



**B.TECH DEGREE EXAMINATIONS: APRIL / MAY 2023**

(Regulation 2018)

Fifth Semester

**ARTIFICIAL INTELLIGENCE AND DATA SCIENCE**

U18AII5203: Reinforcement Learning

**COURSE OUTCOMES**

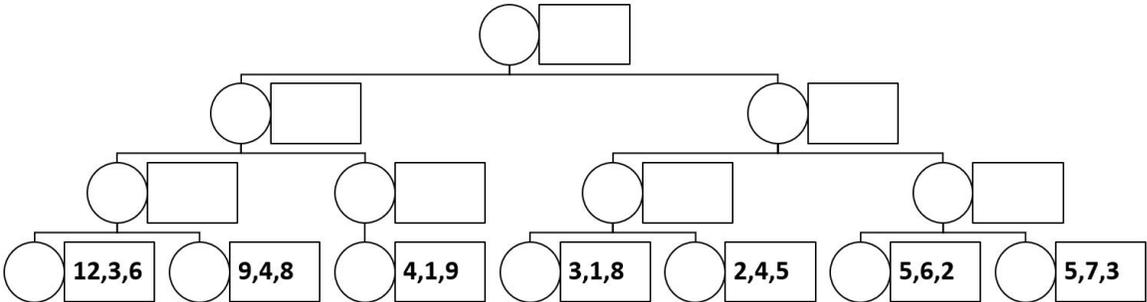
- CO1:** Understand the underpinnings to structure classical solutions for Reinforcement Learning problem.
- CO2:** Apply deep learning architectures to train agents navigating from virtual world from sensory data.
- CO3:** Analyze basic Reinforcement Learning algorithms for simple sequential decision making and control problems in uncertain conditions.
- CO4:** Build system of agents to demonstrate collaboration or cooperation.

**Time: Three Hours**

**Maximum Marks: 100**

**Answer all the Questions:-**  
**PART A (10 x 2 = 20 Marks)**  
**(Answer not more than 40 words)**

1. Explain the usage of reinforcement learning in the classic Gym’s Taxi environment. CO1 [K<sub>2</sub>]
2. List any four reinforcement learning frameworks CO1 [K<sub>1</sub>]
3. Explain the reason behind the overestimation of Q-values by regular Q-learning and DQN. CO2 [K<sub>2</sub>]
4. Outline the steps in building a neural network model. CO2 [K<sub>1</sub>]
5. Explain how the robots work on in a given environment. CO3 [K<sub>2</sub>]
6. Summarize leveraging neural networks to predict machine failures that learns intelligent behaviors from sensory data. CO2 [K<sub>2</sub>]
7. List the ways in which reinforcement learning problems are approached and solved with examples. CO3 [K<sub>1</sub>]
8. Apply min-max algorithm for the following 3-player game scenario. CO4 [K<sub>3</sub>]



- |     |   |  |     |                   |
|-----|---|--|-----|-------------------|
| 9.  | State the differences in training an agent in collaborative and competitive environment |  | CO4 | [K <sub>1</sub> ] |
| 10. | Outline Reinforcement Learning in continuous space                                      |  | CO4 | [K <sub>2</sub> ] |

**Answer any FIVE Questions:-  
PART B (5 x 16 = 80 Marks)  
(Answer not more than 400 words)**

- |     |    |   |   |     |                   |
|-----|----|---|---|-----|-------------------|
| 11. | a) | Explain in detail the Temporal Difference method and the way in which it differs from Monte- Carlo Method.  | 8 | CO2 | [K <sub>2</sub> ] |
|     | b) | Explain Reinforcement Learning, the elements, the components and goal of RL algorithm associated with it.   | 8 | CO1 | [K <sub>2</sub> ] |
| 12. | a) | Interpret how prioritized replay impacts Deep Q- Learning   | 8 | CO2 | [K <sub>2</sub> ] |
|     | b) | Compare and contrast Deep Q-Learning, Deep Q-Network, Double DQN and Dueling DQN with appropriate illustration.   | 8 | CO3 | [K <sub>4</sub> ] |
| 13. | a) | Explain the concept of Dynamic Programming used in reinforcement learning   | 8 | CO1 | [K <sub>2</sub> ] |
|     | b) | Online RL agents incrementally update their parameters while they observe a stream of experiences. In their simplest form, they discard incoming data immediately, after a single update. Analyze and provide solution for the issues associated with the above scenario. | 8 | CO3 | [K <sub>4</sub> ] |
| 14. | a) | Explain the steps and layers involved in building a convolutional neural network and analyze AlexNet and LeNet architectures  | 8 | CO2 | [K <sub>4</sub> ] |
|     | b) | i) State the key idea behind REINFORCE algorithms.  | 8 | CO3 | [K <sub>4</sub> ] |
|     |    | ii) Examine mathematically the need for Trajectory and how gradient ascent is going to affect the expected returns in REINFORCE algorithm.  |   |     |                   |
| 15. | a) | Compare and Contrast the following Reinforcement Learning Terminologies.  | 8 | CO3 | [K <sub>2</sub> ] |
|     |    | i) Value-based & Policy-based   |   |     |                   |
|     |    | ii) On-Policy & Off-Policy  |   |     |                   |
|     |    | iii) Model based & Model Free   |   |     |                   |
|     | b) | Explain Actor- Critic method and analyze why Optimization is much needed using Deep Deterministic Policy Gradient (DDPG).   | 8 | CO4 | [K <sub>4</sub> ] |

16. a) i) Make use of Hierarchical Reinforcement Learning to train smarter agents. 8 CO4 [K<sub>2</sub>]  
ii) Show certain use cases in the field of robotics where various Deep Reinforcement Learning techniques could be applied.
- b) Analyze the Multiplayer environment for Markov games and explain how to train an agent in collaborative and competitive environment. 8 CO4 [K<sub>4</sub>]

\*\*\*\*\*