $L$  concentrator design and the same shared buffer (one for each output) independent of the switch size.



## 8.2 APPLICATIONS OF KNOCKOUT SWITCH:

Each of  $N=1000$  inputs operating at 50Mbits/s, possible applications for a 50Gbits/s knockout packet switch include interconnects of multiprocessing systems, high speed local and metropolitan area networks, and local or toll switches for integrated traffic loads. With the advent of optical backplanes the integrated optoelectronic devices, the line speed and overall switch capacity could grow much larger.

*CHAPTER 9*

*CONCLUSION*

## CONCLUSION

The project "KNOCKOUT SWITCH - A Simple Modular Architecture for Packet Switching" has been successfully implemented by simulating the concentrator and buffer design for the switch by using the simulation package simjava.

A description of the various packages imported along with the interface index, class index, constructors and methods used in the simulation are stated in the appendix.

This project mainly demonstrates the routing of packets that arrive at the inputs of a knockout switch. By simulating the method in which the packets arrive at the output of the switch after traveling through the packet filters, concentrator and shared buffer we can conclude that the knockout switch is superior to conventional contention switches in design and functioning.

Through the project we are able to establish the following about the knockout switch architecture:

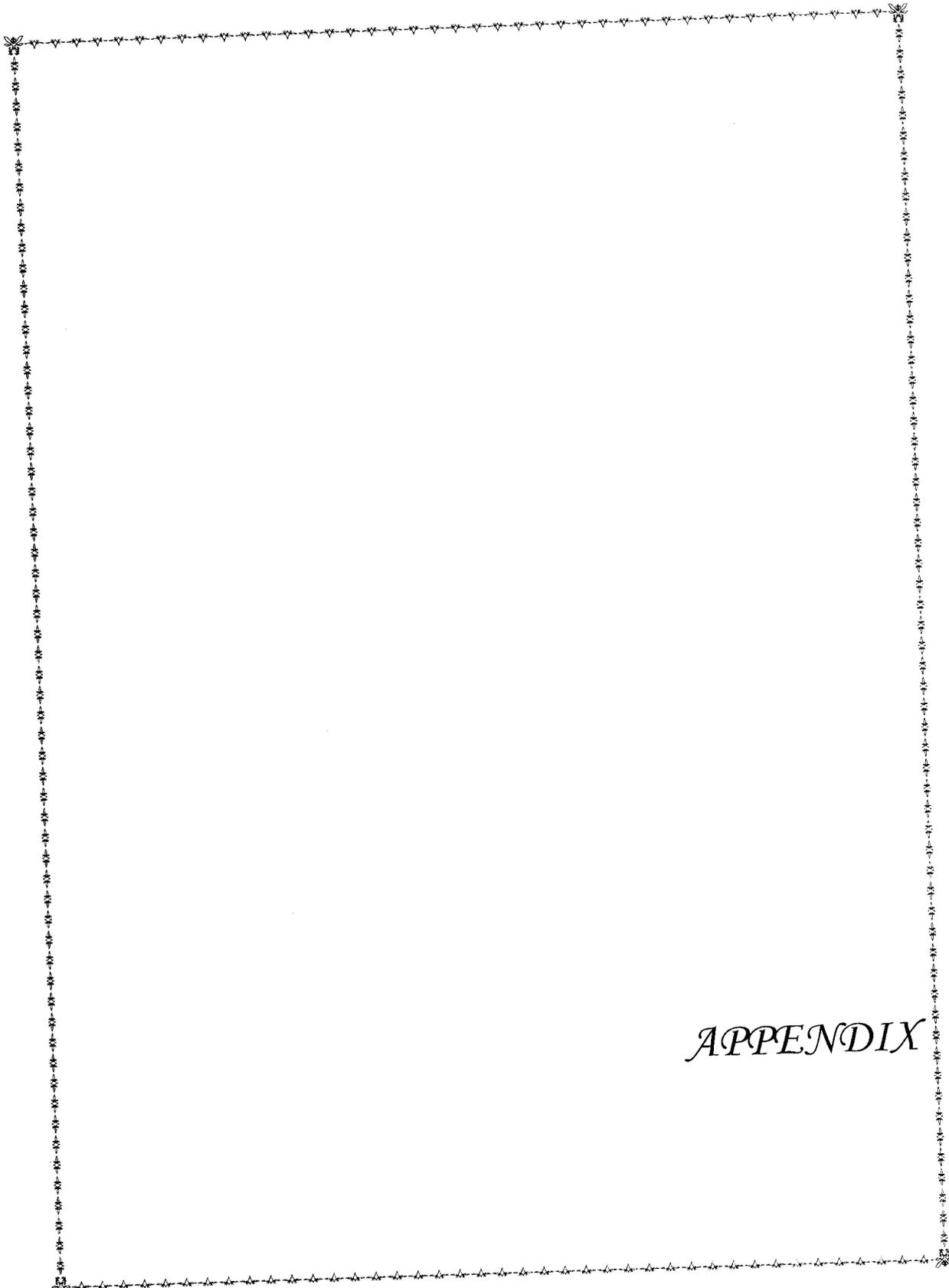
- ◆ It is designed such that it has low latency
- ◆ It is self routing and non blocking
- ◆ It has a simple interconnection topology that allows for easy modular growth
- ◆ Minimal disruption and easy repair of any fault.

CHAPTER 10

BIBLIOGRAPHY

## **BIBLIOGRAPHY**

- [1] W.L.Hoberecht , "A layered network protocol for voice and data integration ,"IEEE J. Select. Areas Commn ., vol. SAC-1, pp. 1006-1013, Dec . 1983.
- [2] "Design of an integrated services packet network," IEEE J. Select. Areas Commn ., vol. SAC-4, pp. 1373-1380, Nov. 1986.
- [3] M.Decina and D.Vlack, Eds., Special Issue on Packet Switched Voice and Data Communication, IEEE J. Select. Areas Commn ., vol. SAC-1, Dec. 1983.
- [4] J.S.Turner, "Design of a broadcast packet network," in Proc.IEEE INFOCOM '86, pp.667 to 675 , Apr.1986 .
- [5] <http://www.dcs.ed.ac.uk/home/hase/simjava>



*APPENDIX*

## APPENDIX

**package eduni.simjava**

### INTERFACE INDEX

- Sim\_output

### CLASS INDEX

- Sim\_entity
- Sim\_event
- Sim\_port
- Sim\_system

### Class eduni.simjava.Sim\_entity

java.lang.Object

|

+----java.lang.Thread

|

+----eduni.simjava.Sim\_entity

### CONSTRUCTORS

Sim\_entity(String)

The standard constructor.

•Sim\_entity(String, String, int, int)

The constructor for use with the eduni.simanim animation package.

## **METHODS**

•add\_param(Anim\_param)

Add a parameter to this entity.

•add\_port(Sim\_port)

Add a port to this entity.

•body()

The method, which defines the behavior of the entity.

•get\_id()

Get the unique id number assigned to this entity

•get\_name()

Get the name of this entity

•get\_port(Sim\_event)

Search through this entity's ports, for the one which sent this event.

•get\_port(String)

Search through this entity's ports, for one called name.

•sim\_hold(double)

Causes the entity to hold for delay units of simulation time.

•sim\_putback(Sim\_event)

Put an event back on the deferred queue.

•sim\_schedule(int, double, int)

Send an event to another entity, by id number and with no data.

•sim\_schedule(int, double, int, Object)

Send an event to another entity, by id number with data.

• sim\_schedule(Sim\_port, double, int)

Send an event to another entity, by a port reference with no data.

• sim\_schedule(Sim\_port, double, int, Object)

Send an event to another entity, by a port reference with data.

• sim\_schedule(String, double, int)

Send an event to another entity, by a port name with no data.

• sim\_schedule(String, double, int, Object)

Send an event to another entity, by a port name with data.

• sim\_wait(Sim\_event)

Hold until the entity receives an event.

• sim\_waiting()

Count how many events are waiting of this entity on the deferred queue .

### **Class eduni.simjava.Sim\_event**

java.lang.Object

|

+-----eduni.simjava.Sim\_event

```
public class Sim_event
```

```
extends Object
```

This class represents events which are passed between the entities in the simulation

## **CONSTRUCTORS**

• Sim\_event()

Constructor, create a blank event.

## **METHODS**

• event\_time()

Get the simulation time that this event was scheduled.

• from\_port(Sim\_port)

Determine if the event was sent from a given port.

• get\_data()

Get the data passed in this event.

• get\_dest()

Get the unique id number of the entity, which received this event.

• get\_src()

Get the unique id number of the entity, which scheduled this event.

• get\_tag()

Get the user-defined tag in this event.

• scheduled\_by()

Get the unique id number of the entity, which scheduled this event.

• set\_dest(int)

Set the destination entity of this event.

• set\_src(int)

Set the source entity of this event.

•type()

Get the user-defined tag in this event

### **Class eduni.simjava.Sim\_port**

java.lang.Object

|

+----eduni.simjava.Sim\_port

public class Sim\_port

extends Object

### **CONSTRUCTORS**

•Sim\_port(String)

Constructor, for stand-alone simulations.

•Sim\_port(String, String, int, int)

Constructor for use with the eduni.simanim package for animations.

### **METHODS**

•get\_dest()

Get the unique id number of the destination entity of this port.

•get\_dest\_ename()

Get the name of the destination entity of this port.

•get\_pname()

Get the name of this port.

•get\_src()

Get the unique id number of the source entity of this port.

### **Class eduni.simjava.Sim\_system**

java.lang.Object

|

+----eduni.simjava.Sim\_system

```
public class Sim_system
```

```
extends Object
```

This is the system class which manages the simulation. All of the members of this class are static, so there is no need to create an instance of this class.

### **VARIABLES**

#### •SIM ANY

A standard predicate that matches any event.

#### •SIM NONE

A standard predicate that does not match any events.

### **CONSTRUCTORS**

•Sim\_system()

### **METHODS**

•add(Sim\_entity)

Add a new entity to the simulation.

•clock()

Get the current simulation time.

•current\_ent()

Find the currently running entity.

•get\_entity(int)

Find an entity by its id number.

•get\_entity(String)

Find an entity by its name.

•get\_entity\_id(String)

Find out an entities unique id number from its name.

•get\_num\_entities()

Get the current number of entities in the simulation

•initialise()

Initialise the system, this function does the job of a constructor, and should be called at the start of any simulation program.

•initialise(Sim\_anim, Thread)

This version of initialise() is used by the standard animation package eduni.simanim

•initialise(Sim\_output, Thread)

This version of initialise() is for experienced users who want to use the trace output to draw a graph or an animation as part of the application.

•link\_ports(String, String, String, String)

Link the ports the ports on two entities, so that events scheduled from one port are sent to the other.

• run()

Start the simulation running.

• run\_start()

Start the simulation running.

• run\_stop()

Stop the simulation

• run\_tick()

Run one tick of the simulation.

• sim\_clock()

A different name for `Sim_system.clock()`.

## **package eduni.simanim**

### **CLASS INDEX**

- Anim\_applet
- Anim\_entity
- Anim\_param
- Anim\_port
- Param\_type
- Sim\_anim

## Class `eduni.simanim.Anim_applet`

`java.lang.Object`

|

+----`java.awt.Component`

|

+----`java.awt.Container`

|

+----`java.awt.Panel`

|

+----`java.applet.Applet`

|

+----`eduni.simanim.Anim_applet`

```
public abstract class Anim_applet
```

```
extends Applet
```

The superclass for all simulation animations. New animations should extend this and provide bodies for the methods `anim_layout()` and `anim_init()`.

```
↳ Anim_applet()
```

### **METHODS**

```
↳ actionPerformed(ActionEvent)
```

Updated action handler for 1.1 event model

• adjustmentValueChanged(AdjustmentEvent)

Scroll bar event handler

• anim\_completed()

This method can be overridden in the subclass, and used to display results.

• anim\_init()

This method can be overridden in the subclass, and used to setup any GUI objects to be used for input to the animation.

• anim\_layout()

This method must be provided in the subclass, it should setup all the simulation entities, and link their ports.

• anim\_relayout()

Reinitialises all the animation entities, by calling `anim_layout()`, then redraws them.

• init()

This method should not be overridden in the subclass, use `anim_init()` instead.

• run()

This method should not be overridden in the subclass

• start()

This method should not be overridden in the subclass

• stop()

This method should not be overridden in the subclass

## **Class eduni.simanim.Anim\_entity**

java.lang.Object

|

+----eduni.simanim.Anim\_entity

```
public class Anim_entity
```

```
extends Object
```

An animation entity, used to store display information about an entity for the animation.

### **CONSTRUCTORS**

• Anim\_entity(String, String)

This constructor should not be used directly, use the extended constructor in eduni.simjava.Sim\_entity instead.

### **METHODS**

• add\_param(Anim\_param)

This method should not be used directly.

• add\_port(Anim\_port)

This method should not be used directly.

• is\_invisible()

• set\_invisible(boolean)

• set\_position(int, int)

This method should not be used directly.

### **Class eduni.simanim.Anim\_param**

java.lang.Object

|

+----eduni.simanim.Anim\_param

```
public class Anim_param
```

```
extends Object
```

An animation parameter, parameters are used to display data relating to its parent entity during an animation.

#### **VARIABLES**

• enum\_type

• HIDDEN

Display type: Don't display.

• NAME

Display type: Show parameter's name only.

• NAME\_VALUE

Display type: Show both the parameter's name and its value.

• STATE

Display type: Show as the entity's bitmap.

## •VALUE

Display type: Show value only.

## **CONSTRUCTORS**

↪Anim\_param(String, int, Param\_type)

Constructor, with co-ordinates defaulting to (0, 0).

↪Anim\_param(String, int, Param\_type, int, int)

Constructor, with Param\_type object and (x, y) co-ordinate.

↪Anim\_param(String, int, String)

Constructor, with co-ordinates defaulting to (0, 0).

↪Anim\_param(String, int, String, int, int)

Constructor, with (x, y) co-ordinate.

## **METHODS**

•get\_intval()

Get integer value of parameter.

•get\_value()

Get string value of parameter.

•set\_value(int)

Set value of parameter to integer.

•set\_value(String)

Set value of parameter to string.

## **Class eduni.simanim.Anim\_port**

java.lang.Object

|

+----eduni.simanim.Anim\_port

```
public class Anim_port
```

```
extends Object
```

An animation port, used to store display information about the port for the animation

## **VARIABLES**

### •BOTTOM

Attatch the port to the bottom side of the parent entity

### •enum\_side

### •LEFT

Attatch the port to the left side of the parent entity

### •RIGHT

Attatch the port to the right side of the parent entity

### •TOP

Attatch the port to the top side of the parent entity

## **CONSTRUCTORS**

### •Anim\_port(String, String)

This constuctor should not be used directly, use the extended constructor in eduni.simjava.Sim\_port instead.

## **METHODS**

### •draw\_messages(Graphics)

### •set\_position(int, int)

This method should not be used directly.

### **Class eduni.simanim.Param\_type**

java.lang.Object

|

+----eduni.simanim.Param\_type

```
public class Param_type
```

```
extends Object
```

An animation parameter type. Stores an array of strings representing the different states of a parameter, e.g. "Idle", "Busy" etc.

You need to specify a parameter type in order to get a parameter to display on a timing diagram.

Example code to add a parameter type from a user's entity constructor is below.

```
String[] wstate = {"idle","busy"};
add_param(new Anim_param( "State",
    Anim_param.STATE,
    new Param_type("wstate", wstate)
    ));
```

+----eduni.simanim.Sim\_anim

```
public class Sim_anim
```

```
extends Panel
```

Do not use this class directly, instead use Anim\_applet.

## **CONSTRUCTORS**

```
•Sim_anim(Anim_applet)
```

Do not use this method directly

## **METHODS**

```
•add_entity(Anim_entity)
```

Do not use this method directly

```
•animate(Thread)
```

Do not use this method directly

Do not use this method directly

```
•draw_all_static()
```

Do not use this method directly

```
•initialise()
```

Do not use this method directly

```
•link_ports(String, String, String, String)
```

Do not use this method directly

```
•paint(Graphics)
```

Do not use this method directly

- println(String)

Do not use this method directly

- update(Graphics)

Do not use this method directly